

King Faisal University, Saudi Arabia
Department of Mechanical Engineering, College of Engineering
ME-441 CONTROL SYSTEMS

Year 1446 (2025) – 2nd Semester – SPRING 2025

Submission Deadline: May 8, 2025

Quiz – 4

Total Marks: 10

Name: _____

KFU ID: _____

Section: _____

Q.No.1: The transfer function of a complex control system is given below.

$$T(s) = \frac{30s^3 + 3s^2 + s}{s^6 + 8s^5 + 30s^4 + 72s^3 + 129s^2 + 160s + 100}$$

- a) Observe the system's stability according to coefficient tests and mention your findings.
- b) Design the Routh array for stability of this system with Routh Hurwitz stability criterion.
- c) Mention the number of characteristic roots on all significant locations of s -plane.
- d) Specify this system as stable, unstable, or marginally stable and mention the reason for your claim.

a) All of the same algebraic sign / none zero \Rightarrow NO information about root location.

$$b) s^6 + 8s^5 + 30s^4 + 72s^3 + 129s^2 + 160s + 100$$

$$s^6 \quad 1 \quad 30 \quad 129 \quad 100$$

$$s^5 \quad 8 \quad 72 \quad 160 \quad 0$$

$$s^4 \quad 21 \quad 109 \quad 100 \quad 0$$

$$s^3 \quad \frac{640}{21} \quad \frac{2560}{21} \quad 0 \quad 0$$

$$s^2 \quad 25 \quad 100 \quad 0 \quad 0$$

$$s^1 \quad \cancel{0} \quad 50 \quad 0 \quad 0$$

$$s^0 \quad 100$$



$$\frac{8 \times 32 - 72 \times 1}{8}$$

$$\frac{8 \times 120 - 160 \times 1}{8}$$

$$\frac{71 \times 72 - 109 \times 8}{21}$$

$$\frac{21 \times 160 - 100 \times 8}{21}$$

$$\frac{640}{21} \times 100 - \frac{2560 \times 21}{21}$$

$$\frac{640}{21}$$

$$25 \times \frac{2560}{21} - 100 \times \frac{640}{21}$$

$$25$$

$$p(s) = 25s^2 + 100$$

Imag Axis

$$\frac{dp(s)}{ds} = 50s$$

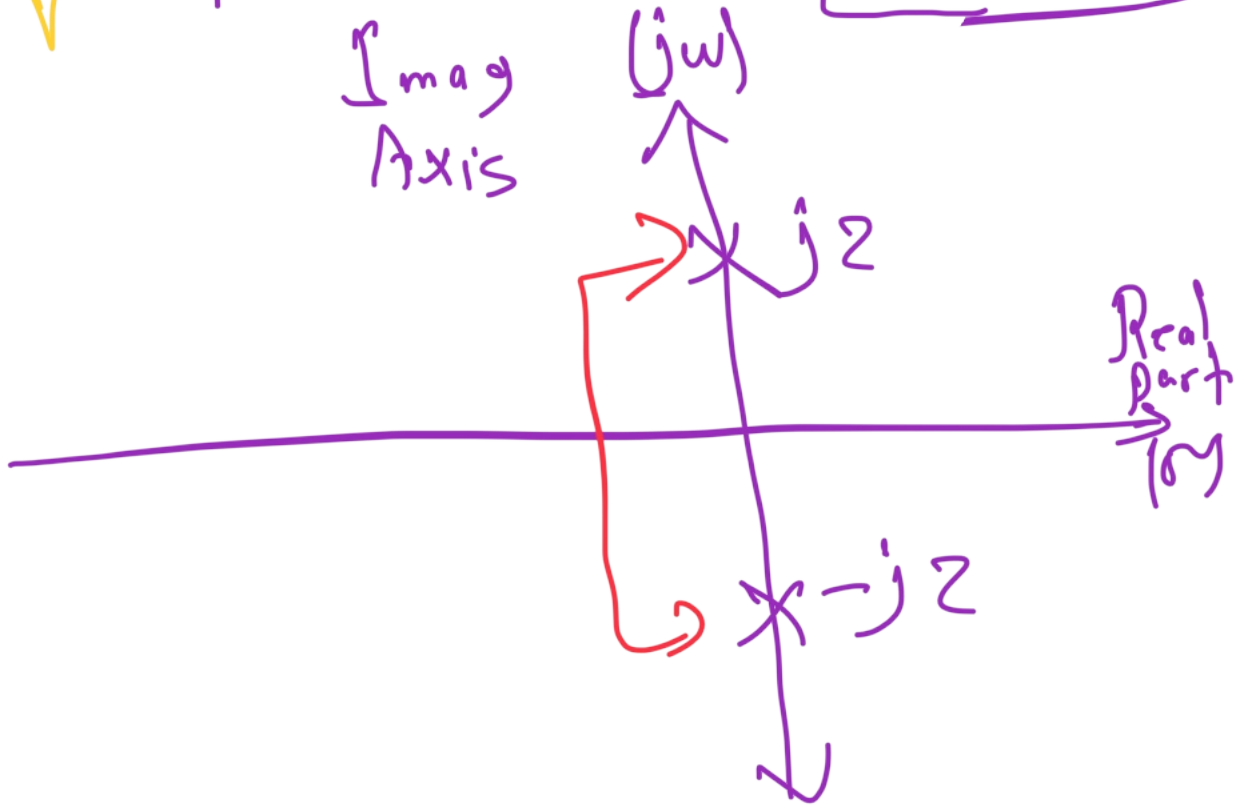
$$c) p(s) = 25s^2 + 100 = 0$$

$$25s^2 = -100$$

$$\sqrt{s^2} = \sqrt{-4} \implies$$

Imag Axis

$$s = \pm j2$$



d) No change in sign 1st column
but we have a row zeros
 \implies marginally stable

There 6 poles

↳ 2 poles on Imag Axis
↳ 4 poles on 2HP

So the system

is marginally stable

Problem #4: (8pts)

Transfer function of a complex control system is given below.

$$T(s) = \frac{30s^3 + 3s^2 + s}{s^5 + 2s^4 + 3s^3 + 6s^2 + 2s + 4}$$

- Observe system's stability according to coefficient tests and mention your findings.
- Design the Routh array for stability of this system with Routh Hurwitz stability criterion.
- Mention the number of characteristic roots on all significant locations of s -plane.
- Specify this system as stable, unstable, or marginally stable and mention the reason for your claim.

a) All found / No change in sign
⇒ No information about

Root location:

b) $s^5 + 2s^4 + 3s^3 + 6s^2 + 2s + 4$

s^5	1	3	2
s^4	2	6	4
s^3	0 8	0 12	0
s^2	3	4	0
s^1	4/3	0	0
s^0	4		

$$\Rightarrow \mathcal{O}(s) = 2s^4 + 6s^2 + 4$$

$$\mathcal{O}'(s) = \underline{\underline{8s^3}} + \underline{\underline{12s}}$$

$$c) \mathcal{P}(s) = 2s^4 + 6s^2 + 4 = 0$$

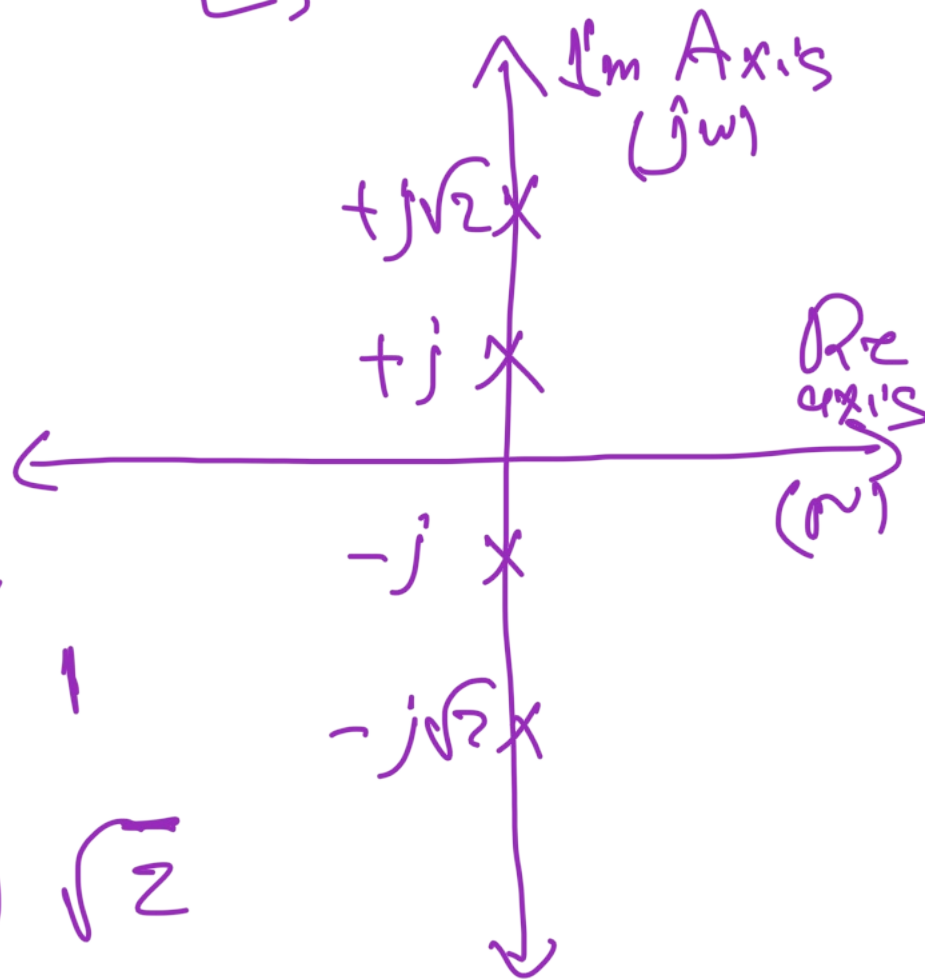
$$\underline{\underline{s^2}} = x \Rightarrow 2x^2 + 6x + 4 = 0$$

↳ mode $\rightarrow s \rightarrow ?$

$$x = \sqrt{s^2} = \sqrt{-1}$$

$$x = \sqrt{s^2} = \sqrt{-2}$$

$$\Rightarrow \begin{cases} s = +j \\ s = +j\sqrt{2} \end{cases}$$



d) No change in sign of 1st column

but, we have a row zeros

⇒ marginally stable

There are 5 poles

↳ 4 poles on Imag Axis

↳ 1 poles on LHP