

# ME 441 - CONTROL SYSTEMS

## Lecture 1

- Design Of Feedback Control Systems, 4<sup>th</sup> Edition  
R. T. Stefani, C. J. Savant, B. Shahian, G. H. Hostetter

Course Instructor:

Dr. Saad Arif - Assistant Professor - [sarif@kfu.edu.sa](mailto:sarif@kfu.edu.sa)

Office # 1056, Department of Mechanical Engineering, College of Engineering,  
King Faisal University, Al-Ahsa, Saudi Arabia

## Lecture Video Links

*Lecture-wise:* [https://youtube.com/playlist?list=PLRsy8EQwnUTPJ\\_lsvljQzYlGvvAHbZTpU](https://youtube.com/playlist?list=PLRsy8EQwnUTPJ_lsvljQzYlGvvAHbZTpU)

*Topic-wise:* <https://www.youtube.com/playlist?list=PLRsy8EQwnUTNP5gOU3NtrtyrALE1obZZH>

For Further Information, Visit the Channel: [www.bit.ly/saadarif](http://www.bit.ly/saadarif)

# Objectives

- ▶ Define a control system
- ▶ Explain why control systems are important
- ▶ Introduce basic components of a control system
- ▶ Give some examples of control system applications
- ▶ Explain why feedback is incorporated into most control systems
- ▶ Introduce types of control systems

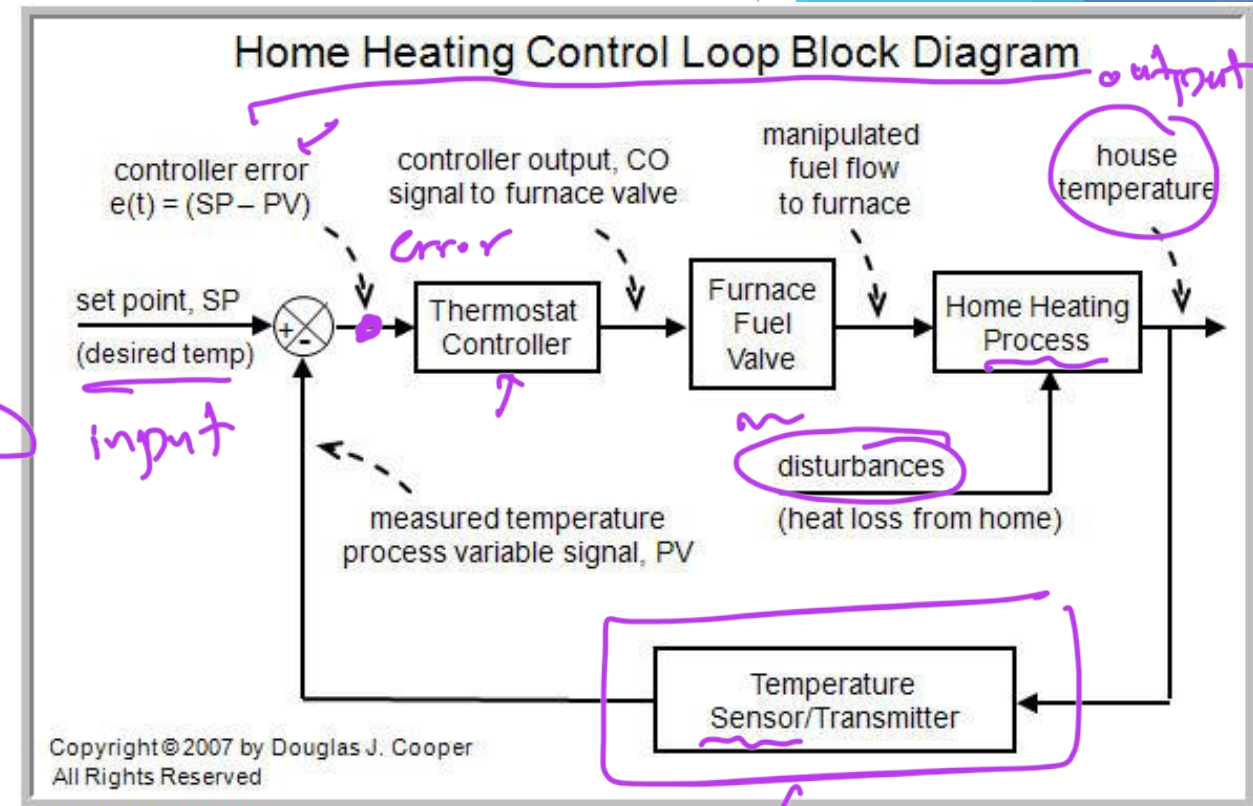
# Basic Concepts

Control system design process consists of

- ▶ Creating a mathematical model of the system (Block Diagram)
- ▶ Identifying the contents of blocks within the diagram
- ▶ Selecting values of adjustable parameters
- ▶ Adding components to provide acceptable performance

Feedback systems actively used in

- ▶ Automated manufacturing plants
- ▶ Automobiles
- ▶ House hold appliances
- ▶ Entertainment systems



# Prerequisite Knowledge

## ► Complex Analysis

$$j \quad i = \sqrt{-1}$$

- Complex numbers & their properties, laws, functions and plotting on complex plane

## ► Ordinary Differential Equations

- 1<sup>st</sup> & 2<sup>nd</sup> order ordinary integro-differential equations

## ► Laplace Transforms

- Solution of linear ODEs using Laplace transforms and Laplace theorems, Inverse Laplace transforms

## ► Linear Algebra

- Solutions of simultaneous algebraic equations

## ► Polynomial

$$x^2 + 5x + 6$$

- Higher order polynomials & their arithmetic, Partial fractions

## ► Geometry

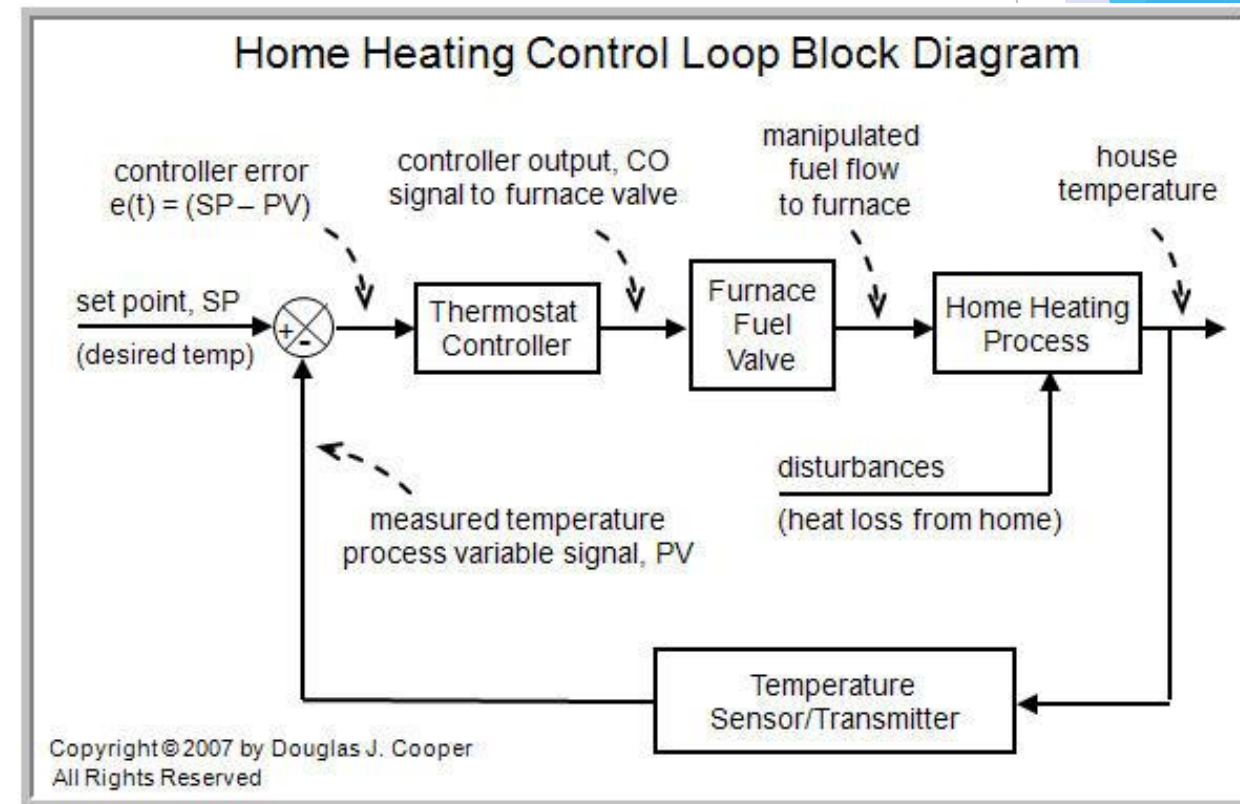
- Solution of problems through geometric identities & laws over plots



# Terminology

## ► System

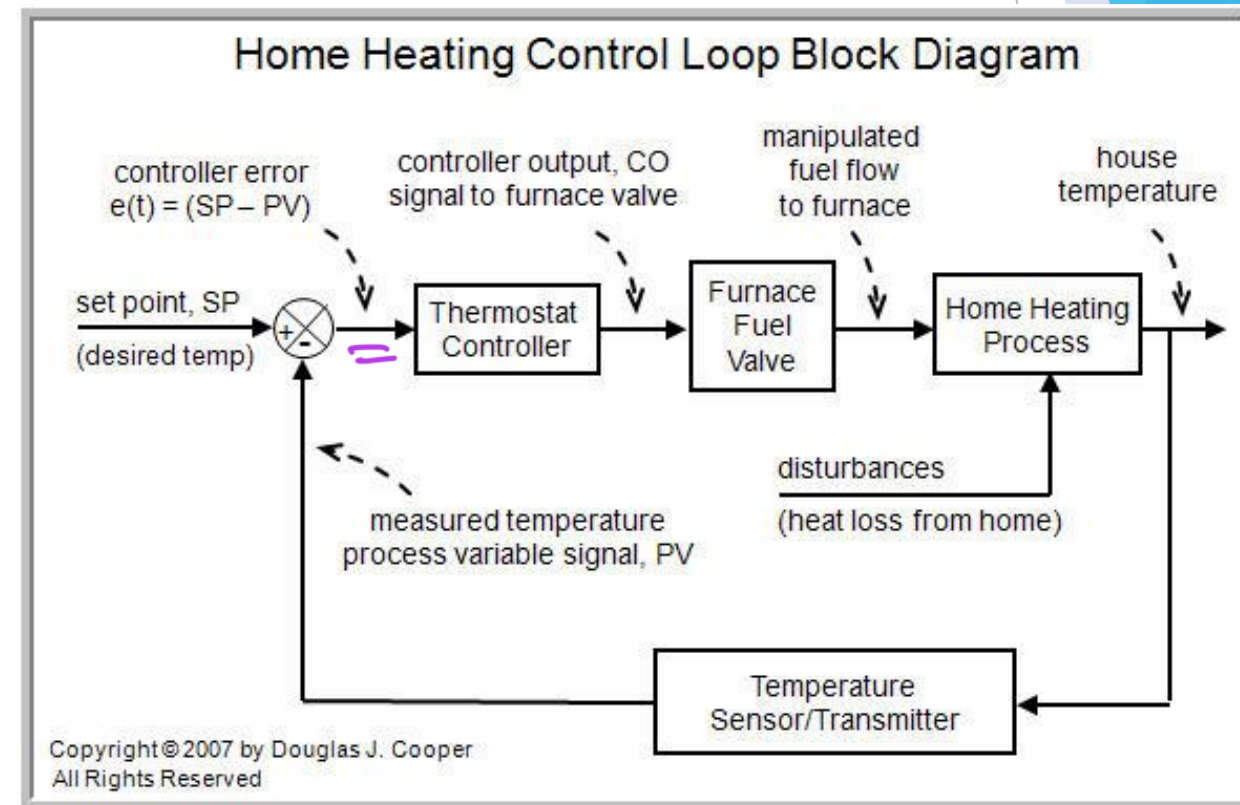
An arrangement or combination of different physical components that are connected or related together to form an entire unit to achieve a certain objective. E.g., Classroom, Car etc.



# Terminology

## ► Control

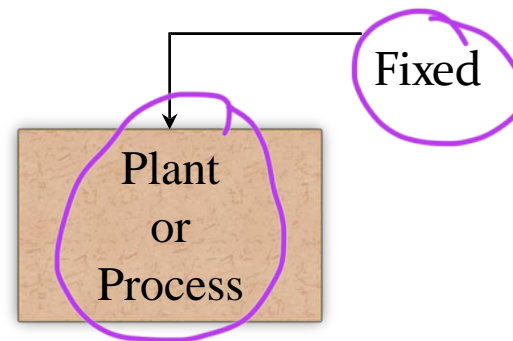
To regulate direct and command a system so that a desired objective is achieved



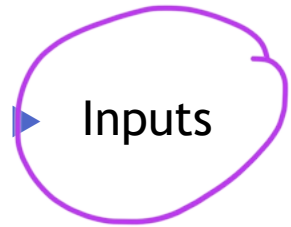
# Terminology

## ► Plant/Process

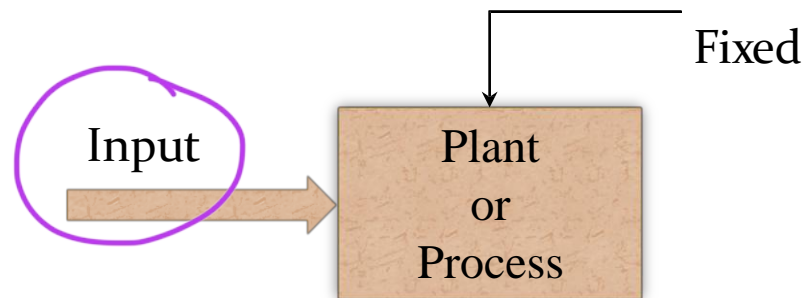
Portion of the system to be controlled. It is fixed as far as the control system designer is concerned. The designer's job is to ensure that the plant operates as required



# Terminology



The applied or excitation signal applied to a control system to get a specific output

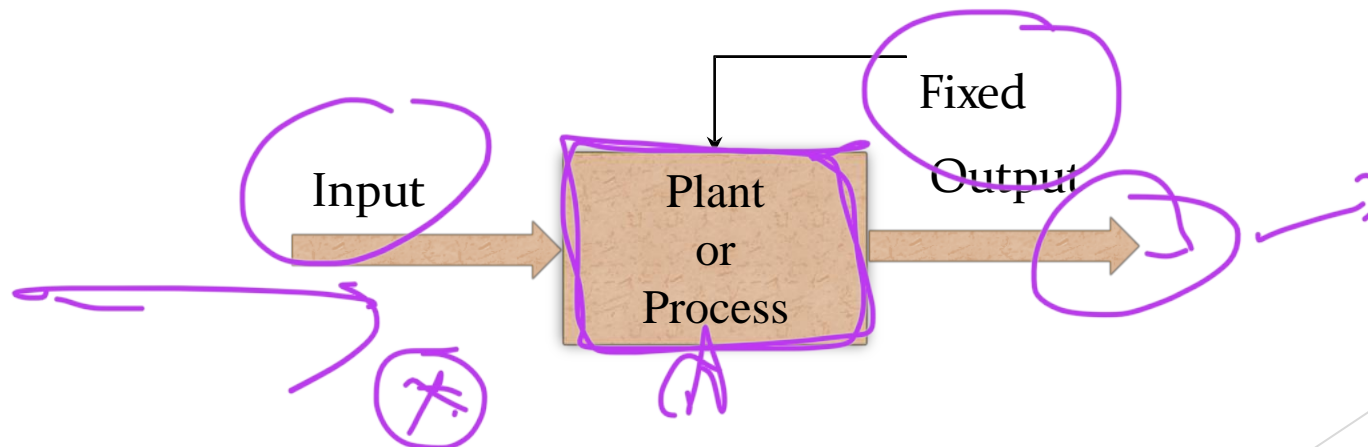




# Terminology

## ► Outputs

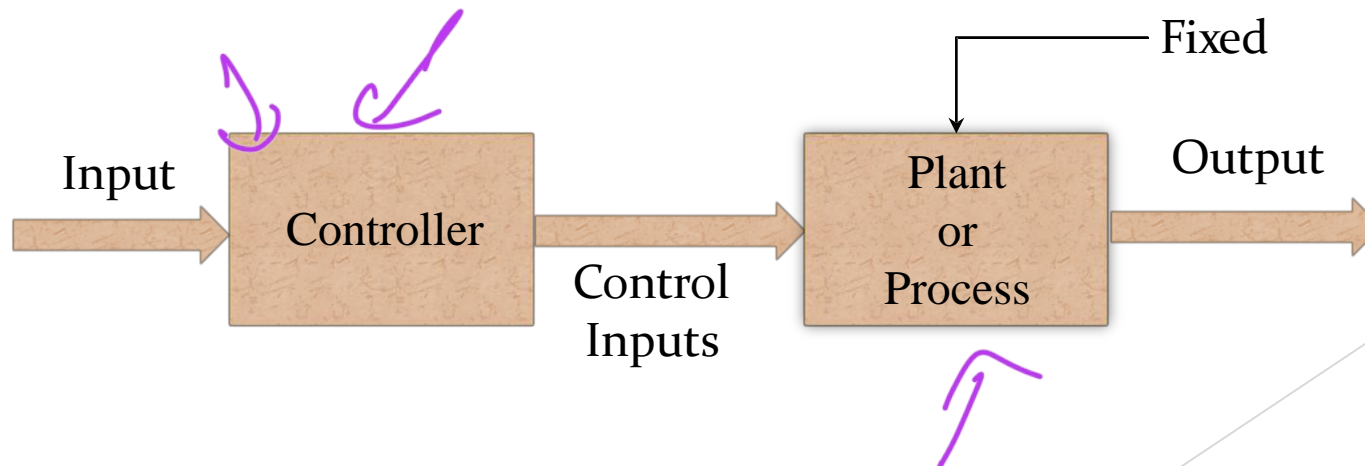
The actual response obtained from a control system due to the application of the input



# Terminology

## ▶ Controller

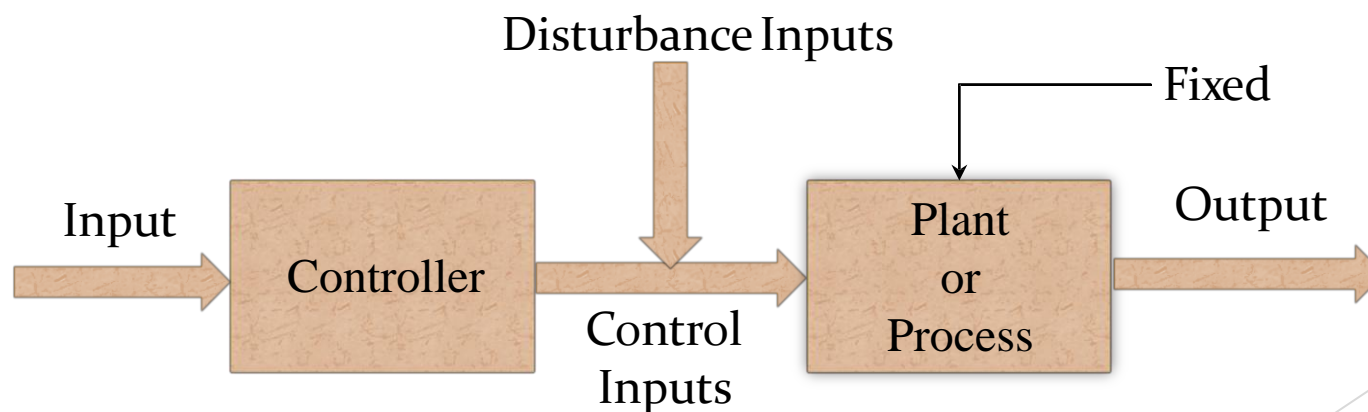
Internal or external element of the system used to control the plant or process. The controller generates plant input signals designed to produce the desired outputs. Some plant inputs are accessible to the designer and some are not available



# Terminology

## Disturbances

A disturbance is an uncontrollable input that has an undesired effect on the desired output of the system. It may be internal (produced within the system) or external



# Terminology

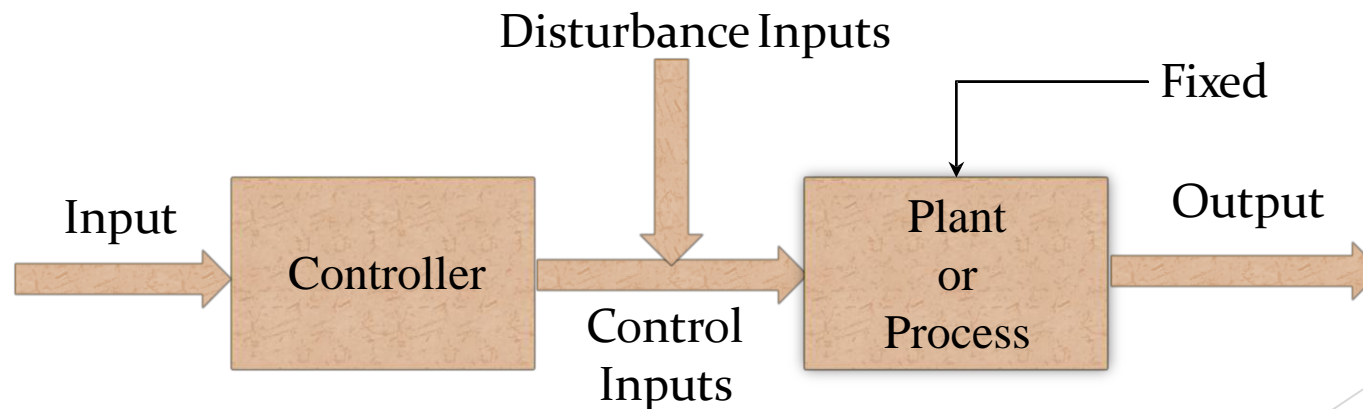
## ► Open Loop System

A system in which the control inputs are not influenced by the plant outputs i.e., there is no feedback around the plant

كيف الأشياء

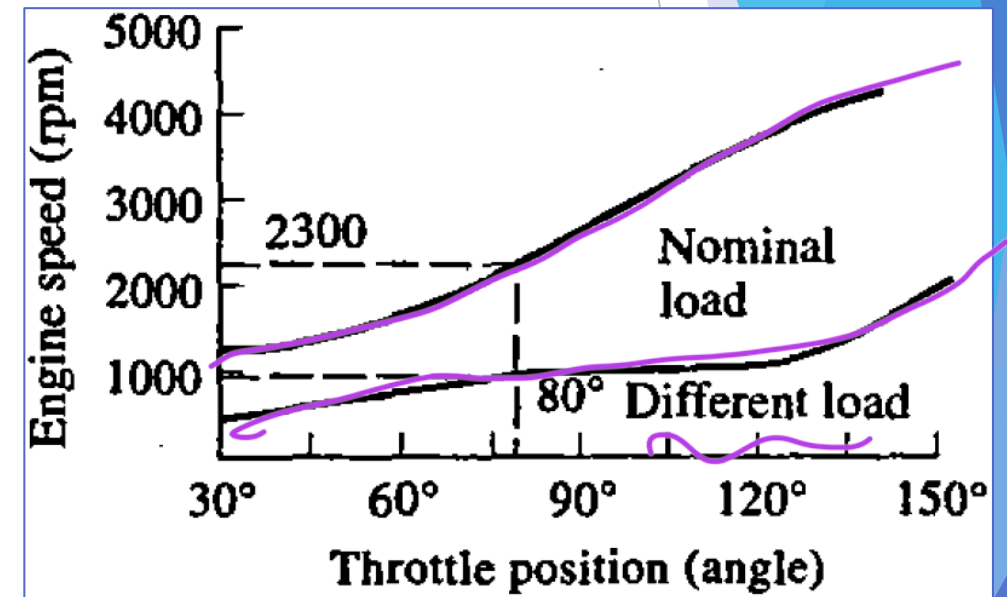
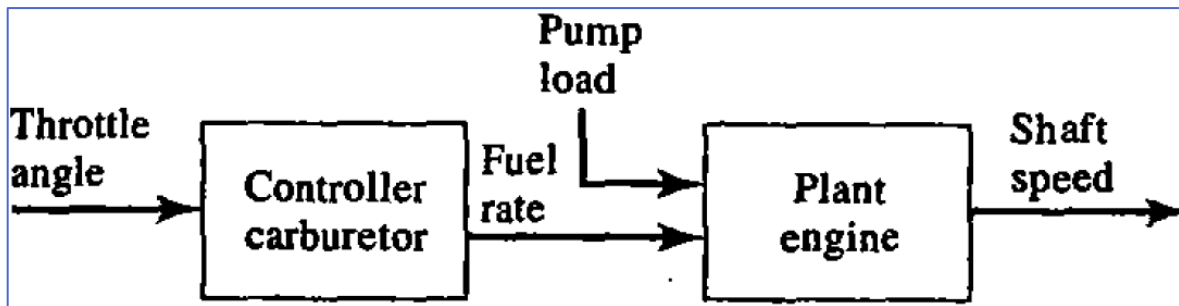


8-1 2, 3, 4



# Terminology

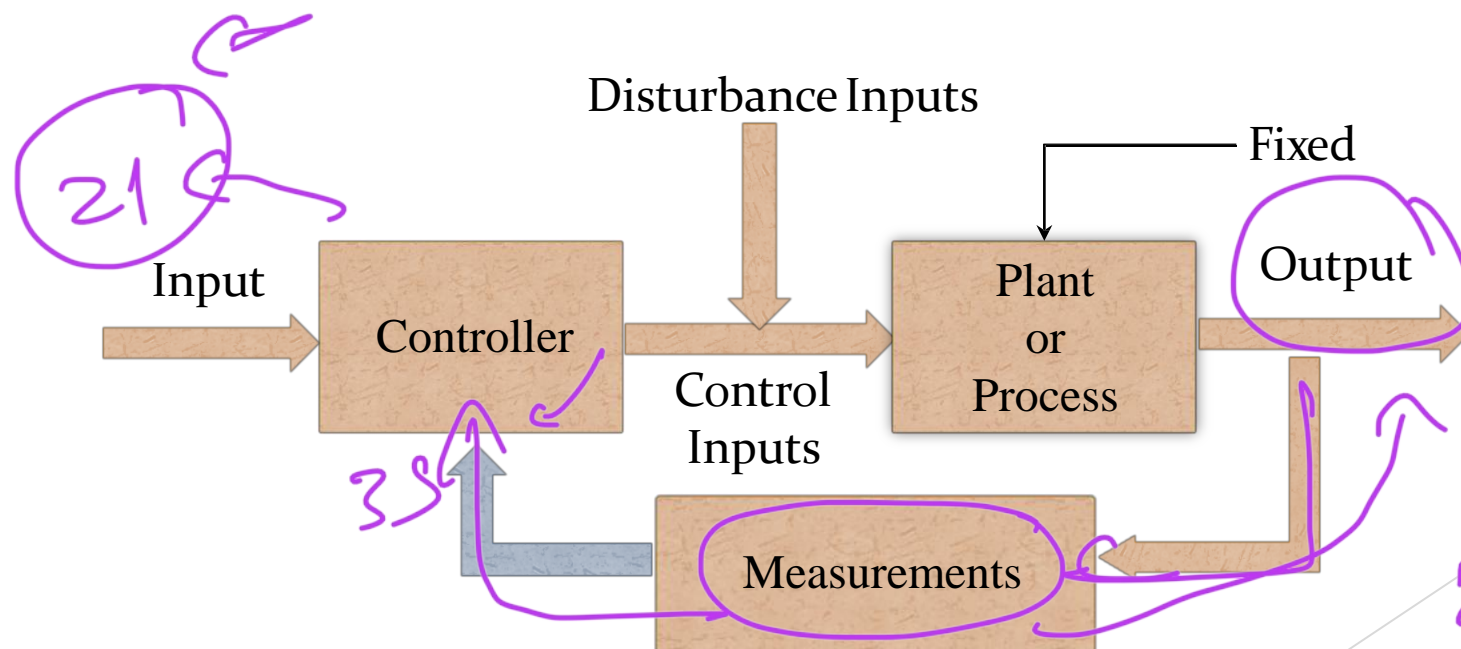
## ► Open Loop System



# Terminology

## ► Closed Loop System

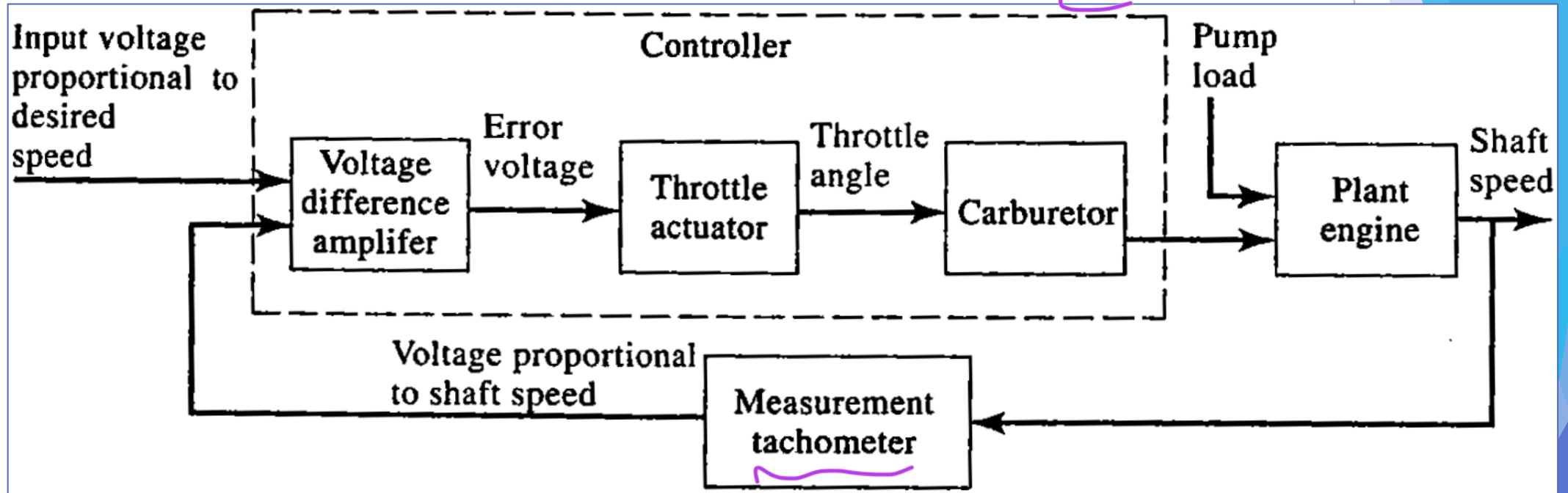
A system in which the control inputs are influenced by the plant outputs i.e., a path (or loop) is provided from the output back to the controller.



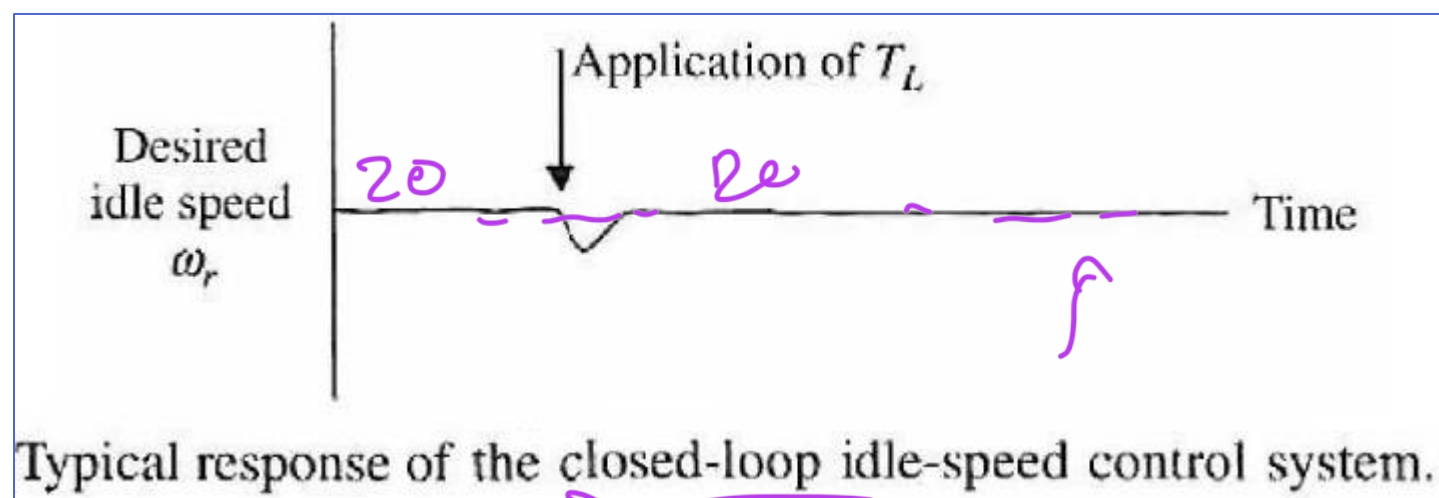
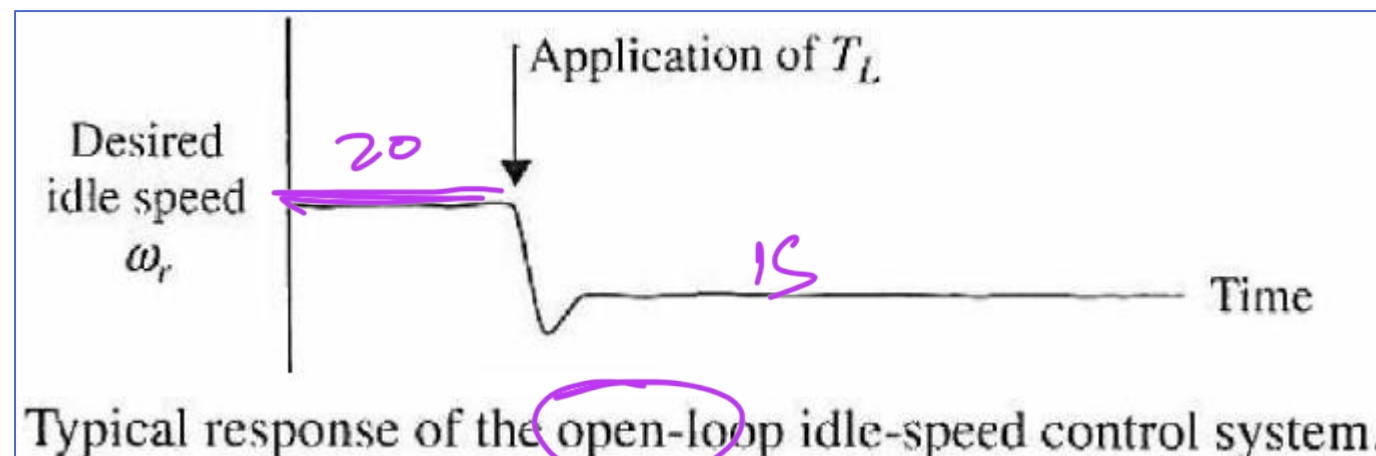
Sensor

# Terminology

## ► Closed Loop System



# Effect of Feedback





# Advantages of Feedback

- ▶ Increased accuracy
- ▶ Reduced sensitivity to changes in components
- ▶ Reduced effects of disturbances
- ▶ Increased speed of response and bandwidth

Feedback should be positive or negative?



# Examples of Open Loop & Closed Loop Control Systems

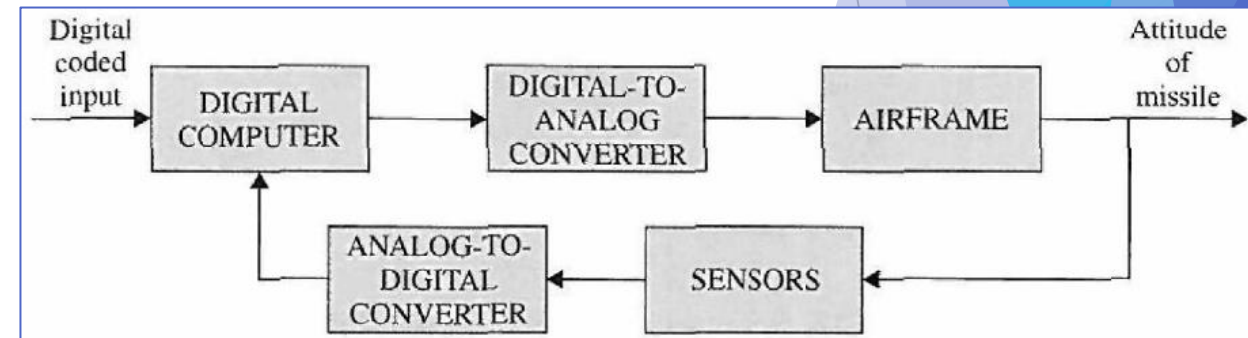
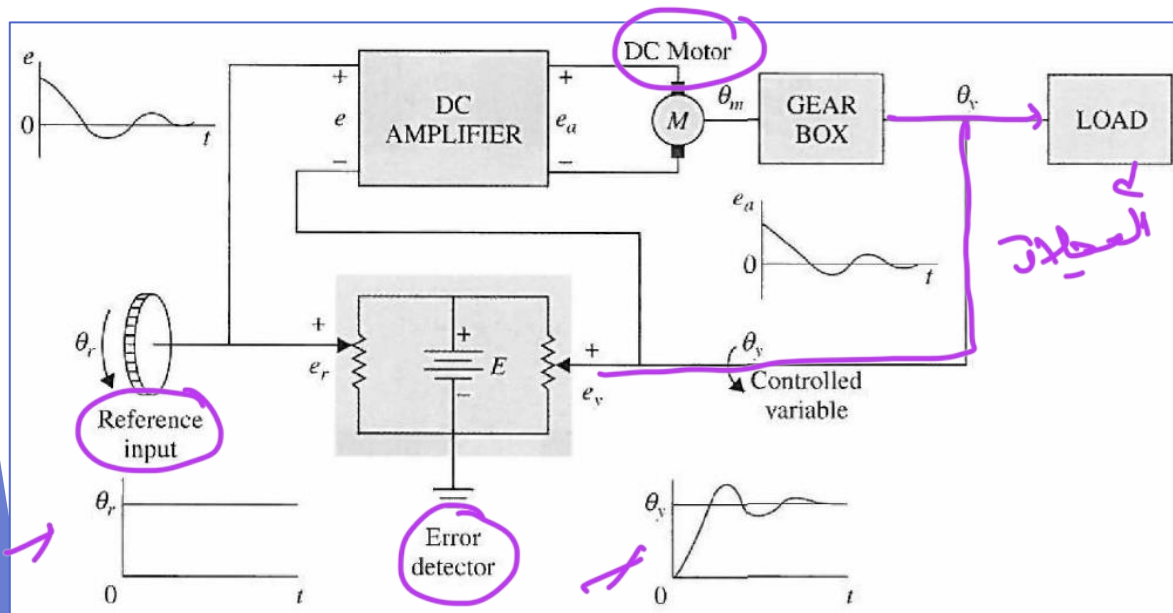
Input	Controller	Plant	Disturbance	Output	Measurement
Heat setting	Dial	Hair dryer	Hair dampness	Hot air temperature	None
Speed setting	Dial	Drill	Type of material	Rotating drill bit speed	None
Desired temperature	Thermostat	Furnace	Outside temperature	Hot air temperature	Room temperature
Desired speed	Cruise control	Auto engine	Driving conditions	Car speed	Engine rpm
Desired performance	Electorate	President	Economy	Decisions	Evaluation

Open Loop

close loop

# Types of Control Systems

- ▶ Linear VS Non-Linear Control Systems
- ▶ Time Invariant VS Time Variant Systems
- ▶ Continuous Data VS Discrete Data Control Systems



# Control System Applications

- ▶ Intelligent systems
  - ▶ Machine tools, Flexible robotics, Process control
- ▶ Control in virtual prototyping and hardware in the loop
- ▶ Smart Transportation Systems
  - ▶ Climate Control
  - ▶ Anti-lock Brake System (ABS)
  - ▶ Traction Control System
  - ▶ Cruise Control System
  - ▶ Dynamic Stability Control
  - ▶ Emergency Brake Assist
  - ▶ Drive-by-wire System / Steering Control
  - ▶ Driver Assist System
  - ▶ Active Suspension System and Cross Wind Stabilization

مکمل کنٹرول  
السیٹرونک سسٹمز