



## **ELECTRICAL ENGINEERING DEPARTMENT**

# EE242: Electric Circuits II

## Lecture 4-6


### AC (Sinusoidal) Analysis

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# AC Analysis

- 
- 1- Sinusoids and Phasor
  - 2- Circuit elements in Phasor domain (frequency domain)
  - 3- Impedance and admittance

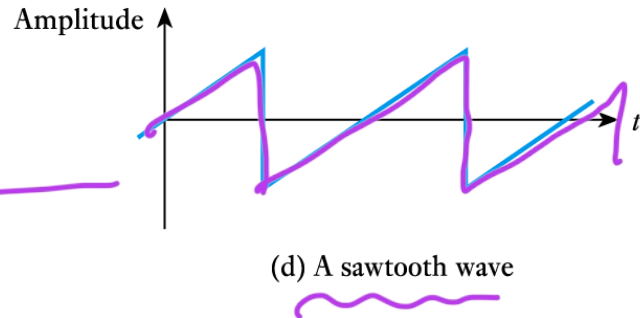
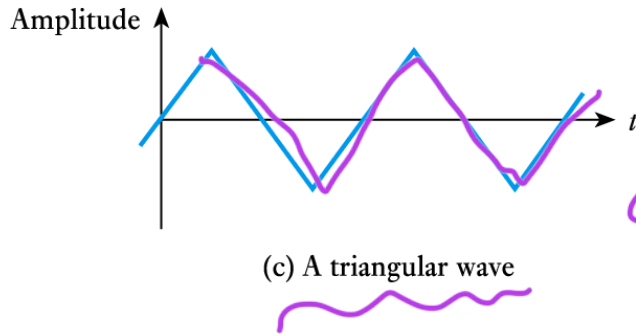
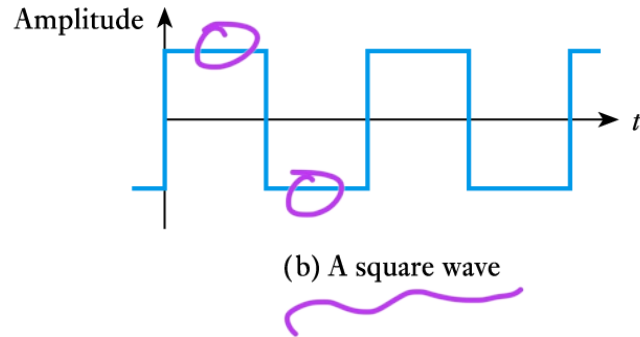
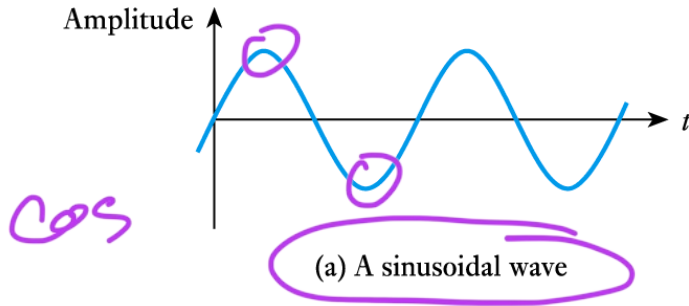


# 1-(a) Sinusoids



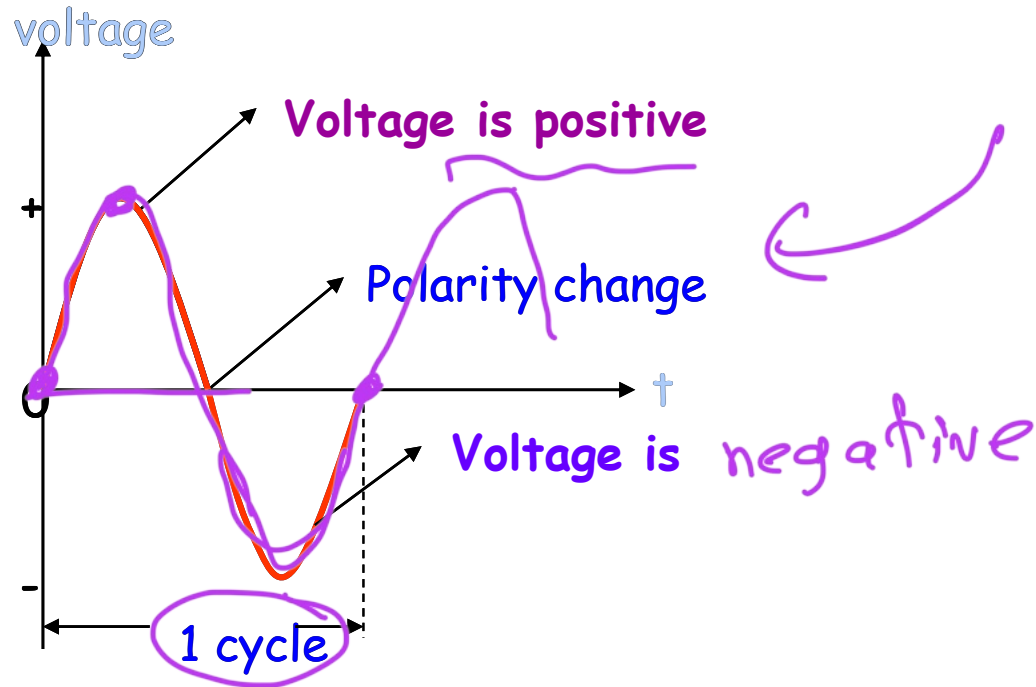
# Introduction- Alternating Current (AC) waveforms

- Alternating currents and voltages vary with time and periodically change their Polarity (the magnitude alternates between “+” and “-” values).



# Introduction- SINE WAVES

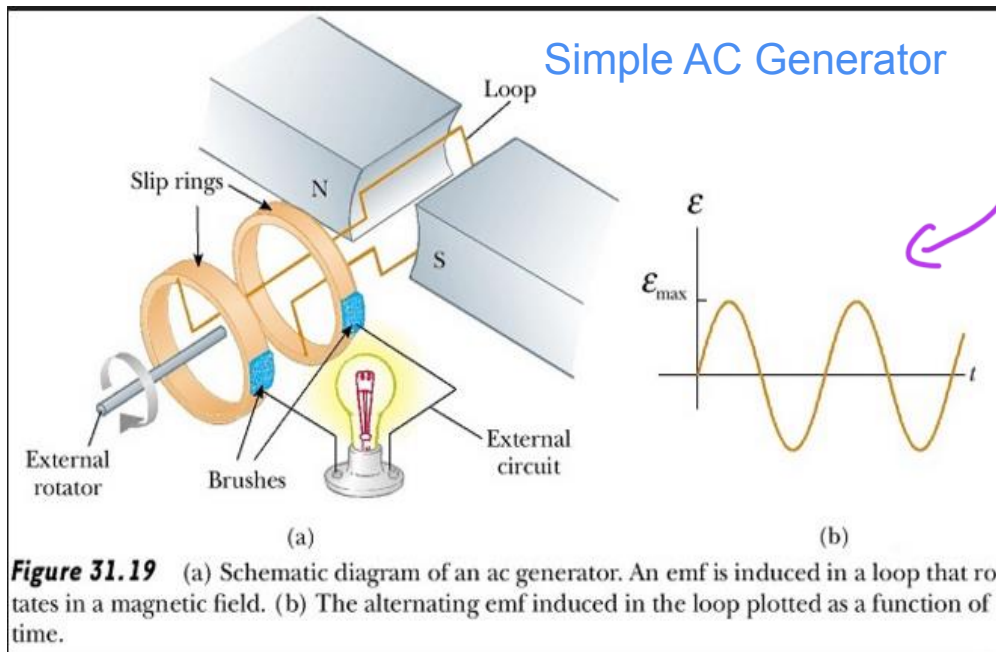
- Voltage can be produced such that, over time, it follows the shape of a sine wave.
- Sine waves by far are the most important form of alternating quantity.



# Introduction- GENERATING AC VOLTAGES



One way to generate ac voltage is to rotate a coil of wire at constant angular velocity in a fixed magnetic field.

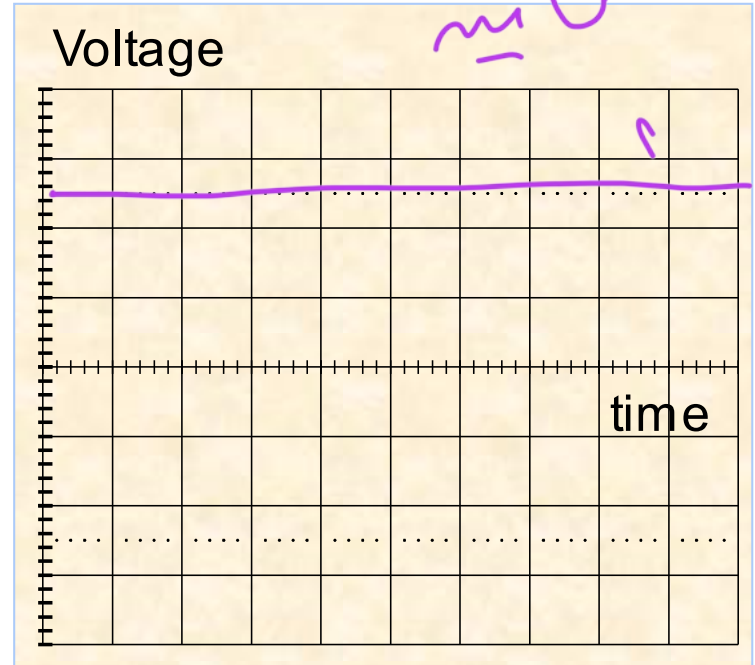
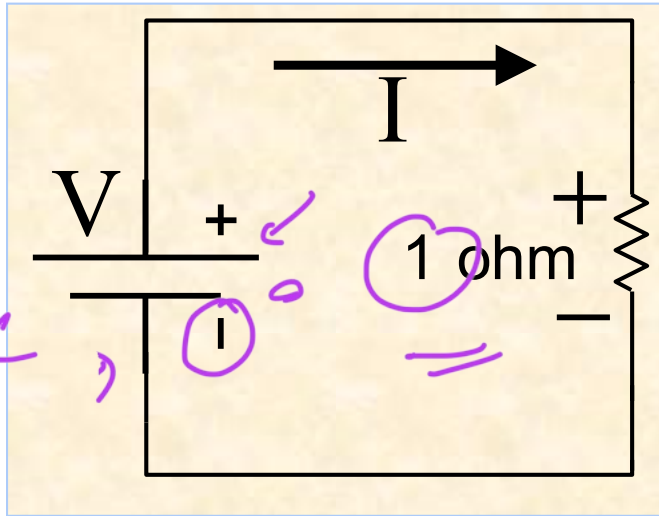


Click for more details about [Working Principle of AC Generator! - YouTube!](#)



# DC vs AC

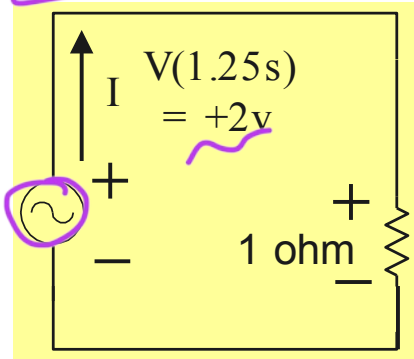
□ DC Source: voltage POLARITY of the source and current DIRECTION do not change over time.



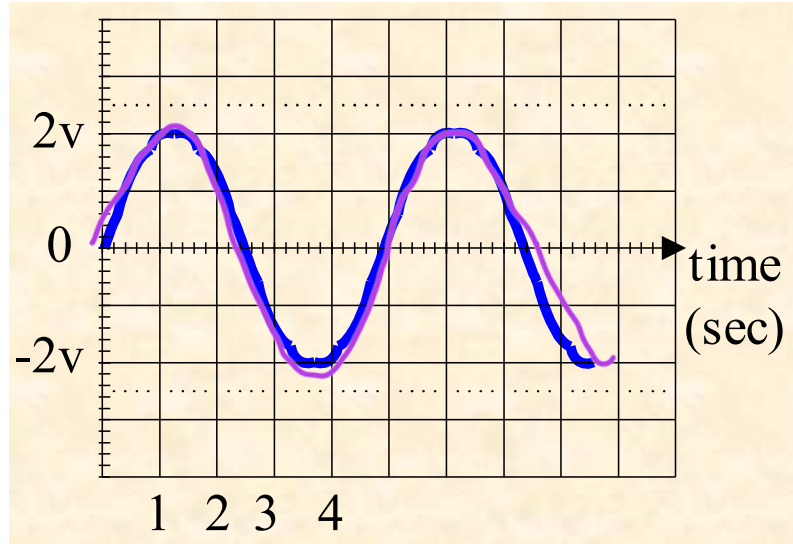
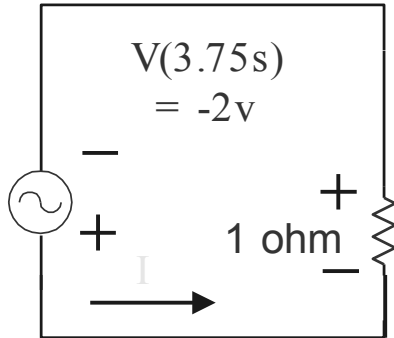


# DC vs AC

□ AC source: Voltage polarity changes therefore the current changes direction.



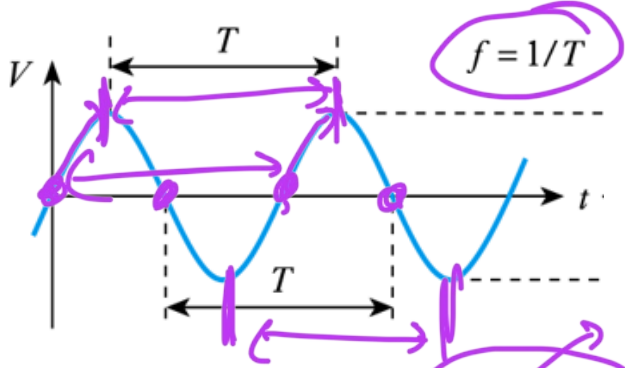
AC





# Sinusoids Characteristics: PERIOD AND FREQUENCY

➤ A sinusoid is a signal that has the form of the sine or cosine function.



- ✓ Period: Time to complete one complete cycle  
Symbol:  $T$   
Measured in second (s).
- ✓ Frequency: Number of cycles in one second  
Symbol:  $f$   
Measured in hertz (Hz).

تکرار  
بشکل  
دوره

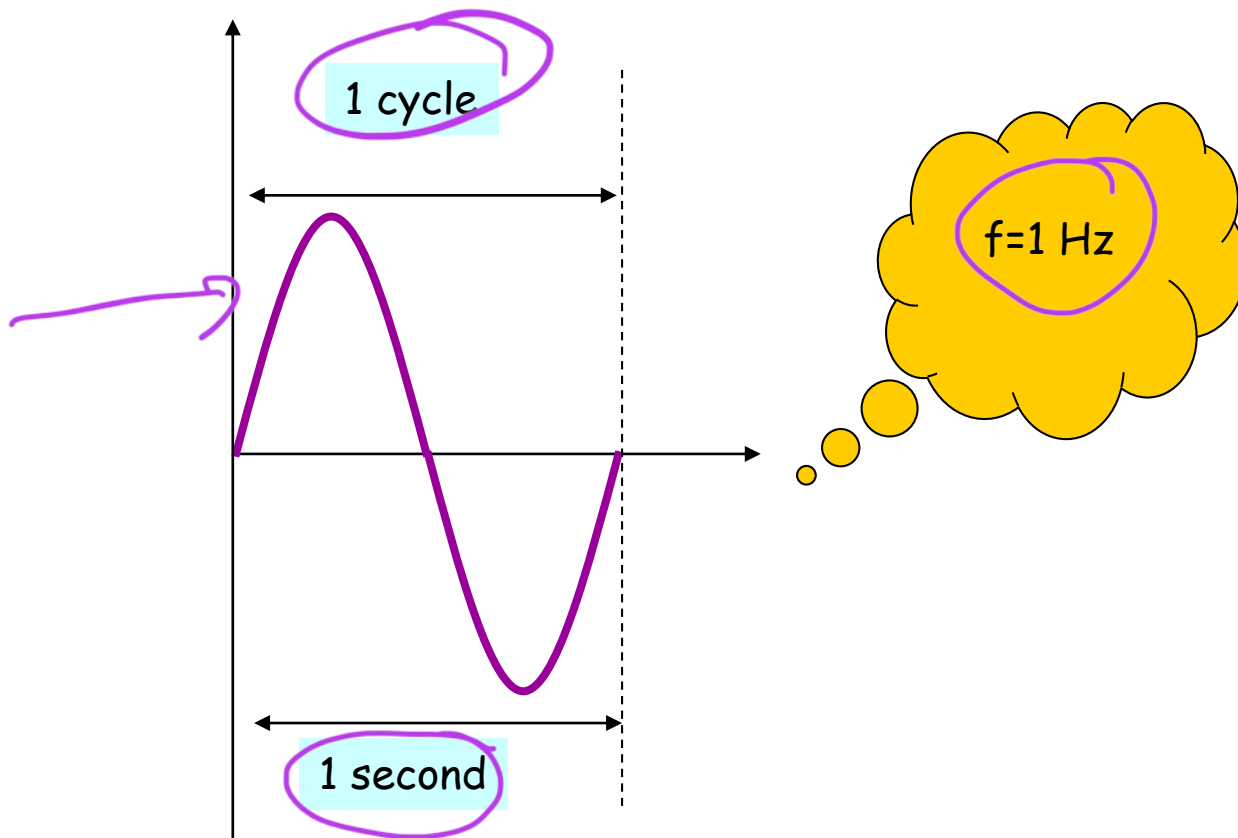
- ✓ A sinusoid is an example of a periodic signal.
- ✓ It repeats at regular time intervals: A section of a periodic signal between two consecutive maxima (or any other corresponding points) is called a cycle.
- The duration of a cycle is the period: Denoted by the Capital letter T.
- The number of cycles in one second is the frequency. Denoted by the lower case letter f.
- The unit of frequency is the hertz (Hz): where 1 Hz = 1 cycle per second.
- If f is the frequency in Hz and T is the period in seconds, then:

$$T = \frac{1}{f} \text{ (s) and } f = \frac{1}{T} \text{ (Hz)}$$



# Sinusoids Characteristics: 1- PERIOD AND FREQUENCY

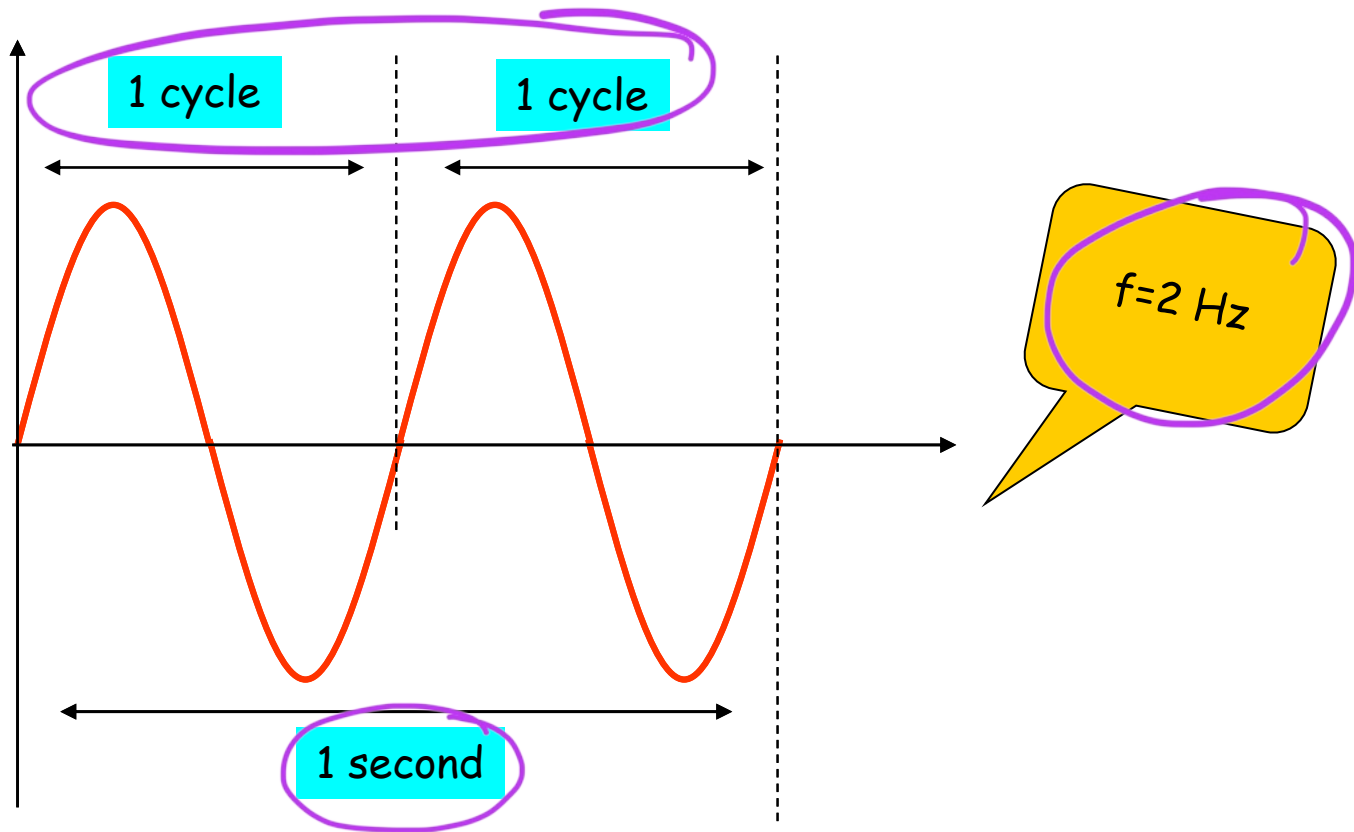
➤ Example:





# Sinusoids Characteristics: 1- PERIOD AND FREQUENCY

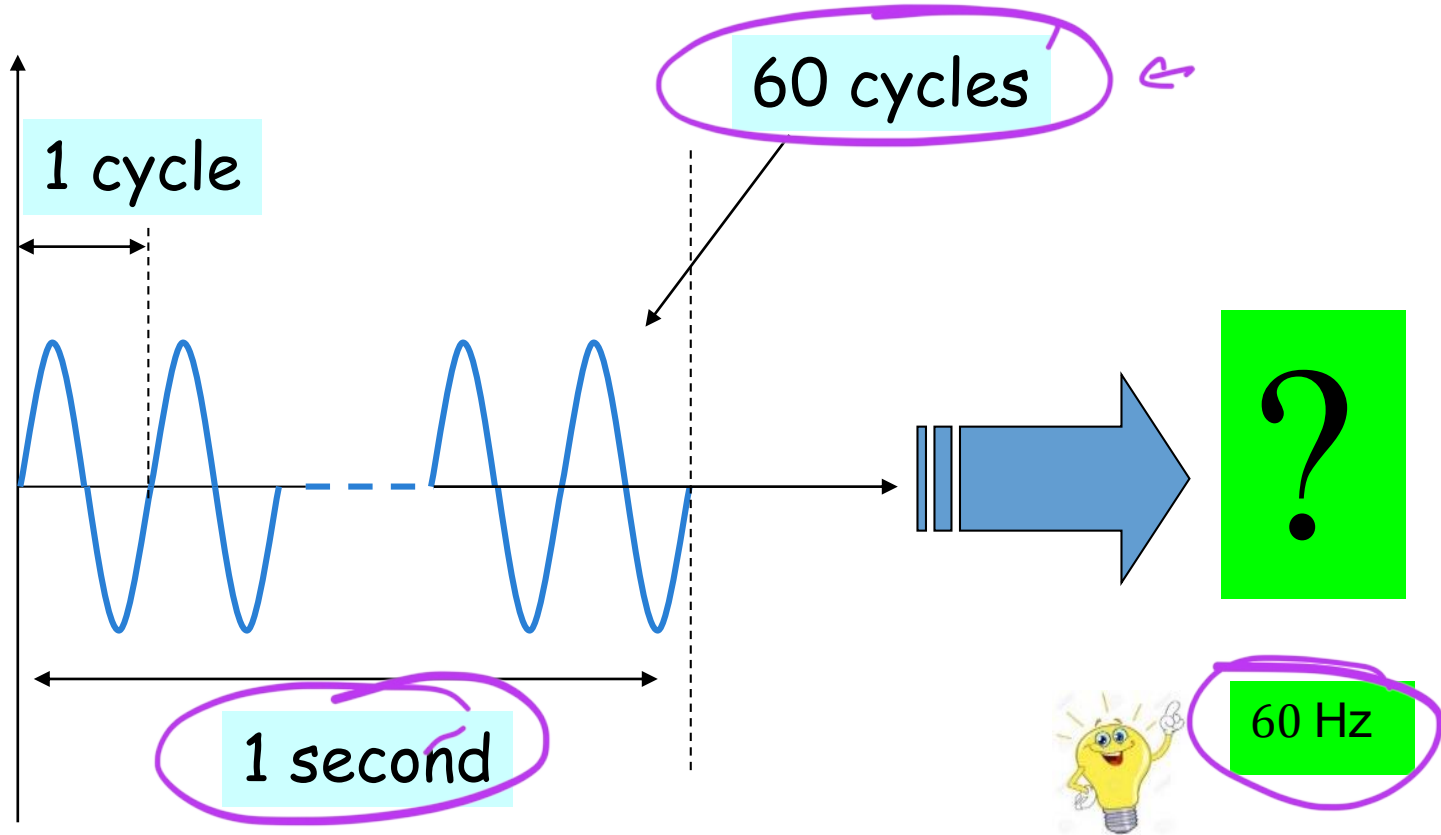
➤ Example:





# Sinusoids Characteristics: 1- PERIOD AND FREQUENCY

➤ Example:

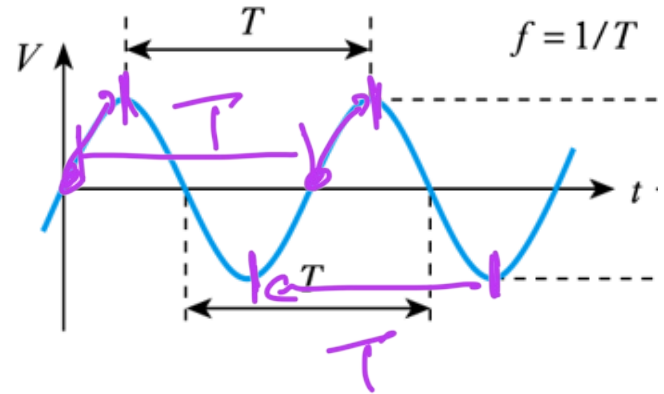
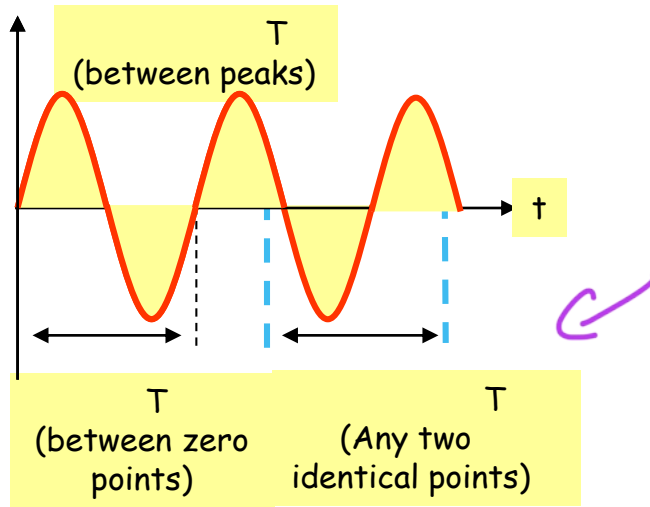




# Sinusoids Characteristics: 1- PERIOD AND FREQUENCY



- The period of a waveform can be measured between any two corresponding points.
- Often it is measured between zero points because they are easy to establish on an oscilloscope trace.

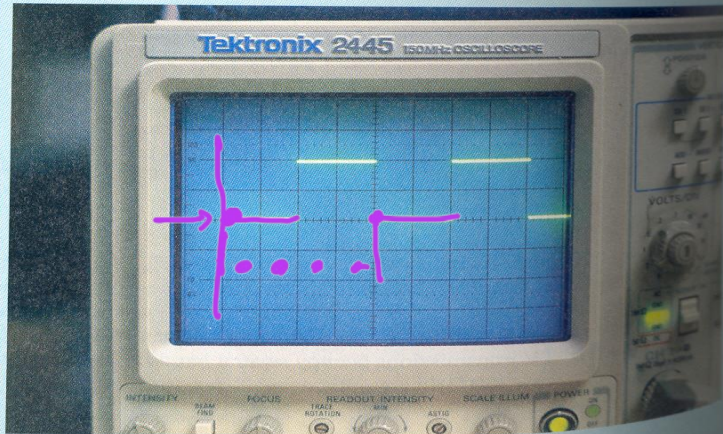




# Sinusoids Characteristics: 1- PERIOD AND FREQUENCY

## ➤ Example:

**EXAMPLE 15-3** Figure 15-16 shows an oscilloscope trace of a square wave. Each horizontal division represents  $50 \mu\text{s}$ . Determine the frequency.



**FIGURE 15-16** The concepts of frequency and period apply to nonsinusoidal waveforms.



This Figure shows an oscilloscope trace of a square wave. Each horizontal division represents  $50 \mu\text{s}$ . Determine the frequency?



4 squares  $\times 50 \mu\text{s}$

$$T = \frac{1}{5000}$$

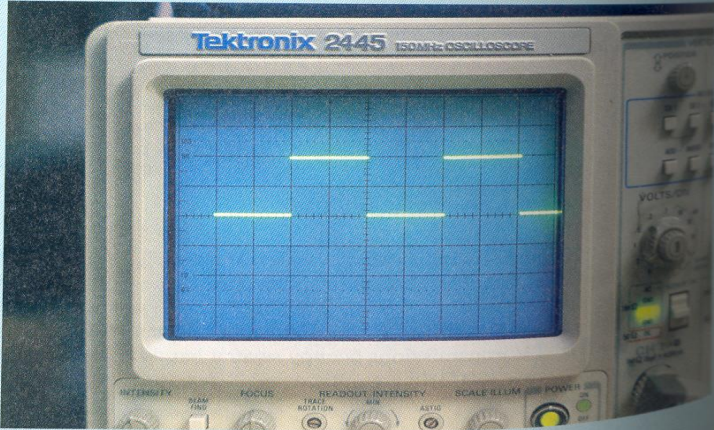
$$f = \frac{1}{T} = 5000 \text{ Hz}$$



# Sinusoids Characteristics: 1-PERIOD AND FREQUENCY

## ➤ Example:

**EXAMPLE 15-3** Figure 15-16 shows an oscilloscope trace of a square wave. Each horizontal division represents  $50 \mu\text{s}$ . Determine the frequency.



**FIGURE 15-16** The concepts of frequency and period apply to nonsinusoidal waveforms.



This Figure shows an oscilloscope trace of a square wave. Each horizontal division represents  $50 \mu\text{s}$ . Determine the frequency?

## Solution:

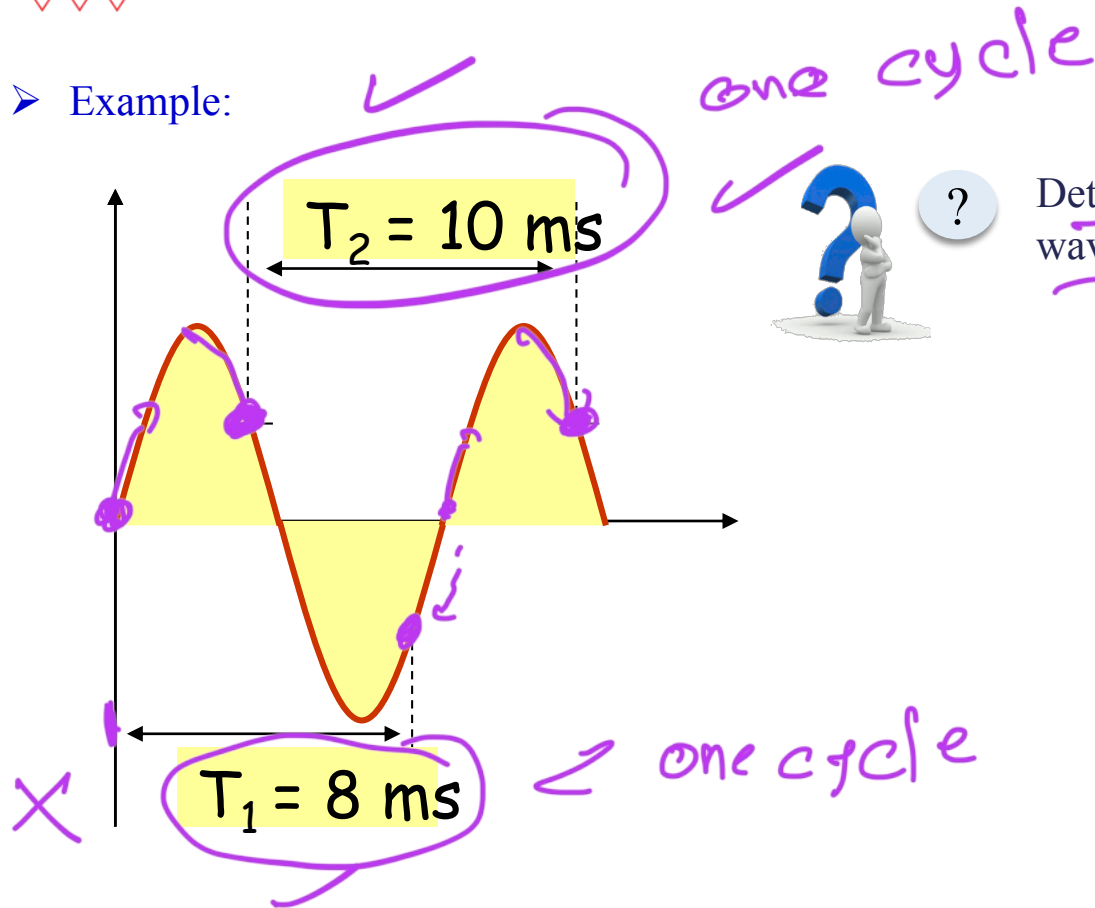
- Since the wave repeats itself every  $200 \mu\text{s}$  ( $4 \times 50 \mu\text{s}$ ), its period (T) is  $200 \mu\text{s} = 200 \times 10^{-6} \text{ s}$ , and:

$$f = \frac{1}{200 \times 10^{-6} \text{ s}} = 5 \text{ kHz}$$



# Sinusoids Characteristics: 1- PERIOD AND FREQUENCY

➤ Example:



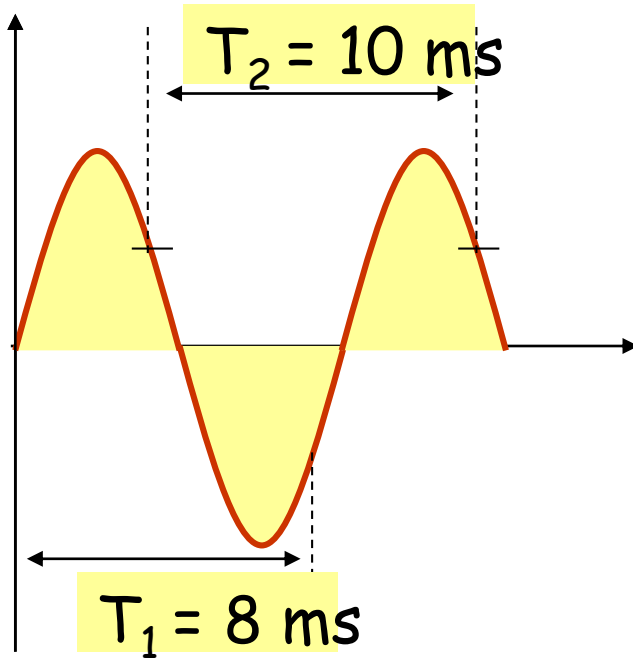
Determine the period and frequency of the waveform of the figure above.

$$f = \frac{1}{T} = \frac{1}{10 \times 10^{-3}}$$
$$= 100 \text{ Hz}$$



# Sinusoids Characteristics: 1- PERIOD AND FREQUENCY

➤ Example:



Determine the period and frequency of the waveform of the figure above.

**Solution:**

➤ Time interval  $T_1$  does not represent a period as it is not measured between corresponding points. Interval  $T_2$ , however, is. Thus,  $T = 10 \text{ ms}$  and,

$$f = \frac{1}{10 \times 10^{-3} \text{ s}} = 100 \text{ Hz}$$



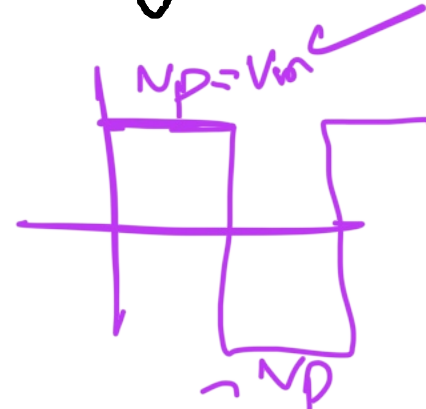
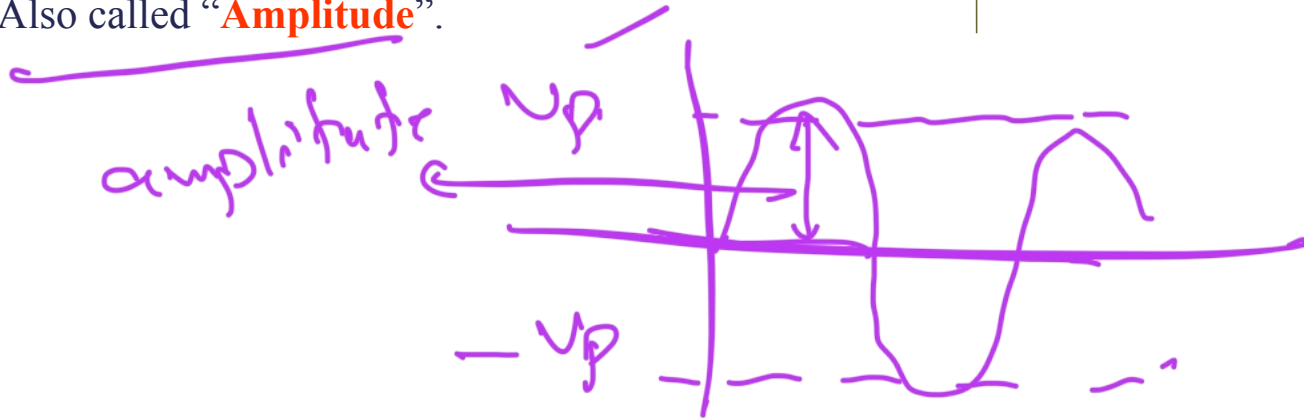
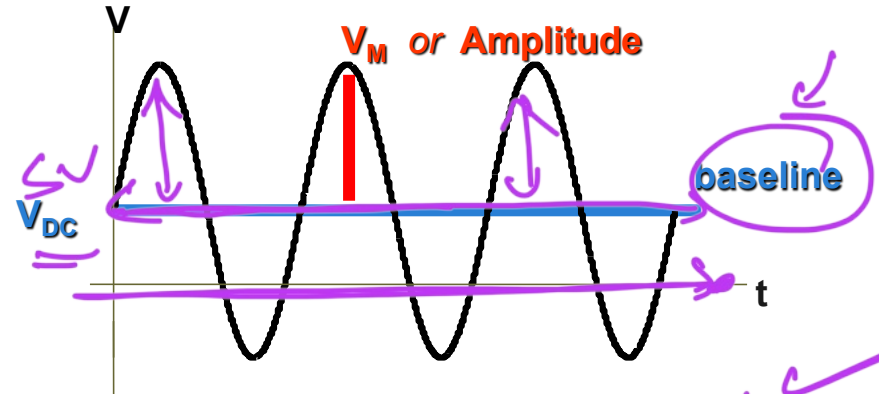
# Sinusoids Characteristics: 2-PEAK VALUES ( $V_p$ , $I_p$ )

$$v(t) = 1 \cos(3t) e$$

$$V_p = 1 \quad V_{avg} = 0.5V$$

$$v(t) = V_m \cos(\omega t + \theta)$$

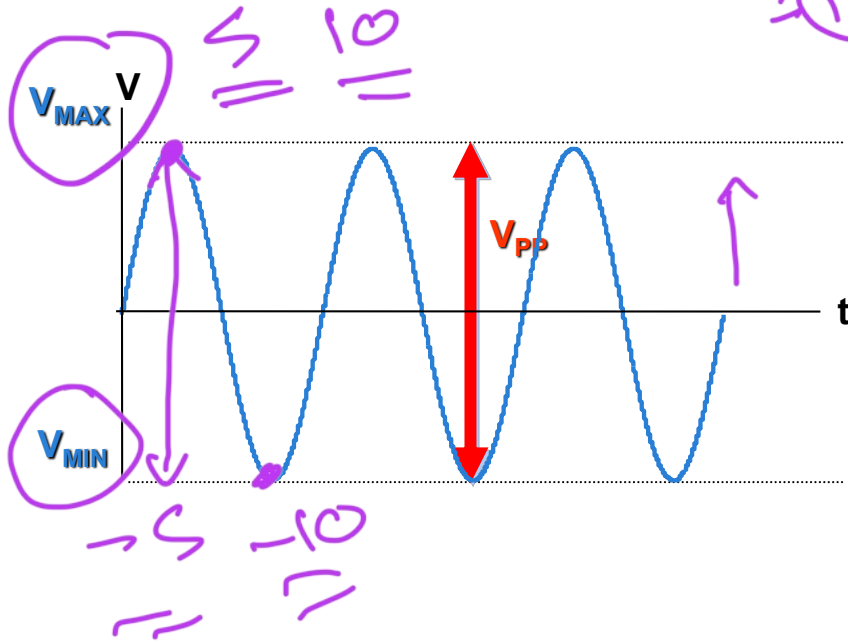
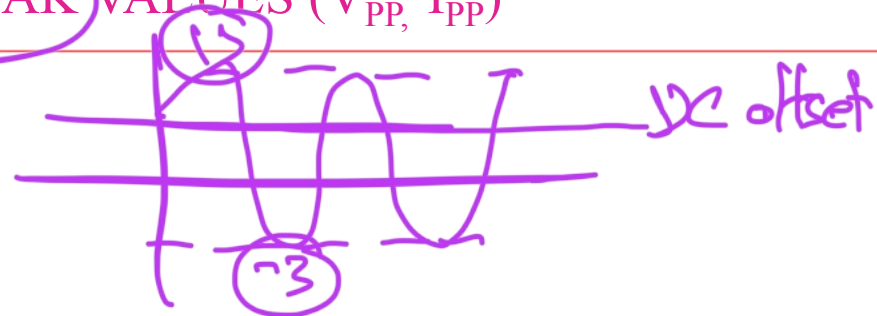
- Max Voltage (Current) : Symbol  $V_M$  ( $I_M$ ).
- The maximum value of  $V$  ( $I$ ) measured from the point of inflection (“baseline or DC offset”).
- From the graph:  $V_M - V_{DC}$ .
- Also called “Amplitude”.





# Sinusoids Characteristics: 3- PEAK TO PEAK VALUES ( $V_{PP}$ , $I_{PP}$ )

$$15 - (-3) = 18$$



- Peak to Peak Voltage (Current): Symbol  $V_{PP}$  ( $I_{PP}$ )
- The difference between the maximum value of V (I) and the minimum value of V (I)
- From the graph:  $V_{MAX} - V_{MIN}$
- Equals twice peak value:  $V_{PP} = 2V_P$



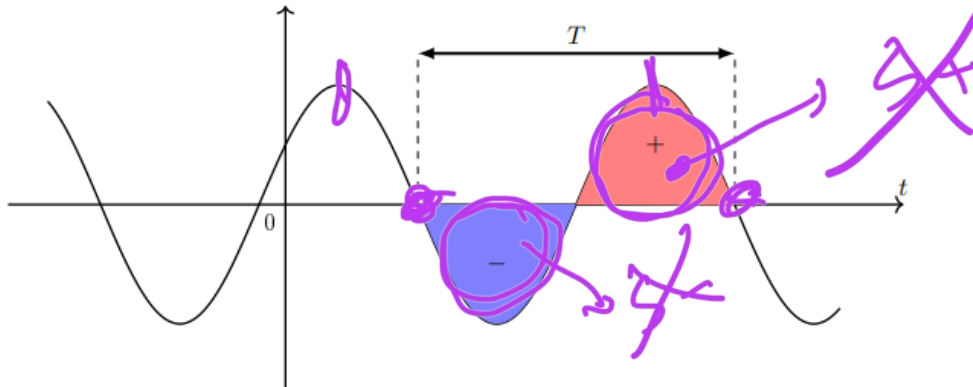
## Sinusoids Characteristics: 4- AVERAGE VALUE

- The average value (DC value) of a periodic signal can be calculated as follows:

$$V_{av} = \frac{1}{T} \int_0^T [v(t)] dt$$

$T$ : period

- The average value of a sinusoid signal is the integral of the sine wave over one full cycle.
- This is always equal to zero.

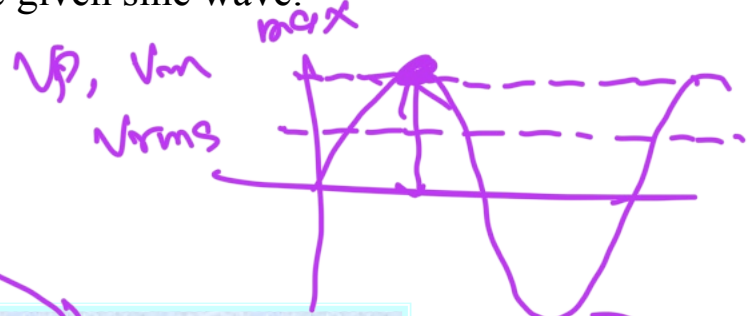




# Sinusoids Characteristics: 5- ROOT MEAN SQUARE ( $V_{RMS}$ , $I_{RMS}$ )

RMS ←

- ✓ Named for the mathematical process by which the value is calculated. **“Effective Voltage ( $V_{EFF}$ )”**
- ✓ The RMS value of a sine wave is equal to the value of an **equivalent DC circuit** that would produce the same heating effect or power in a load as the given sine wave.”
- ✓ Most **meters** read in RMS (lab DMM)
- ✓ The voltage accessed at electrical **wall sockets** is RMS.



100%

$$V_p = \sqrt{2} V_{RMS}$$

$$V_{RMS} = \frac{\sqrt{2}}{2} V_P = 0.707 \cdot V_P$$

$$V_{RMS} \approx V_p$$

$$V_{RMS} = \frac{V_p}{\sqrt{2}}$$



## Sinusoids Characteristics: 5- ROOT MEAN SQUARE ( $V_{RMS}$ , $I_{RMS}$ )

- The effective value of a periodic wave fore is known as the root mean square value.
- This is signified by  $V_{RMS}$ .
- RMS voltage and current are used to calculate the average power associated with the voltage or current signal in one cycle.
- The **RMS** voltage and current are used to calculate the average power associated with the voltage or current signal in one cycle.



$$V_{RMS} = \sqrt{\frac{1}{T} \int_0^T [v(t)]^2 dt}$$

$$V_{RMS} = \frac{V_p}{\sqrt{2}} = 0.707V_p$$

$$V_{RMS} = \frac{\sqrt{2}}{2} V_P = 0.707 \cdot V_P$$

$$P_{Ave} = (V_{RMS}^2) / R$$





# Sinusoids Characteristics: 6-COMPATIBILITY OF VALUES

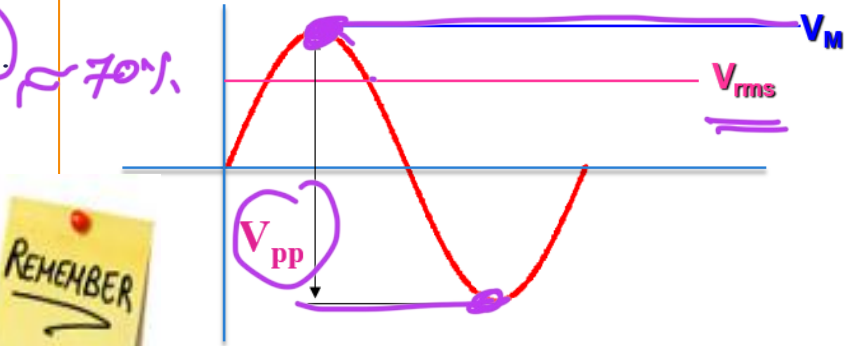
NOTE

$\sqrt{\frac{1}{T} \int_0^T \cos^2 t dt}$   
"rms"

$\sqrt{\cos^2 t}$   
peak

- When **Peak voltages** are used as source values, current calculations will also be in **Peak values**.
- Likewise, an **RMS** source produces answers in **RMS**.
- When solving a problem make sure all values are expressed **ONE** way (**peak**, peak to peak, or **RMS**)!

REMEMBER  
→

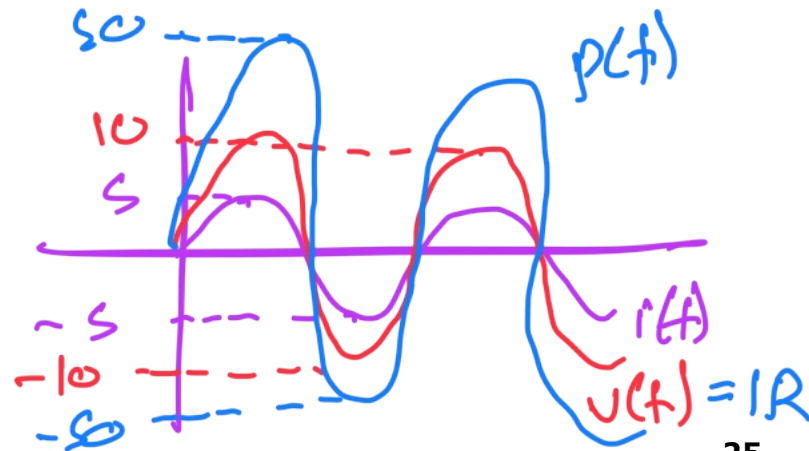




# Sinusoids Characteristics: 7-VOLTAGE & CURRENT VALUES

$$\underline{\underline{P = IV}}$$

- Ohm's Law still applies:  $V=IR$ .
- If current changes with time and R is a constant, voltage will also change with time.
- Voltage will be proportional to current.
- A graph of current and voltage in a resistor produces identical waveforms:
  - Peak at the same time;
  - Cross the same baseline, at the same time ;
  - Differ only in amplitude:
    - $I_p$  is  $1/R$  of  $V_p$





# Sinusoids Characteristics: 8- INSTANTANEOUS VALUES

## ❖ TIME DOMAIN

- Because the time to complete a cycle is frequency dependent, we can also identify points on the sine wave in terms of time:

$$v(t) = V_M \sin(2\pi ft \pm \theta)$$

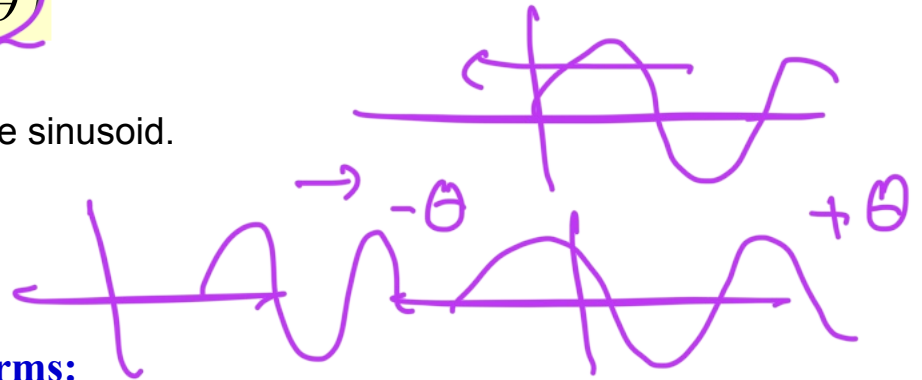
$$\omega = 2\pi f$$



Where:  $V_m$  = the **amplitude** of the sinusoid.

$\phi/\theta$  = the **phase**

$f$  = the **frequency**



## ❖ Angular Velocity of Sinusoidal Waveforms:

- The quantity  $2\pi f$  is equal to the **angular frequency**, which is denoted by the Greek letter  $\omega$  (omega).

$\omega$  rad/s

$$\omega = 2\pi f = \frac{2\pi}{T}$$

$$v(t) = V_m \sin(\omega t + \phi)$$



# Sinusoids Characteristics: 8- INSTANTANEOUS VALUES

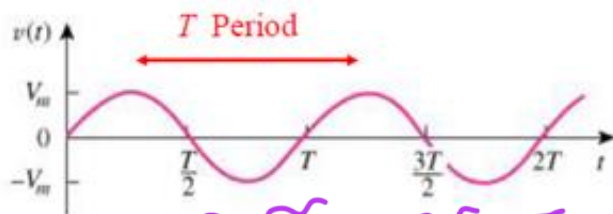


$$v(t) = V_M \sin(2\pi ft \pm \theta)$$

$$\omega = 2\pi f = \frac{2\pi}{T}$$

$$v(t) = V_m \sin(\omega t + \phi)$$

➤ Sketch of  $V_m \sin \omega t$ .



(a) As a function of  $t$ .



(b) As a function of  $\omega t$ .

$$\omega = \frac{2\pi}{T} \quad \rightarrow \quad \omega T = 2\pi$$



## Sinusoids Characteristics: 8- INSTANTANEOUS VALUES

instant

$$v(t = Ts)$$

- Instantaneous Values (  $v, i$  ): value of voltage and current at any:
  - Instant in time or
  - At any angle

➤ Mathematically expressed 2 ways:

$$v(t) = V_M \sin(2\pi ft \pm \theta)$$

$$v(\alpha) = V_M \sin(\alpha \pm \theta)$$



# Sinusoids Characteristics: 8- INSTANTANEOUS VALUES

rad  $\leftarrow \frac{\pi}{180} \rightarrow \text{deg}$

## ❖ ANGULAR DOMAIN

- We can **identify points on the sine wave** in terms of an angular measurement (degrees or radians).
- The instantaneous value of the sine wave can be related to the angular rotation of the generator:  
(T=1 rotation = 360°=2π radians).

$\Rightarrow$

$$\text{rad} = \left( \frac{\pi}{180^\circ} \right) \text{deg} \quad \longleftrightarrow \quad \text{deg} = \left( \frac{180^\circ}{\pi} \right) \text{rad}$$

deg  $\rightarrow$  rad  
 $\times \frac{\pi}{180}$

rad  $\rightarrow$  deg  
 $\times \frac{180}{\pi}$

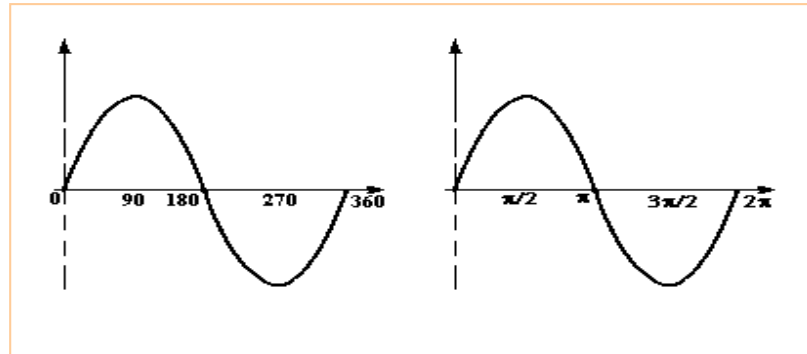
### □ Sine Wave Angles: Degrees & Radians

□ T=2π radians = 360°

1 radian = 57.3°

$\downarrow$

$(180/\pi) * 2\pi = 180 * 2 = 360^\circ$





# Sinusoids Characteristics: 8- INSTANTANEOUS VALUES

## ❖ ANGULAR DOMAIN



$$rad = \left( \frac{\pi}{180^\circ} \right) deg$$



$$deg = \left( \frac{180^\circ}{\pi} \right) rad$$

$$30^\circ \rightarrow \text{Radians} = \frac{\pi}{180^\circ}(30^\circ) = \frac{\pi}{6} \text{ rad}$$

$$90^\circ \rightarrow \text{Radians} = \frac{\pi}{180^\circ}(90^\circ) = \frac{\pi}{2} \text{ rad}$$



$$\frac{5\pi}{4} \text{ rad} \rightarrow \text{Degrees} = \frac{180^\circ}{\pi} \left( \frac{5\pi}{4} \right) = 225^\circ$$

$$\frac{3\pi}{2} \text{ rad} \rightarrow \text{Degrees} = \frac{180^\circ}{\pi} \left( \frac{3\pi}{2} \right) = 270^\circ$$

$$30 \times \frac{\pi}{180} = \frac{1}{6} \pi$$

$$\frac{5\pi}{4} \times \frac{180}{\pi} = 225^\circ$$

# Sinusoids Characteristics: 8- INSTANTANEOUS VALUES

$$R = 7 \Omega$$

## ❖ PHASE ANGLE (Angular Domain)

$$v(t) = V_M \sin(2\pi ft \pm \theta)$$

$$i(t) = 5 \cos(3t + 5)$$

$$v(t) = 10 \cos(3t + 5)$$

$$v(t) = i(t)R$$

in phase

can

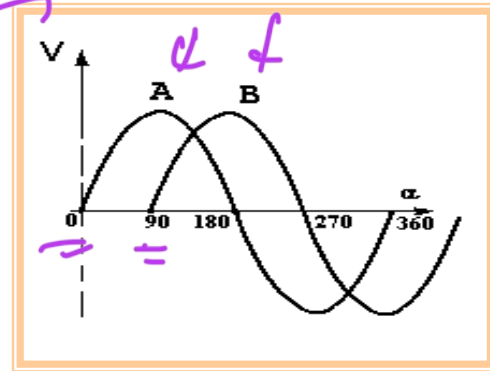
- Symbol is  $\theta$  (theta): It is expressed as an angle.
- Phase angle specifies the lateral shift in the position of a sine wave from a reference wave.
- Examine the same event, on each wave:
  - Two events occurring at the same angle or at the same time are in phase.
  - Events occurring at different angles or at different times are out of phase.

resistance  $\rightarrow$

ind / cap  $\rightarrow$  L/C

### ✓ Example:

- Wave A is the reference wave:
- Wave B is 90° out of phase.



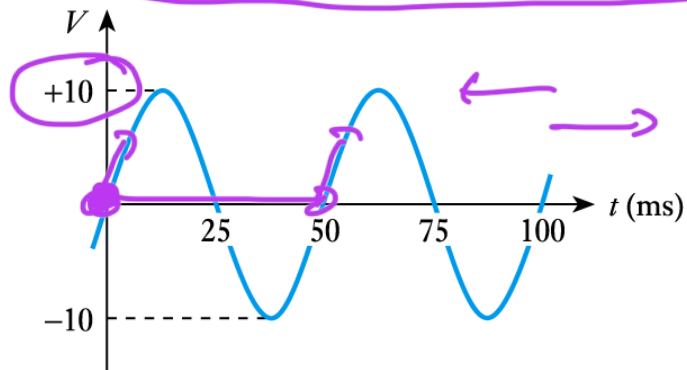


# Sinusoids Characteristics: 8- INSTANTANEOUS VALUES

## ❖ PHASE ANGLE (Angular Domain)

$$v(t) = V_M \sin(2\pi ft \pm \theta)$$

**Example:** Determine the equation of the following voltage signal.



$$T = 50 \text{ ms}$$

From diagram:

- Period is 50 ms = 0.05 s
- Thus  $f = 1/T = 1/0.05 = 20$  Hz
- Peak voltage is 10 V
- Therefore



$$\begin{aligned} v &= V_p \sin 2\pi ft \\ &= 10 \sin 2\pi 20t \\ &= 10 \sin 126t \end{aligned}$$

- The angle of the sine wave is zero at  $t = 0$ .

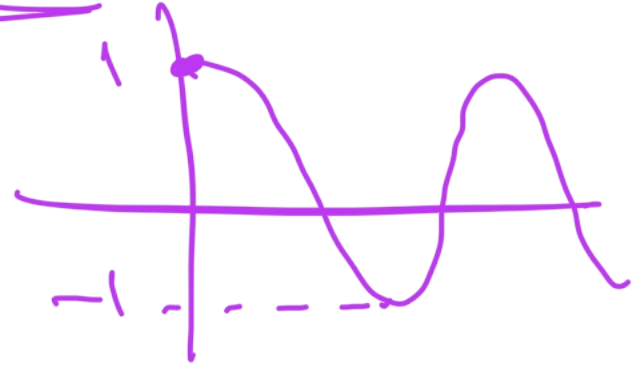
Sin



$$T = 50 \text{ ms}$$

$$f = \frac{1}{T} = \underline{20 \text{ Hz}}$$

cos



$$v(t) = 10 \sin(2\pi \times 20 t + \theta)$$

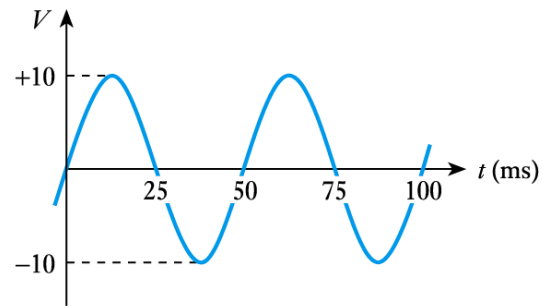
$$v(t) = 10 \sin(125.66 t)$$



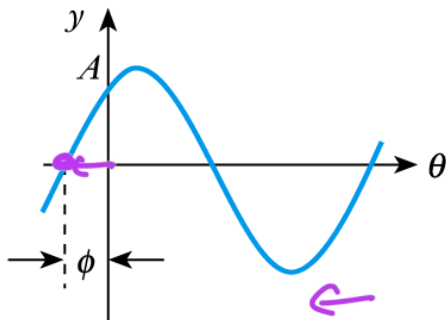
# Sinusoids Characteristics: 8- INSTANTANEOUS VALUES

## ❖ PHASE ANGLE (Angular Domain)

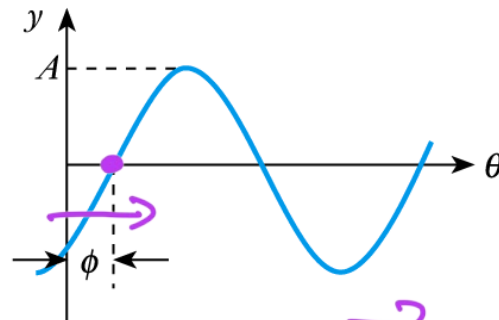
➤  $v(t) = V_m \sin(2\pi ft)$ : The angle of the sine wave is zero at  $t = 0$ .



➤ If this is not the case the expression is modified by adding the angle at  $t = 0$ .



(a)  $y = A \sin(\omega t + \phi)$



(b)  $y = A \sin(\omega t - \phi)$



# Sinusoids Characteristics: 8- INSTANTANEOUS VALUES

## ❖ PHASE ANGLE

✓ Example:

$$v(t) = V_M \sin(2\pi ft \pm \theta)$$



? Determine the Phase angle  $\theta$  of the waveform B of the figure above?

□ Wave A is the reference wave ( $\theta=0$ ).

➤ Compare the positive peak events:

➤ Wave A peaks at 30ms & Wave B at 60ms

➤  $T=120$ ms

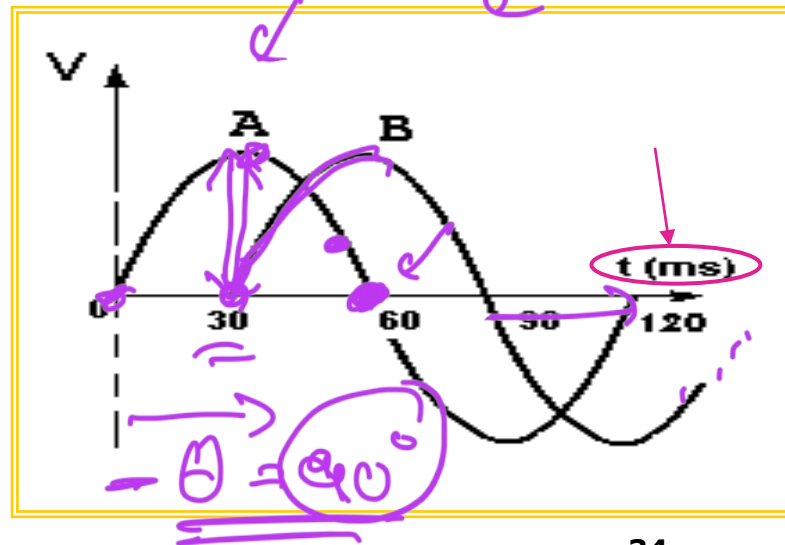


$$\theta / 360^\circ = \Delta t / T$$

$$\theta / 360^\circ = \Delta t / T$$

$$\theta / 360^\circ = (30\text{ms} - 0\text{ms}) / 120\text{ms} = 30 / 120$$

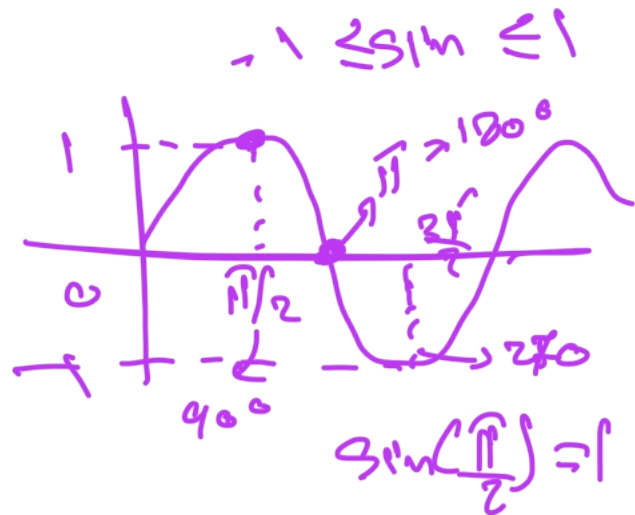
$$\theta = 360 \times 30 / 120 = 90^\circ$$



A Peak = 30 ms  $\rightarrow T = 120$  ms

B Peak = 60 ms

$$\frac{\theta}{360} = \frac{\Delta t}{T} = \frac{30}{120}$$



~~360~~  $\times \frac{\theta}{360} = \frac{30}{120} \times 360 \rightarrow \theta = 90^\circ$   
max  $\times$  A peak = 90°

$$\frac{60}{120} \times 360 = 180^\circ$$

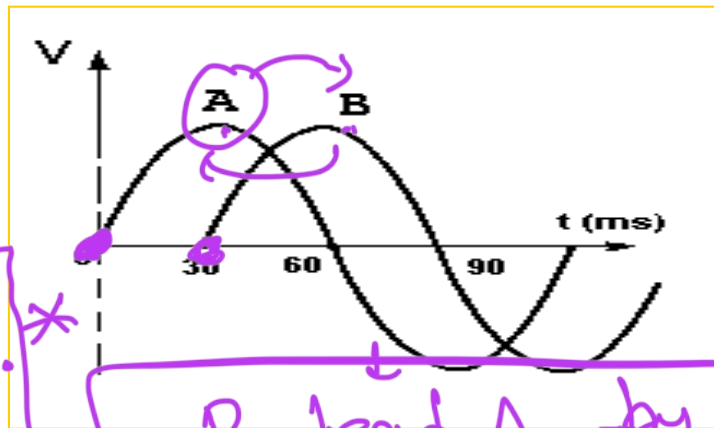


# Sinusoids Characteristics: 9- LEADING & LAGGING

- Since wave B peaked after the reference wave peaked, we say it LAGS the reference wave by  $90^\circ$ .  $\theta = -90^\circ$
- If wave B was the reference, wave A would peak before the reference wave (B): we would say it LEADS the reference wave:  $\theta = +90^\circ$

NOTE

Because it is the reference wave,  $\theta$  for ANY reference wave is  $0^\circ$ .



الموجة

A lead B by  $90^\circ$  \*

B lag A by  $90^\circ$

التي  
سوية

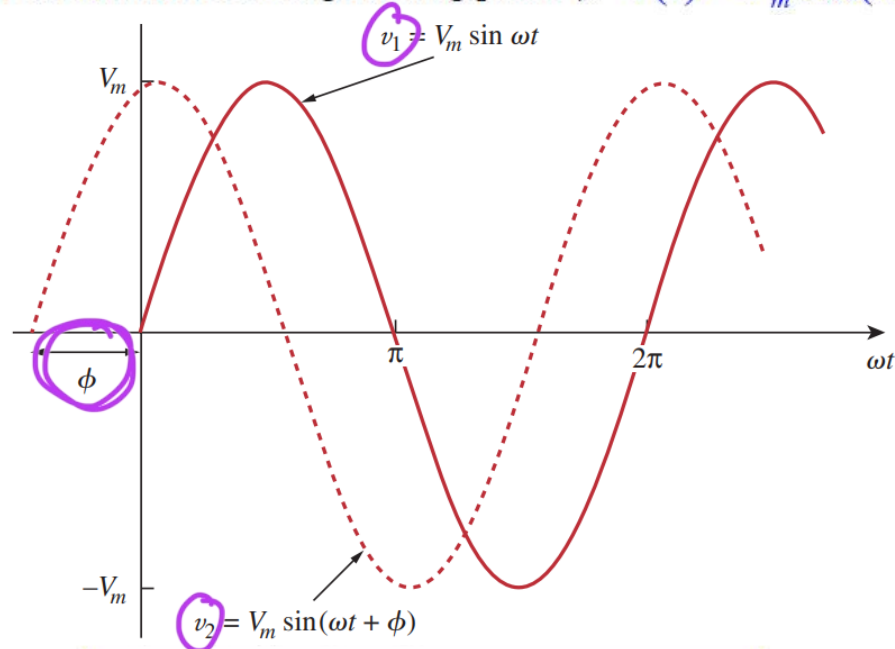
B lead A by  $-90$

A lag B by  $-90$



## Sinusoids Characteristics: 9- LEADING & LAGGING

✓ Example 2: Consider the sinusoidal voltage having phase  $\phi$ ,  $v(t) = V_m \sin(\omega t + \phi)$

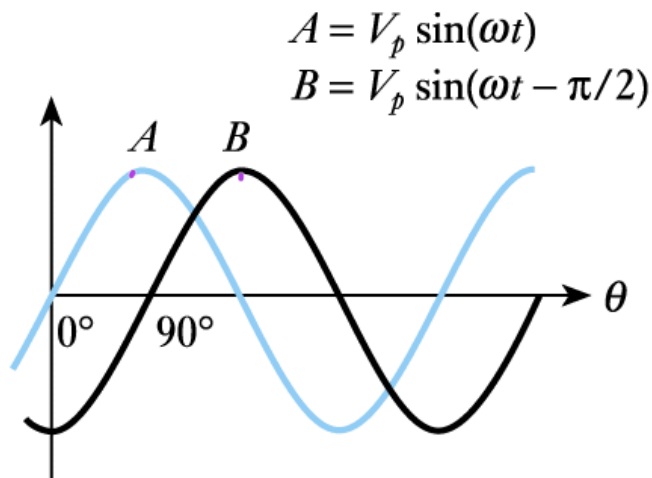


- $v_2$  LEADS  $v_1$  by phase  $\phi$ .
- $v_1$  LAGS  $v_2$  by phase  $\phi$ .
- $v_1$  and  $v_2$  are out of phase.



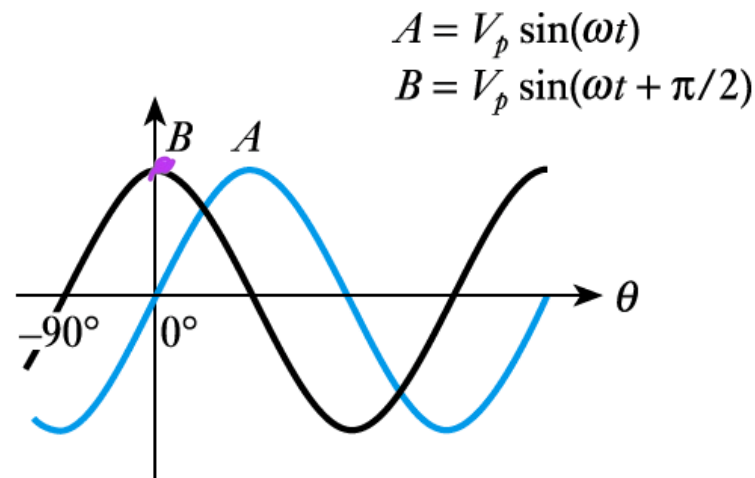
# Sinusoids Characteristics: 8- LEADING & LAGGING

✓ Example 3:



(a)  $B$  lags  $A$  by  $90^\circ$

*A leads B by 90*



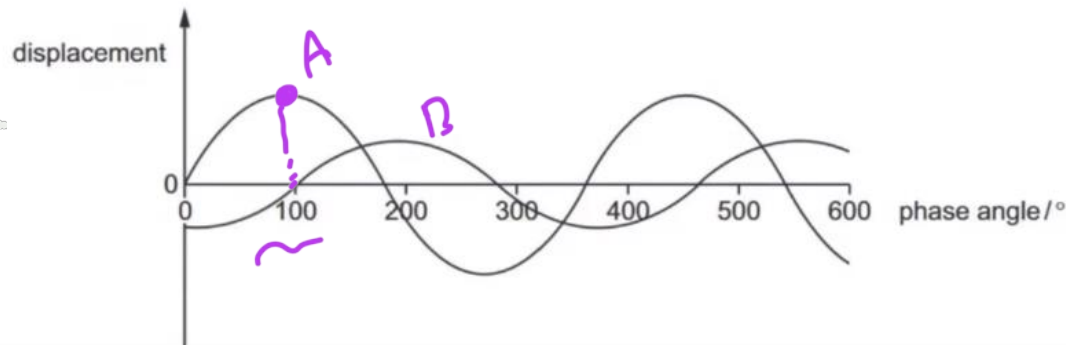
(b)  $B$  leads  $A$  by  $90^\circ$

*A lags B by 90*

# Sinusoids Characteristics: 8- LEADING & LAGGING

✓ Example 4:

Two light waves of the same frequency are represented by the diagram.



What could be the phase difference between the two waves?

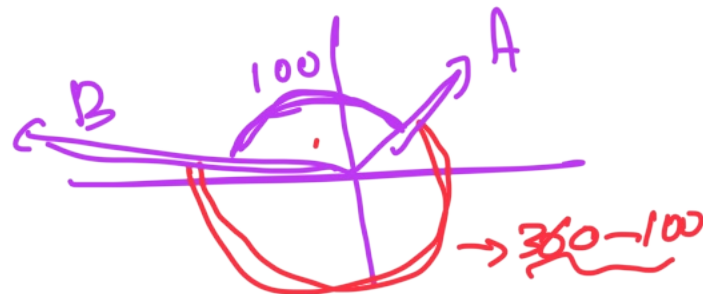
- A 150°      B 220°      **C 260°**      D 330°

A lead B by 100°  
B lag A by 100°

➤ Since wave B peaked **after** the reference wave peaked, we say it **LAGS** the reference wave by 90° :

$$\theta = -100^\circ$$

$$\theta = 360 - 100^\circ = 260^\circ$$



## Sinusoids Characteristics: 8- LEADING & LAGGING

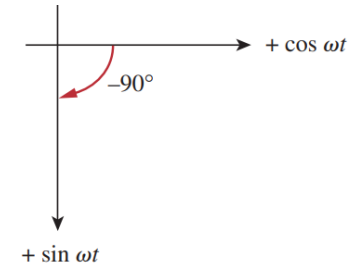
- A sinusoid can be expressed in either sine or cosine form.
- When comparing two sinusoids, it is expedient to **express both as either sine or cosine** with **positive amplitudes**.

$$\begin{aligned}\sin(A \pm B) &= \sin A \cos B \pm \cos A \sin B \\ \cos(A \pm B) &= \cos A \cos B \mp \sin A \sin B\end{aligned}\quad (9.9)$$

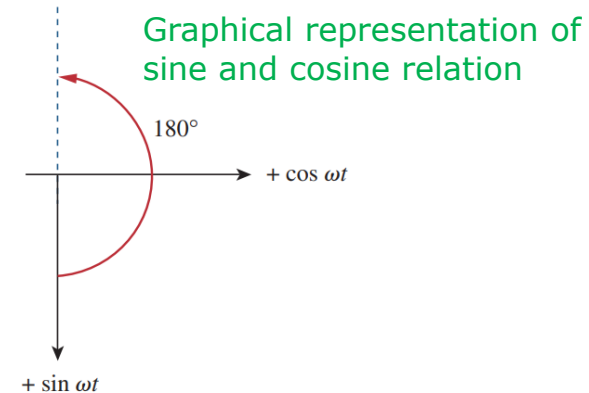
With these identities, it is easy to show that

$$\begin{aligned}\sin(\omega t \pm 180^\circ) &= \mp \sin \omega t \\ \cos(\omega t \pm 180^\circ) &= \mp \cos \omega t \\ \sin(\omega t \pm 90^\circ) &= \pm \cos \omega t \\ \cos(\omega t \pm 90^\circ) &= \mp \sin \omega t\end{aligned}\quad (9.10)$$

Using these relationships, we can transform a sinusoid from sine form to cosine form or vice versa.



(a)



(b)

$$\left. \begin{aligned} -7 \sin(\omega t) &\rightarrow 7 \sin(\omega t \pm 180) \\ -8 \cos(\omega t - 30) &\rightarrow +8 \cos(\omega t - 30 - 180) \\ &\quad -210 \end{aligned} \right\}$$

---

$$\begin{aligned} + \cos(\omega t) &\rightarrow \sin(\omega t + 90) \\ \underline{\underline{=}} \cos(\omega t) &\rightarrow \sin(\omega t - 90) \end{aligned}$$

---

$$\begin{aligned} + \sin(\omega t) &\rightarrow + \cos(\omega t - 90) \\ \underline{\underline{-}} \sin(\omega t) &\rightarrow + \underline{\underline{\cos}}(\omega t + \underline{\underline{90}}) \end{aligned}$$

## Example 5

Given a sinusoid,  $5 \sin(4\pi t - 60^\circ)$ , calculate its amplitude, phase, angular frequency, period, and frequency.

### Solution:

Amplitude = 5,  $\sqrt{A}$   
phase =  $-60^\circ$   
angular frequency =  $4\pi$  rad/s,  
Period = 0.5 s,  
frequency = 2 Hz.

$$\omega = \frac{2\pi f}{2\pi} \quad f = \frac{\omega}{2\pi}$$
$$f = 2 \text{ Hz}$$
$$T = \frac{1}{f} = \frac{1}{2} \text{ s}$$

## Example 6

Find the phase angle between  $i_1 = -4\sin(377t + 25^\circ)$  and  $i_2 = 5\cos(377t - 40^\circ)$   
Does  $i_1$  lead or lag  $i_2$ ?

Solution:

✓ Since  $\cos \omega t = \sin(\omega t + 90^\circ)$

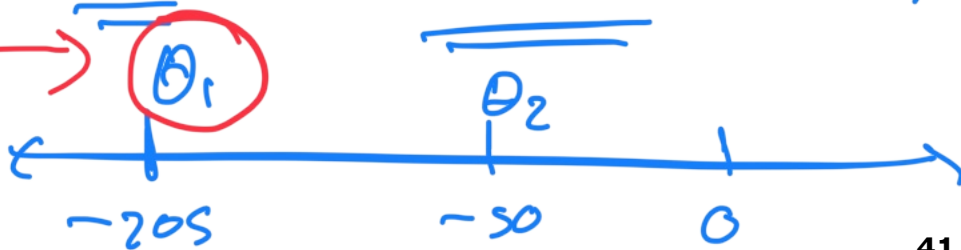
$$i_2 = 5\sin(377t - 40^\circ + 90^\circ) = 5\sin(377t + 50^\circ)$$

$$i_1 = -4\sin(377t + 25^\circ) = 4\sin(377t + 180^\circ + 25^\circ) = 4\sin(377t + 205^\circ)$$

➤ Therefore,  $i_1$  leads  $i_2$   $155^\circ$ .



$$\begin{aligned}\sin(\omega t \pm 180^\circ) &= -\sin \omega t \\ \cos(\omega t \pm 180^\circ) &= -\cos \omega t \\ \sin(\omega t \pm 90^\circ) &= \pm \cos \omega t \\ \cos(\omega t \pm 90^\circ) &= \mp \sin \omega t\end{aligned}$$



$$i_1(t) = -4 \sin(\underline{377}t + 25) * 4 \cos(\underline{377}t + 25 + 90)$$

$$i_2(t) = \underline{+5} \cos(\underline{377}t - 40)$$

لحقی تقارن، پیش، lag و lead) لوجر تسود

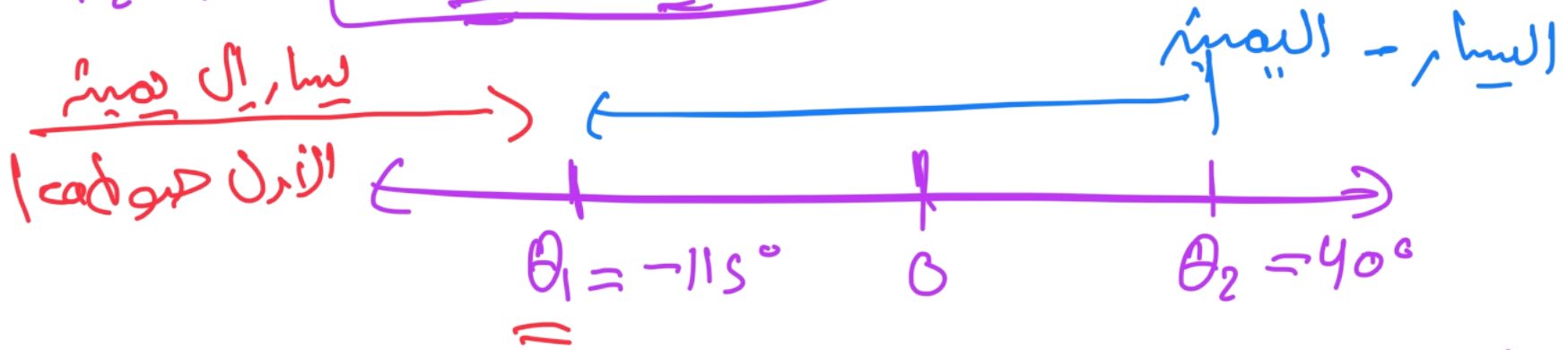
[1] انہ ٹکون موجیہ

[2] انہ ٹکون کلتاھا  $\sin$  او  $\cos$

[3] انہ ٹکون نفسی  $\omega$

$$i_1(t) = 4 \cos(377t + 115^\circ) \rightarrow \theta_1 = -115^\circ$$

$$i_2(t) = 5 \cos(377t - 40^\circ) \rightarrow \theta_2 = +40^\circ$$



$i_1$  lead  $i_2$  by  $40 - (-115) = 155^\circ$

## Example 7

Find the phase angle between  $v_1 = -10 \cos(\omega t + 50^\circ)$  and  $v_2 = 12 \sin(\omega t - 10^\circ)$ .  
State which sinusoid is leading.

### Solution:

$$v_1 = -10 \cos(\omega t + 50^\circ) = 10 \cos(\omega t + 50^\circ - 180^\circ)$$

$$v_1 = 10 \cos(\omega t - 130^\circ) \quad \text{or} \quad v_1 = 10 \cos(\omega t + 230^\circ)$$

and

$$v_2 = 12 \sin(\omega t - 10^\circ) = 12 \cos(\omega t - 10^\circ - 90^\circ)$$

$$v_2 = 12 \cos(\omega t - 100^\circ)$$

$$\begin{aligned}\sin(\omega t \pm 180^\circ) &= -\sin \omega t \\ \cos(\omega t \pm 180^\circ) &= -\cos \omega t \\ \sin(\omega t \pm 90^\circ) &= \pm \cos \omega t \\ \cos(\omega t \pm 90^\circ) &= \mp \sin \omega t\end{aligned}$$



$$v_2 = 12 \cos(\omega t - 100 + 360)$$

$$v_2 = 12 \cos(\omega t + 260)$$

$v_2$  leads  $v_1$  by  $30^\circ$

$$V_1 = -10 \cos(\omega t + 50) \rightarrow 10 \sin(\omega t + 50 - 90)$$

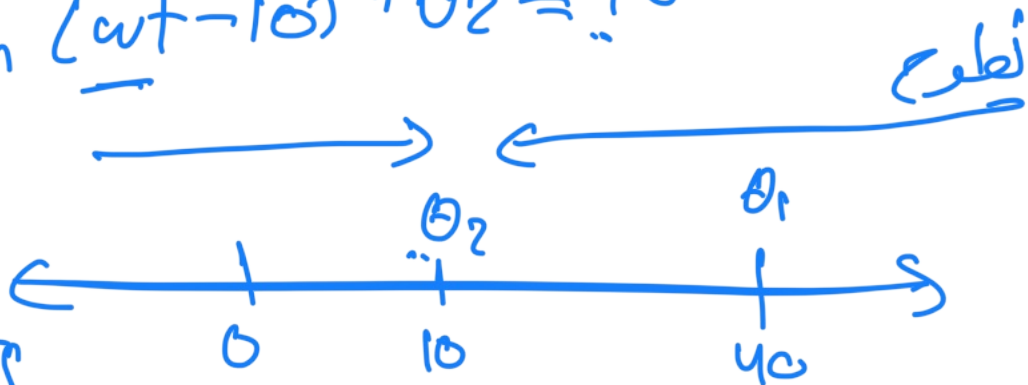
$$V_2 = +12 \underline{\underline{\sin}}(\omega t - 10)$$

$$\Rightarrow V_1 = +10 \underline{\underline{\sin}}(\omega t - 40), \theta_1 = 40$$

$$V_2 = +12 \underline{\underline{\sin}}(\omega t - 10), \theta_2 = 10$$

$V_2$  lead  $V_1$

$$\text{by } 40 - 10 = \boxed{30}$$



## Example 8

Find the phase angle between  $v_1 = -10 \cos(\omega t + 50^\circ)$  and  $v_2 = 12 \sin(\omega t - 10^\circ)$ .  
State which sinusoid is leading.

### Another Solution:

$$v_1 = -10 \cos(\omega t + 50^\circ) = 10 \sin(\omega t + 50^\circ - 90^\circ)$$

$$= 10 \sin(\omega t - 40^\circ)$$

$$v_2 = 12 \sin(\omega t - 10^\circ)$$



$$\sin(\omega t \pm 180^\circ) = -\sin \omega t$$

$$\cos(\omega t \pm 180^\circ) = -\cos \omega t$$

$$\sin(\omega t \pm 90^\circ) = \pm \cos \omega t$$

$$\cos(\omega t \pm 90^\circ) = \mp \sin \omega t$$

$v_2$  leads  $v_1$  by  $30^\circ$



# Example 9

R

Let us consider the behavior of an Ironing Machine (المكواة) as a pure resistive load of 1kW power supplied by a single phase AC voltage of (220V, 50Hz) for domestic application.



- a- Find R
- b- Find  $i(t)$

The supplied voltage can be represented mathematically as:

$$v(t) = V_{max} \sin(\omega t)$$

Since its rms value is 220V then its maximum value ( $V_{max}$ ) is:

$$V_{rms} = \frac{V_{max}}{\sqrt{2}}$$

$$V_{max} = 220 \times \sqrt{2} = 311.127V$$

Then

$$v(t) = 311.127 \sin(\omega t)$$

Since,

$$P = \frac{(V_{rms})^2}{R}$$

$$R = \frac{(V_{rms})^2}{P} = \frac{(220)^2}{1000} = 48.4\Omega$$

Then

$$I_{rms} = \frac{V_{rms}}{R} = \frac{220}{48.4} = 4.546A$$

The time domain function of the current  $i(t)$  is already known as:

$$\rightarrow i(t) = I_{max} \sin(\omega t) = \sqrt{2} I_{rms} \sin(\omega t) = 6.429 \sin(\omega t)$$

(220V, 50Hz)

↙  
rms value

$$v(t) = \underline{V_m} \sin(\omega t)$$

$$\underline{P} = 1000 \text{ W}$$

$V_m > V_{rms}$

$$\begin{aligned} V_m &= \sqrt{2} \times V_{rms} \\ &= \sqrt{2} \times 220 \\ &= 311,127 \end{aligned}$$

$$v(t) = 311,127 \sin(314,158 t)$$

$$P = \frac{V_{rms}^2}{R}$$

AC source → rms

$$R = \frac{V_{rms}^2}{P} = \frac{220^2}{1000} = \boxed{48,4 \Omega}$$

$$V \in \mathbb{R} \rightarrow \underline{V}(t) = \frac{U}{R}$$

$$\underline{I}(t) = \frac{311,127}{48,4} \sin(314,16t)$$

$$\underline{I}(t) = 6,429 \sin(314,16t)$$

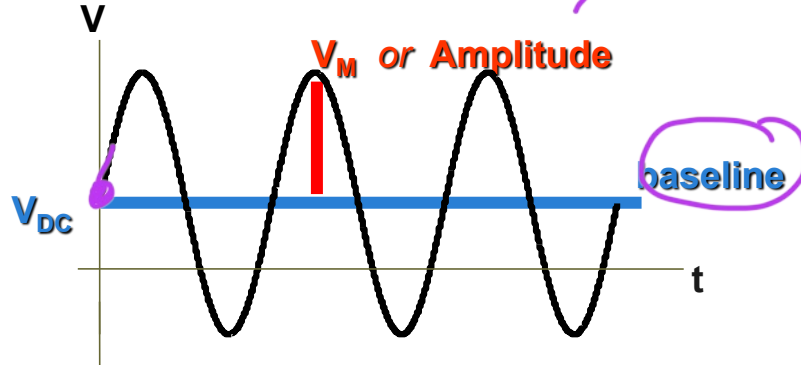
# SUPERIMPOSED DC & AC

- A circuit can have both a DC voltage source and an AC
- We say that the “AC rides on the DC”
- The graph of the voltage is displaced vertically from 0, to the DC voltage level. Algebraically:

$$v(t) = V_{dc} + V_M \sin(2\pi ft \pm \theta)$$

$$v(\alpha) = V_{dc} + V_M \sin(\alpha \pm \theta)$$

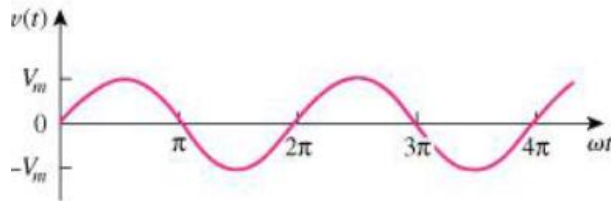
$$\alpha = 2\pi ft$$



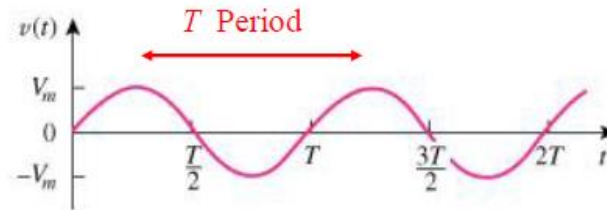
# AC Circuits and AC Analysis

- **A Sinusoid** is a signal that has the form of **sine** or **cosine** function
- The **sinusoidal** current is referred to as **Alternating Current (AC)**
- **AC** circuits are energized with **AC independent sources** (current or voltage)

➤ Sketch of  $V_m \sin \omega t$ .



(a) As a function of  $\omega t$ .



(b) As a function of  $t$ .

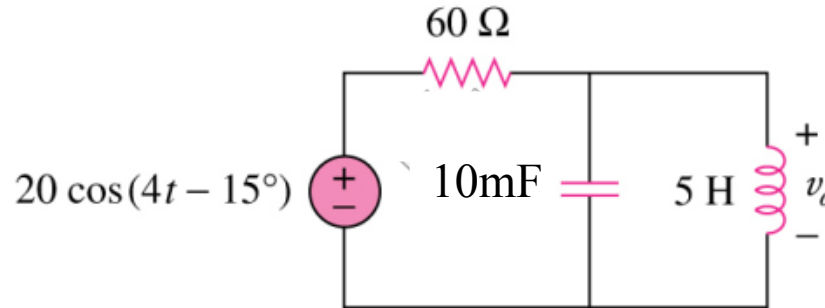
- $V_m$  is the **AMPLITUDE** of the sinusoid.
- $\omega$  is the **ANGULAR FREQUENCY** in radians/s.

$$\omega = 2\pi f \quad \text{and} \quad f = \frac{1}{T}$$

- $f$  is the **FREQUENCY** in Hertz.
- $T$  is the **period** in seconds.

# AC Circuits and AC Analysis

- **Solving AC circuits** in time domain involves solving **differential equations**.
- Example, for the given circuit below, what is  $V_o(t)$ ?



- Writing KCL at  $V_o$  node results in: 
$$\frac{d^2 v_o}{dt^2} + \frac{5}{3} \frac{dv_o}{dt} + 20v_o = -\frac{400}{3} \sin(4t - 15^\circ)$$

- **However**, forming and solving the DE in time domain are sometimes very tedious.
- Therefore, **AC circuits** analysis is done in **Phasor (frequency) domain**.





## 1-(b) Phasor

# 1-(b) Phasors

- A **phasor** is a **complex number** that represents the amplitude and phase of a sinusoid (**Polar Form**).
- Phasor is the mathematical equivalent of a sinusoid with **time variable dropped**.
- Phasor representation is based on **Euler's identity**.

$$e^{\pm j\phi} = \cos\phi \pm j\sin\phi \quad \text{Euler's Identity}$$

$$\cos\phi = \operatorname{Re}\{e^{j\phi}\} \quad \text{Real part}$$

$$\sin\phi = \operatorname{Im}\{e^{j\phi}\} \quad \text{Imaginary part}$$

- Given a sinusoid  $v(t) = V_m \cos(\omega t + \phi)$ .

$$v(t) = V_m \cos(\omega t + \phi) = \operatorname{Re}(V_m e^{j(\omega t + \phi)}) = \operatorname{Re}(V_m e^{j\phi} e^{j\omega t}) = \operatorname{Re}(\mathbf{V} e^{j\omega t})$$

$$\mathbf{V} = V_m e^{j\phi} = V_m \angle \phi = \text{PHASOR REP.}$$

$$v(t) = V_m \cos(\omega t + \phi) \Leftrightarrow \mathbf{V} = V_m \angle \phi$$

(Time Domain Re pr.)      (Phasor Domain Re presentation)

$$v(t) = \operatorname{Re}\{\mathbf{V} e^{j\omega t}\} \quad (\text{Converting Phasor back to time})$$



# Complex Numbers and Mathematical Foundation of Phasor

---

# Complex Numbers

➤ A complex number may be written in RECTANGULAR FORM as:

## RECTANGULAR FORM

$$z = x + jy \quad j = \sqrt{-1}, \quad x = \text{Re}(z), \quad y = \text{Im}(z)$$

➤ A second way of representing the complex number is by specifying the MAGNITUDE and  $r$  and the ANGLE  $\theta$  in POLAR form.

## POLAR FORM

$$z = x + jy = |z| \angle \phi = r \angle \phi$$

➤ The third way of representing the complex number is the EXPONENTIAL form.

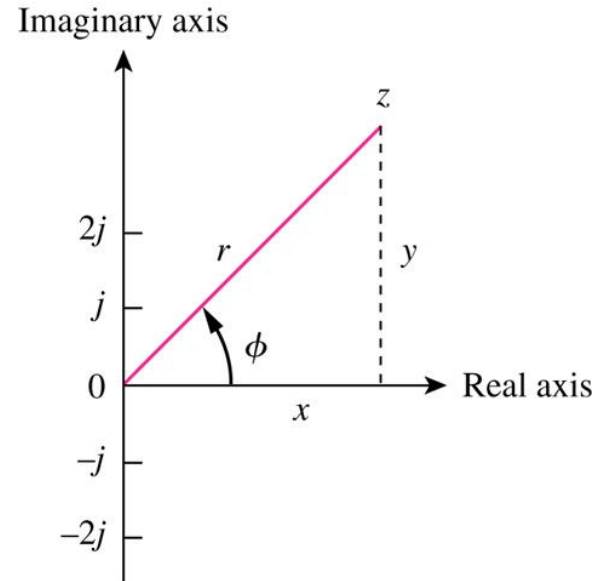
## EXPONENTIAL FORM

$$z = x + jy = |z| \angle \phi = re^{j\phi}$$

$$re^{j\phi} = r\cos\phi + jr\sin\phi \quad \text{Euler's Identity}$$

$$r\cos\phi = \text{Re}\{re^{j\phi}\} \quad \text{Real part}$$

$$r\sin\phi = \text{Im}\{re^{j\phi}\} \quad \text{Imaginary part}$$



- $x$  is the REAL part.
- $y$  is the IMAGINARY part.
- $r$  is the MAGNITUDE.
- $\phi$  is the ANGLE.

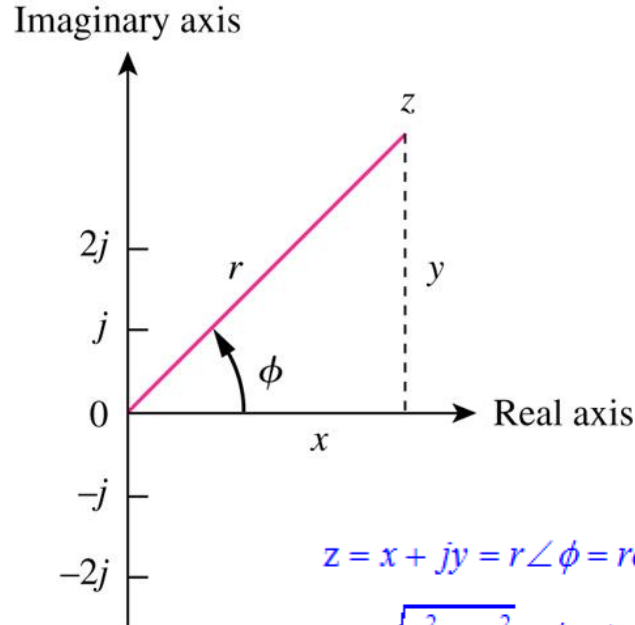
# Complex Number Conversions

- We need to convert COMPLEX numbers from one form to the other form.

$$z = x + jy = r \angle \phi = re^{j\phi} = r(\cos \phi + j \sin \phi)$$

## EXPONENTIAL FORM

$$z = x + jy = |z| \angle \phi = re^{j\phi}$$



$$z = x + jy = r \angle \phi = re^{j\phi} = r(\cos \phi + j \sin \phi)$$

$$r = \sqrt{x^2 + y^2}, \quad \phi = \tan^{-1} \frac{y}{x} \quad \text{Rectangular to Polar}$$

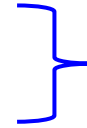
$$x = r \cos \phi, \quad y = r \sin \phi \quad \text{Polar to Rectangular}$$

# Mathematical Operations of Complex Numbers

- Mathematical operations on complex numbers may require conversions from one form to other form.

**ADDITION:**  $z_1 + z_2 = (x_1 + x_2) + j(y_1 + y_2)$

**SUBTRACTION:**  $z_1 - z_2 = (x_1 - x_2) + j(y_1 - y_2)$



Better performed in  
Rectangular form

**MULTIPLICATION:**  $z_1 z_2 = r_1 r_2 \angle \phi_1 + \phi_2$

**DIVISION:**  $\frac{z_1}{z_2} = \frac{r_1}{r_2} \angle \phi_1 - \phi_2$

**RECIPROCAL:**  $\frac{1}{z} = \frac{1}{r} \angle -\phi$

**SQUARE ROOT:**  $\sqrt{z} = \sqrt{r} \angle \frac{\phi}{2}$



Better performed  
in Polar form

**COMPLEX CONJUGATE:**  $z^* = x - jy = r \angle -\phi = r e^{-j\phi}$

# Complex Numbers

## ✓ Example 1:

Evaluate  $[(5 + j2)(-1 + j4) - 5\angle 60^\circ]^*$  and  $\frac{10 + j5 + 3\angle 40^\circ}{-3 + j4} + 10\angle 30^\circ$

**Solution:**

(a)  $(5 + j2)(-1 + j4) = -5 + j20 - j2 - 8 = -13 + j18$

$$5\angle 60^\circ = 2.5 + j4.33$$

$$(5 + j2)(-1 + j4) - 5\angle 60^\circ = -15.5 + j13.67$$

$$[(5 + j2)(-1 + j4) - 5\angle 60^\circ]^* = \underline{\underline{-15.5 - j13.67}} = \underline{\underline{20.67\angle 221.41^\circ}}$$

(b)  $3\angle 40^\circ = 2.298 + j1.928$

$$10 + j5 + 3\angle 40^\circ = 12.298 + j6.928 = 14.115\angle 29.39^\circ$$

$$-3 + j4 = 5\angle 126.87^\circ$$

$$\frac{10 + j5 + 3\angle 40^\circ}{-3 + j4} = \frac{14.115\angle 29.39^\circ}{5\angle 126.87^\circ} = 2.823\angle -97.48^\circ$$

$$2.823\angle -97.48^\circ = -0.3675 - j2.8$$

$$10\angle 30^\circ = 8.66 + j5$$

$$\frac{10 + j5 + 3\angle 40^\circ}{-3 + j4} + 10\angle 30^\circ = \underline{\underline{8.293 + j2.2}}$$

# Complex Numbers

✓ Example 2:

$$(4\angle 50^\circ)(2\angle -20^\circ) = 4 \cdot 2 \angle (50^\circ + (-20^\circ)) = 8\angle 30^\circ$$

✓ Example 3:

$$\frac{4\angle 50^\circ}{2\angle -20^\circ} = \frac{4}{2} \angle (50^\circ - (-20^\circ)) = 2\angle 70^\circ$$



# Back to Phasor



---

Sinusoids and Phasor

Circuit elements in Phasor domain (frequency domain)

Impedance and admittance

# Phasors

- A **phasor** is a **complex number** that represents the amplitude and phase of a sinusoid (**Polar Form**).
- Phasor is the mathematical equivalent of a sinusoid with **time variable dropped**.
- Given a sinusoid  $v(t) = V_m \cos(\omega t + \phi)$ .

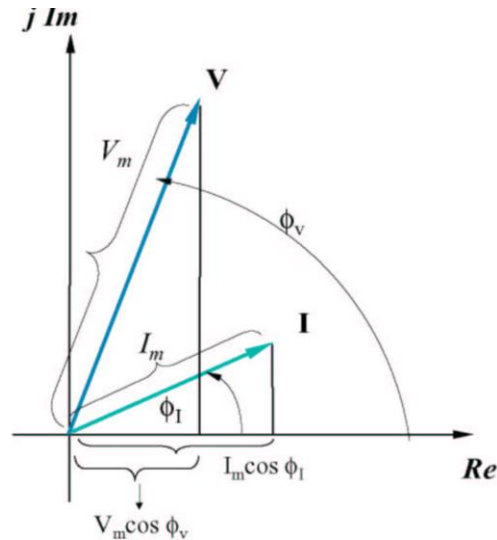
$$v(t) = V_m \cos(\omega t + \phi) \xleftrightarrow{\omega} \mathbf{V} = V_m \angle \phi$$

(Time Domain Repr.)

(Phasor Domain Representation)

# Phasor Diagrams

- Amplitude and phase difference are two principal concerns in the study of voltage and current sinusoids.
- Phasor can be defined using either sine or cosine functions.
- By convention, source of the circuit is used as reference (zero phase angle).
- If not stated, cosine function is used as reference and any voltage or current expression is in the form of a sine is changed to a cosine:



Time Domain Representation

$$V_m \cos(\omega t + \phi)$$

$$V_m \sin(\omega t + \phi)$$

$$I_m \cos(\omega t + \theta)$$

$$I_m \sin(\omega t + \theta)$$

Phasor Domain Representation

$$V_m \angle \phi$$

$$V_m \angle \phi - 90^\circ$$

$$I_m \angle \theta$$

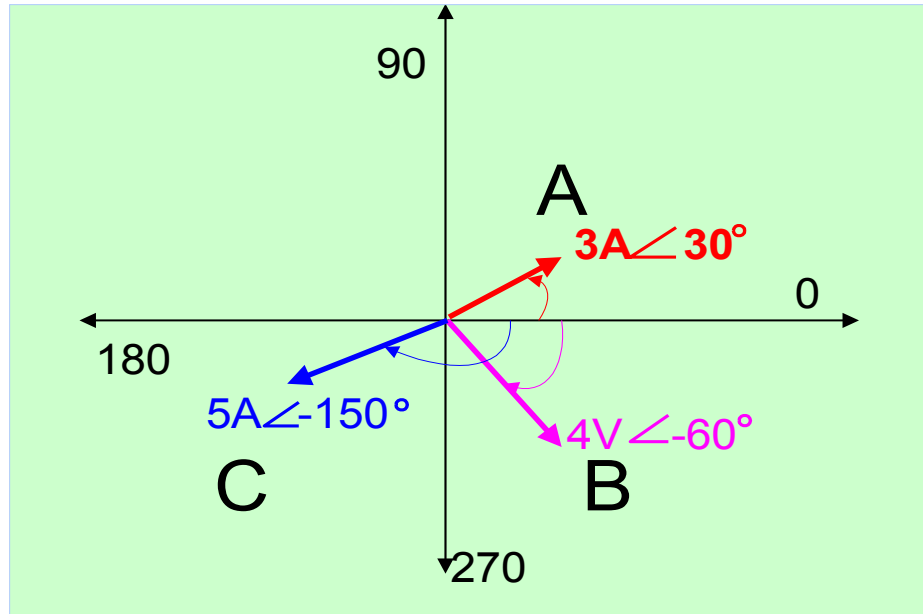
$$I_m \angle \theta - 90^\circ$$

# Phasor Diagrams



## ✓ Graphing phasors

- Positive phase angles are drawn counterclockwise from the axis;
- Negative phase angles are drawn clockwise from the axis.



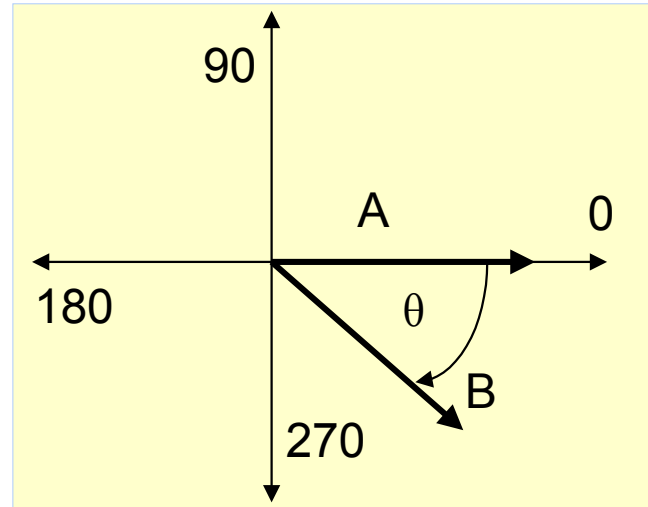
Note:  
A leads B  
B leads C  
C lags A  
etc.

# Phasor Diagrams



## ✓ PHASOR DIAGRAM

- Represents one or more sine waves (of the same frequency) and the relationship between them.
- The arrows A and B rotate together. A leads B or B lags A.



# Example 11

Transform the following sinusoids to phasors:

$$i = 6\cos(50t - 40^\circ) \text{ A}$$

$$v = -4\sin(30t + 50^\circ) \text{ V}$$

## Solution:

a.  $I = 6\angle -40^\circ \text{ A}$

b. Since  $-\sin(A) = \cos(A+90^\circ)$ ;

$$v(t) = 4\cos(30t+50^\circ+90^\circ) = 4\cos(30t+140^\circ) \text{ V}$$

Transform to phasor  $\Rightarrow V = 4\angle 140^\circ \text{ V}$



$$\sin(\omega t \pm 180^\circ) = -\sin \omega t$$

$$\cos(\omega t \pm 180^\circ) = -\cos \omega t$$

$$\sin(\omega t \pm 90^\circ) = \pm \cos \omega t$$

$$\cos(\omega t \pm 90^\circ) = \mp \sin \omega t$$

# Time Domain Versus Phasor Domain

## The differences between $v(t)$ and $V$ :

- $v(t)$  is instantaneous or time-domain representation  
 $V$  is the frequency or phasor-domain representation.
- $v(t)$  is time dependent,  $V$  is not.
- $v(t)$  is always real with no complex term,  $V$  is generally complex.



Note: Phasor analysis applies only when frequency is constant; when it is applied to two or more sinusoid signals only if they have the same frequency.

# Differentiation and Integration in Phasor Domain

- Differentiating a sinusoid is equivalent to multiplying its corresponding phasor by  $j\omega$ .

$$v(t) = V_m \cos(\omega t + \theta) = \text{Re}[V e^{j\omega t}]$$
$$\frac{dv(t)}{dt} = -\omega V_m \sin(\omega t + \theta) = \omega V_m \cos(\omega t + \theta + 90^\circ)$$

which transforms to the phasor

$$\frac{dv(t)}{dt} = \omega V_m e^{j(\theta + 90^\circ)} = \omega V_m \angle \phi + 90^\circ$$
$$\frac{dv(t)}{dt} = \omega e^{j90^\circ} V_m e^{j\theta}$$

$$\frac{dv}{dt} \Leftrightarrow J\omega V$$

$$\begin{aligned}\sin(\omega t \pm 180^\circ) &= -\sin \omega t \\ \cos(\omega t \pm 180^\circ) &= -\cos \omega t \\ \sin(\omega t \pm 90^\circ) &= \pm \cos \omega t \\ \cos(\omega t \pm 90^\circ) &= \mp \sin \omega t\end{aligned}$$



$$e^{\pm j\phi} = \cos \phi \pm j \sin \phi$$

- Integrating a sinusoid is equivalent to dividing its corresponding phasor by  $j\omega$ .

# Differentiation and Integration in Phasor Domain



- Relationship between differential, integral operation in phasor listed as follow:

(Time Domain)		(Phasor Domain)
$v(t) = V_m \cos(\omega t + \phi)$	$\Leftrightarrow$	$\mathbf{V} = V_m \angle \phi$
$v(t) = V_m \sin(\omega t + \phi)$	$\Leftrightarrow$	$\mathbf{V} = V_m \angle \phi - 90^\circ$
$\frac{dv}{dt}$	$\Leftrightarrow$	$J\omega \mathbf{V}$
$\int v dt$	$\Leftrightarrow$	$\frac{\mathbf{V}}{J\omega}$

# Example 9.7: Using Phasor to solve integro-differential equations

## Example 9.7

Use phasor approach, determine the current  $i(t)$  in a circuit described by the integro-differential equation.

$$4i + 8 \int idt - 3 \frac{di}{dt} = 50 \cos(2t + 75^\circ)$$

➤ **Solution:**

$$4\mathbf{I} + \frac{8\mathbf{I}}{j\omega} - 3j\omega\mathbf{I} = 50\angle 75^\circ$$

But  $\omega = 2$ , so

$$\mathbf{I}(4 - j4 - j6) = 50\angle 75^\circ$$
$$\mathbf{I} = \frac{50\angle 75^\circ}{4 - j10} = \frac{50\angle 75^\circ}{10.77\angle -68.2^\circ} = 4.642\angle 143.2^\circ \text{ A}$$

Converting this to the time domain,

$$i(t) = 4.642 \cos(2t + 143.2^\circ) \text{ A}$$



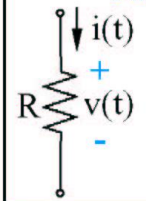
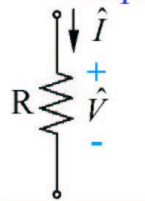
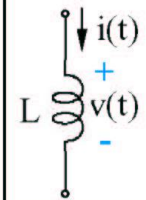

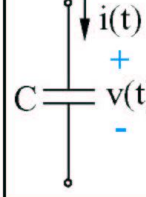
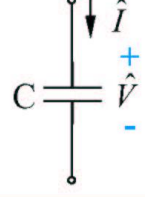
$v(t)$	$\longleftrightarrow$	$V = V\angle\phi$
$\frac{dv}{dt}$	$\longleftrightarrow$	$j\omega V$
$\int v dt$	$\longleftrightarrow$	$\frac{V}{j\omega}$

# Phasor Relationships for Circuit Elements

- Ohm's Law still applies even though the voltage source is AC

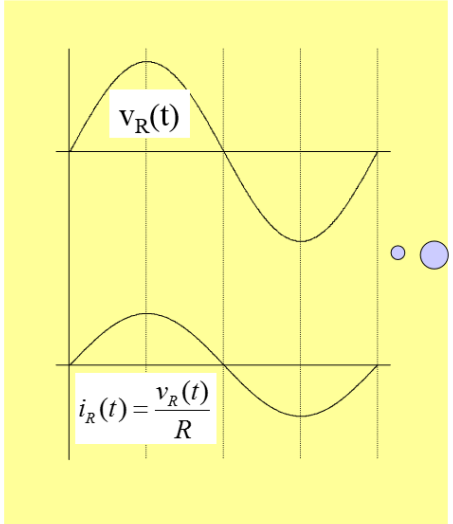
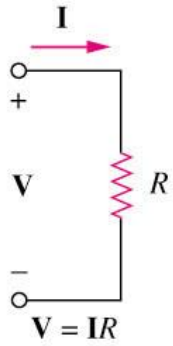
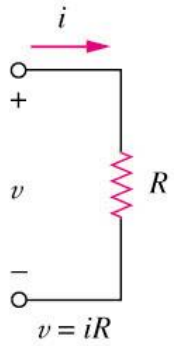
## Terminal Equations

4

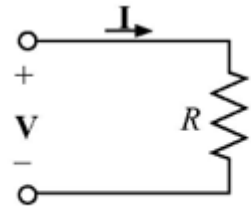
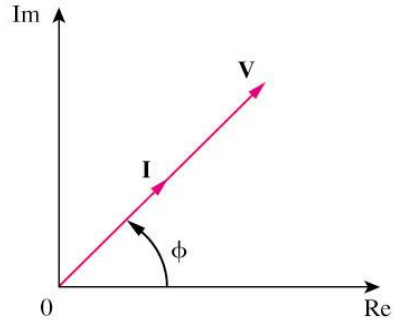
Time Domain	Frequency Domain
 $v(t) = Ri(t)$	 $\begin{aligned}\hat{V} &= R\hat{I} \\ \hat{I} &= G\hat{V}\end{aligned}$
 $v(t) = L \frac{di(t)}{dt}$	 $\begin{aligned}\hat{V} &= j\omega L\hat{I} \\ \hat{I} &= \frac{1}{j\omega L}\hat{V}\end{aligned}$
 $\begin{aligned}i(t) &= C \frac{dv(t)}{dt} \\ v(t) &= \frac{1}{C} \int i(t) dt\end{aligned}$	 $\begin{aligned}\hat{V} &= \frac{1}{j\omega C}\hat{I} \\ \hat{I} &= j\omega C\hat{V}\end{aligned}$

# Phasor Relationships for Circuit Elements

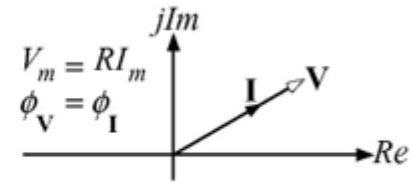
## A- Resistor:



PHASE ANGLE FOR R,  $\theta=0^\circ$



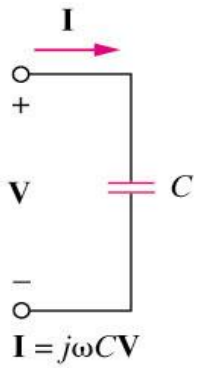
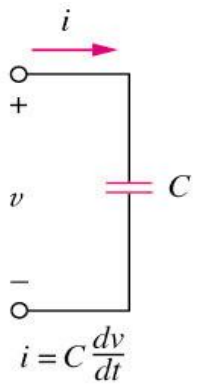
For R, I and V are in phase



(a)

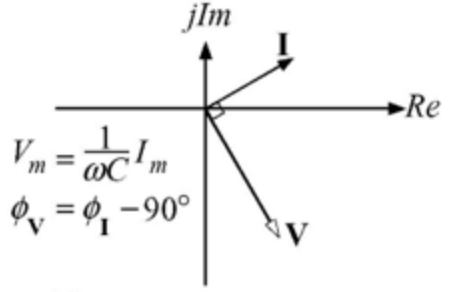
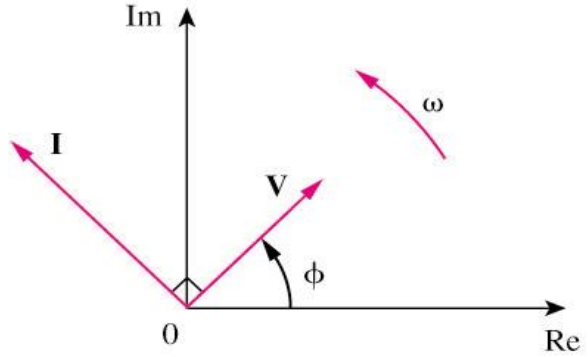
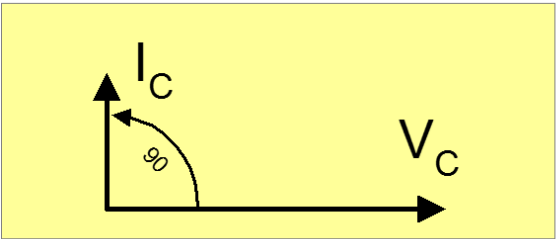
# Phasor Relationships for Circuit Elements

## B- Capacitor:



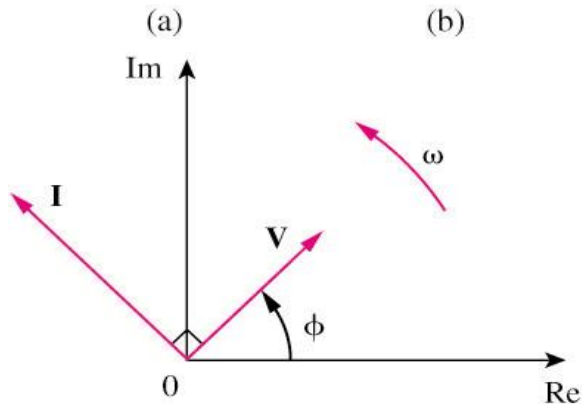
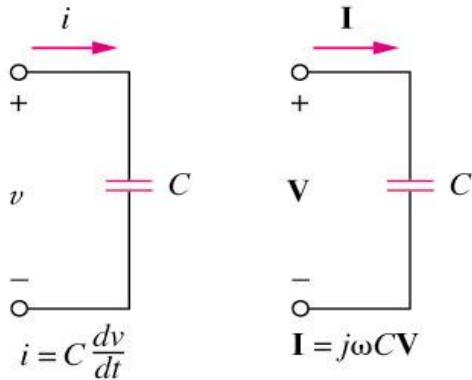
❖ In the Capacitor (C), Voltage **LAGS** charging current by 90° or Charging Current (I) **LEADS** Voltage (E) by 90°

❖ I. C. E.



# Phasor Relationships for Circuit Elements

## B- Capacitor:



## ❖ CAPACITIVE REACTANCE

- ❖ In resistor, the Ohm's Law is  $V=IR$ , where  $R$  is the opposition to current.
- ❖ We will define **Capacitive Reactance**,  $X_C$ , as the opposition to current in a capacitor.

$$V = I X_C$$

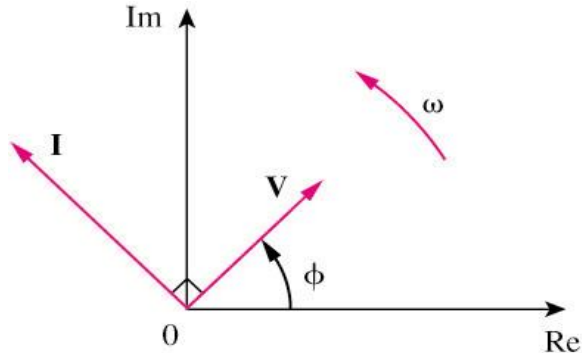
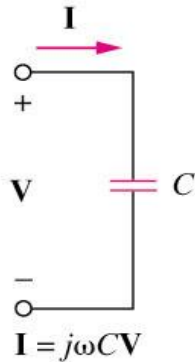
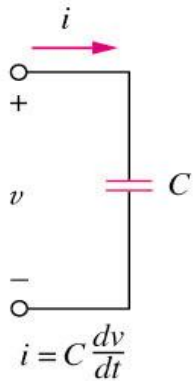
- ❖  $X_C$  will have units of **Ohms**.
- ❖ Note inverse proportionality to  $f$  and  $C$ .

$$X_C = \frac{1}{2\pi fC} = \frac{1}{\omega C}$$

Magnitude of  $X_C$

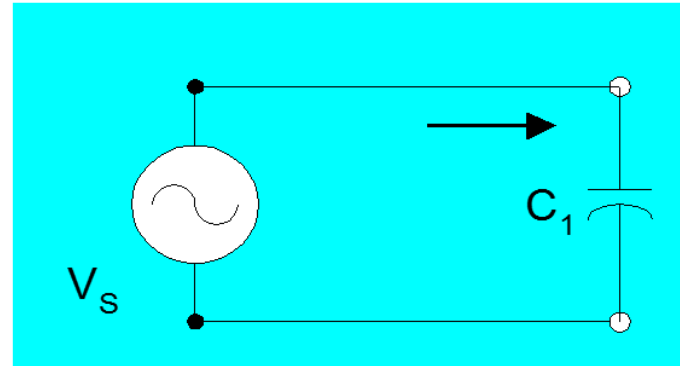
# Phasor Relationships for Circuit Elements

## B- Capacitor:



## ❖ CAPACITIVE REACTANCE

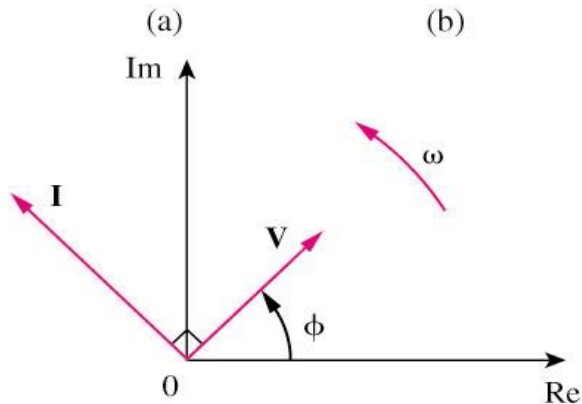
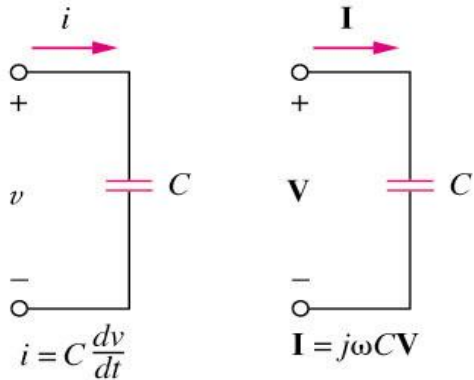
Ex:  $f = 500 \text{ Hz}$ ,  $C = 50 \mu\text{F}$ ,  $X_C = ?$



$$X_C = \frac{1}{2\pi f C} = \frac{1}{2\pi(500 \text{ Hz})50 \mu\text{F}} = 6.4 \Omega$$

# Phasor Relationships for Circuit Elements

## B- Capacitor:



## ❖ PHASE ANGLE FOR $X_C$

- ❖ Capacitive reactance also has a **phase angle** associated with it.

$$X_C = \frac{V}{I}$$

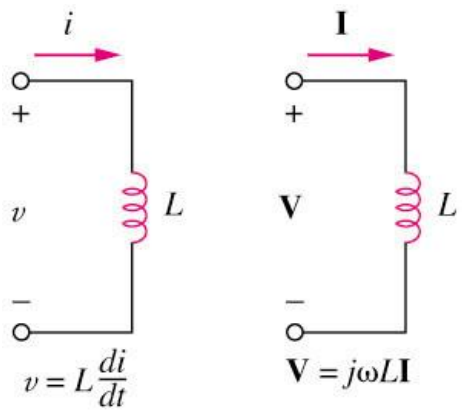
$$X_C = \frac{V \angle 0^\circ}{I \angle 90^\circ} = Z \angle -90^\circ$$

- ❖ The phase angle for Capacitive Reactance ( $X_C$ ) will always =  **$-90^\circ$**
- ❖  $X_C$  may be expressed in POLAR or RECTANGULAR form.

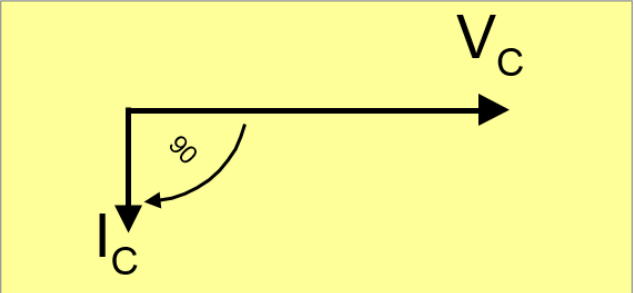
$$X_C \angle -90^\circ \quad \text{or} \quad -jX_C$$

# Phasor Relationships for Circuit Elements

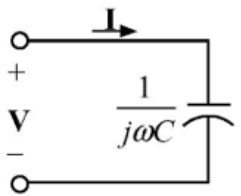
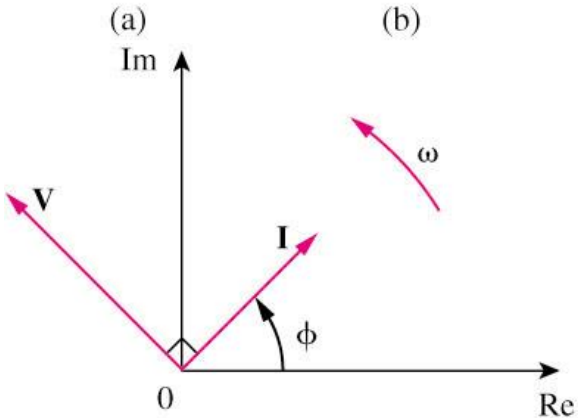
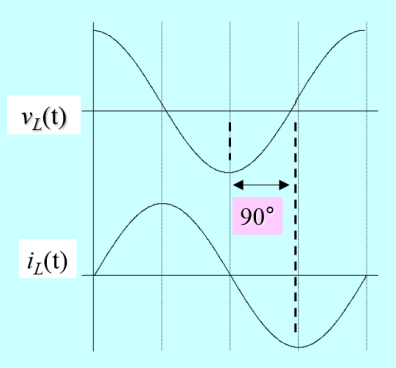
## C-Inductor:



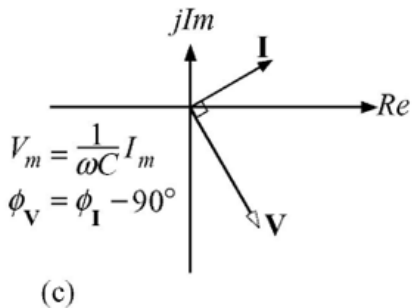
- ❖ In the Inductor (L), Induced Voltage **LEADS** current by  $90^\circ$  or Current (I) **LAGS** Induced Voltage (E) by  $90^\circ$ .



## Graph $v_L(t)$ and $i_L(t)$

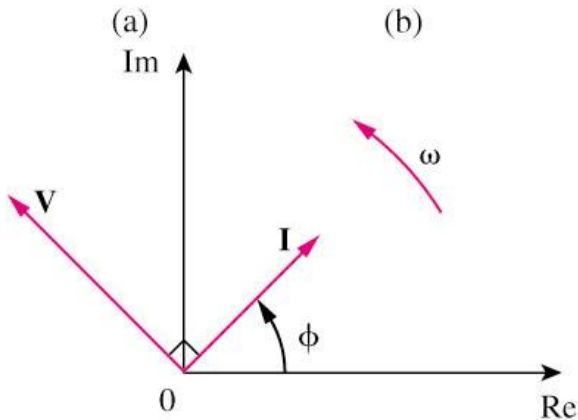
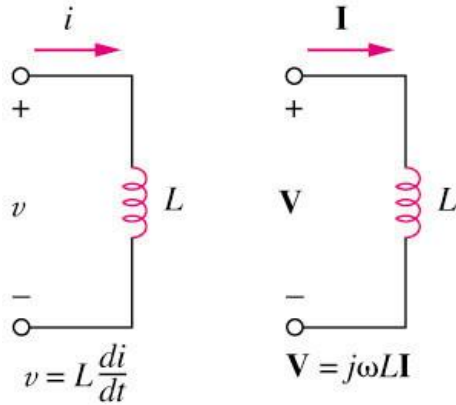


For C, I Leads V by  $90^\circ$



# Phasor Relationships for Circuit Elements

## C-Inductor:



## ❖ INDUCTIVE REACTANCE

- ❖ We will define **Inductive Reactance**,  $X_L$ , as the opposition to current in an inductor.

$$V = I X_L$$

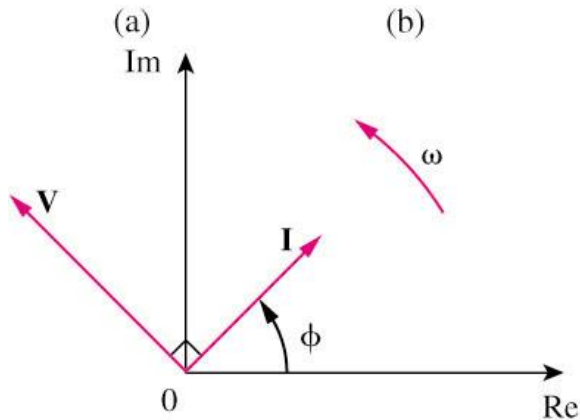
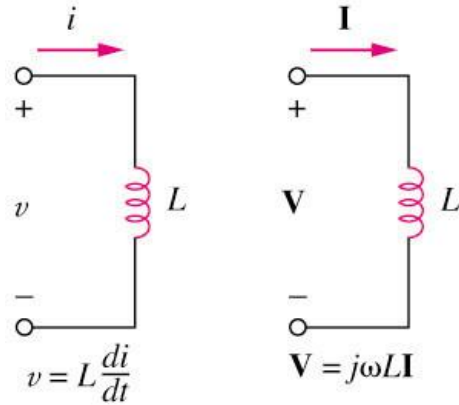
- ❖  $X_L$  will have units of Ohms ( $\Omega$ ).
- ❖ Note direct proportionality to  $f$  and  $L$ .

$$X_L = 2\pi fL = \omega L$$

Magnitude of  $X_L$

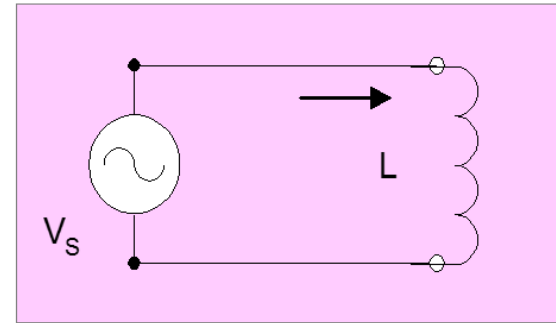
# Phasor Relationships for Circuit Elements

## C-Inductor:



## ❖ INDUCTIVE REACTANCE

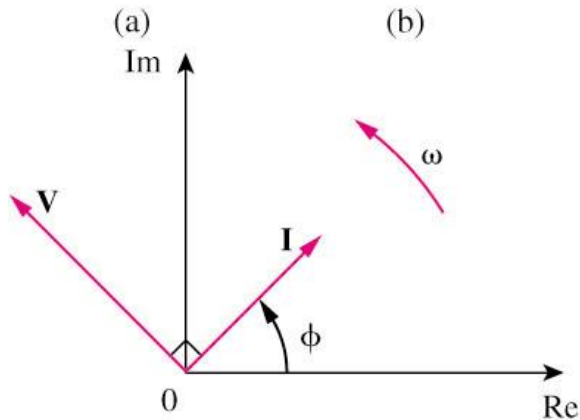
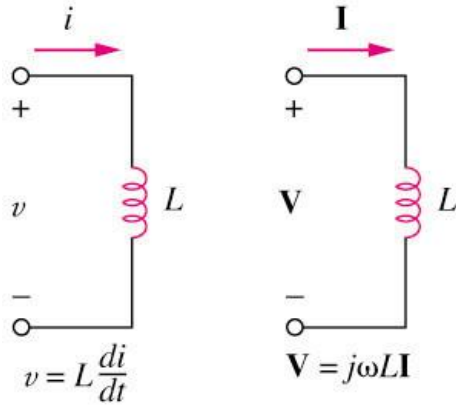
$$f = 500 \text{ Hz}, C = 500 \text{ mH}, X_L = ?$$



$$X_L = 2\pi fL = 2\pi(500)(.5) = 1.57k\Omega$$

# Phasor Relationships for Circuit Elements

## C-Inductor:



## ❖ PHASE ANGLE FOR $X_L$

❖ If  $\underline{V}$  is our reference wave:

$$\mathbf{X}_L = \frac{V \angle 0^\circ}{I \angle -90^\circ} = Z \angle +90^\circ$$

- ❖ The phase angle for Inductive Reactance ( $\mathbf{X}_L$ ) will always =  $+90^\circ$
- ❖  $\mathbf{X}_L$  may be expressed in POLAR or RECTANGULAR form.

$$X_L \angle 90^\circ \quad \text{or} \quad jX_L$$

# Phasor Relationships for Circuit Elements



## ✓ COMPARISON OF $X_L$ & $X_C$

- ❖  $X_L$  is directly proportional to frequency and inductance.

$$X_L = 2\pi fL = \omega L$$

- ❖  $X_C$  is inversely proportional to frequency and capacitance.

$$X_C = \frac{1}{2\pi fC} = \frac{1}{\omega C}$$

# Phasor Relationships for Circuit Elements

## ❖ Frequency effects

- ❖ Using the reactances of an inductor and a capacitor you can show the effects of low and high frequencies on them.



- ❖ At low frequencies ( $f=0$ ):
  - an inductor acts like a **short circuit**.
  - a capacitor acts like an **open circuit**.
- ❖ At high frequencies ( $f=\infty$ ):
  - an inductor acts like an **open circuit**.
  - a capacitor acts like a **short circuit**.

$$X_C = \frac{1}{2\pi fC} = \frac{1}{\omega C}$$

$$X_L = 2\pi fL = \omega L$$

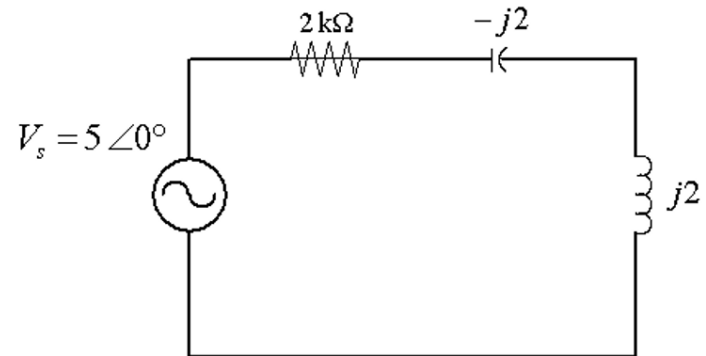
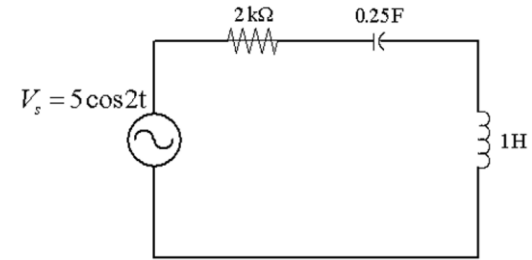
# Example

Represent the below circuit in frequency domain:

Solution:

❖  $\omega = 2$  rad/s:

Time domain	Freq domain
$R = 2 \Omega$	$R = 2 \Omega$
$C = 0.25 \text{ F}$	$X_C = -j(1/\omega C) = -j2 \Omega$
$L = 1 \text{ H}$	$X_L = j\omega L = j2 \Omega$
$V_s = 5 \cos 2t$	$V_s = 5 \angle 0^\circ$



## Example 9.8

---

The voltage  $v = 12 \cos(60t + 45^\circ)$  is applied to a 0.1-H inductor. Find the steady-state current through the inductor.

### Solution:

For the inductor,  $\mathbf{V} = j\omega L\mathbf{I}$ , where  $\omega = 60$  rad/s and  $\mathbf{V} = 12\angle 45^\circ$  V. Hence,

$$\mathbf{I} = \frac{\mathbf{V}}{j\omega L} = \frac{12\angle 45^\circ}{j60 \times 0.1} = \frac{12\angle 45^\circ}{6\angle 90^\circ} = 2\angle -45^\circ \text{ A}$$

Converting this to the time domain,

$$i(t) = 2 \cos(60t - 45^\circ) \text{ A}$$

# Using phasor to add sinusoids- Example 9.6



Given  $i_1(t) = 4 \cos(\omega t + 30^\circ)$  A and  $i_2(t) = 5 \sin(\omega t - 20^\circ)$  A, find their sum.

## Solution:

Here is an important use of phasors—for summing sinusoids of the same frequency. Current  $i_1(t)$  is in the standard form. Its phasor is

$$\mathbf{I}_1 = 4 \angle 30^\circ$$

We need to express  $i_2(t)$  in cosine form. The rule for converting sine to cosine is to subtract  $90^\circ$ . Hence,

$$i_2(t) = 5 \sin(\omega t - 20^\circ) = 5 \cos(\omega t - 20^\circ - 90^\circ) = 5 \cos(\omega t - 110^\circ)$$

and its phasor is

$$\mathbf{I}_2 = 5 \angle -110^\circ$$

If we let  $i = i_1 + i_2$ , then

$$\begin{aligned}\mathbf{I} &= \mathbf{I}_1 + \mathbf{I}_2 = 4 \angle 30^\circ + 5 \angle -110^\circ \\ &= 3.464 + j2 - 1.71 - j4.698 = 1.754 - j2.698 \\ &= 3.218 \angle -56.97^\circ \text{ A}\end{aligned}$$



$$\begin{aligned}\sin(\omega t \pm 180^\circ) &= -\sin \omega t \\ \cos(\omega t \pm 180^\circ) &= -\cos \omega t \\ \sin(\omega t \pm 90^\circ) &= \pm \cos \omega t \\ \cos(\omega t \pm 90^\circ) &= \mp \sin \omega t\end{aligned}$$



---

# Impedance and Admittance

# A-Impedance

□ The impedance Z of a circuit is the ratio of the phasor voltage V to the phasor current I, measured in ohms Ω.

$$Z = \frac{V}{I} = R + jX$$

- Impedance is a complex quantity:
  - R = Real part of Z = Resistance
  - X = Imaginary part of Z = Reactance

□ Impedance in polar form:

$$Z = \frac{V}{I} = R + jX = |Z| \angle \theta \quad |Z| = \sqrt{R^2 + X^2} \quad \theta = \tan^{-1} \frac{X}{R}$$
$$R = |Z| \cos \theta \quad X = |Z| \sin \theta$$

➤ The Reactance may be positive or negative:

- It is Inductive if X is positive.
- It is Capacitive if X is negative.

Impedances of passive elements	
Element	Impedance
<b>R</b>	$Z = R$
<b>L</b>	$Z = j\omega L$
<b>C</b>	$Z = \frac{1}{j\omega C}$

## IMPEDANCES SUMMARY

Impedance	Phasor form:	Rectangular form
$Z_R$	$R \angle 0^\circ$	$R + j0$
$Z_L$	$X_L \angle 90^\circ$	$0 + jX_L$
$Z_C$	$X_C \angle -90^\circ$	$0 - jX_C$

# B- ADMITTANCE



- ✓ The reciprocal of impedance.
- ✓ Symbol is Y.
- ✓ Measured in Siemens (S).

$$Y = \frac{1}{Z} = \frac{I}{V}$$

➤ Admittance is a complex quantity:

$$Y = G \pm jB$$

- G = Real part of Y : Conductance
- B = Imaginary part of Y : Susceptance



## Z AND Y OF PASSIVE ELEMENTS

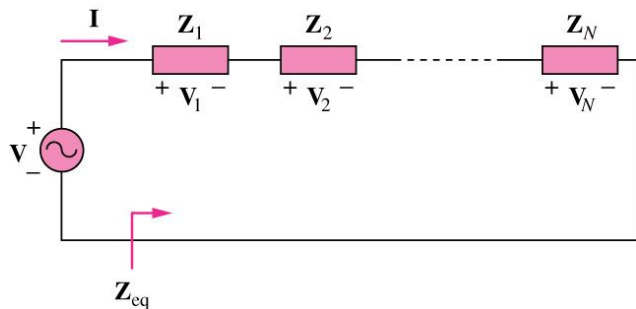
ELEMENT	IMPEDANCE	ADMITTANCE
R	$Z = R$	$Y = \frac{1}{R}$
L	$Z = j\omega L$	$Y = \frac{1}{j\omega L}$
C	$Z = -j\frac{1}{\omega C}$	$Y = j\omega C$



# C-TOTAL IMPEDANCE FOR AC CIRCUITS

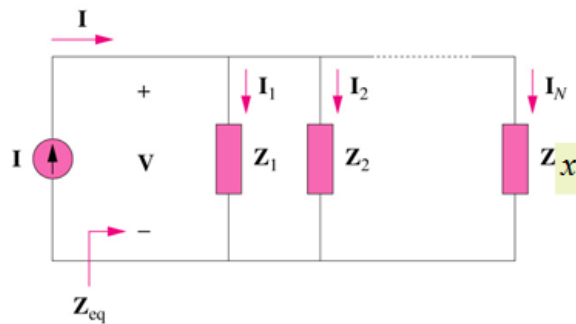
- To compute total circuit impedance in AC circuits, use the same techniques as in DC.
- The **only difference** is that instead of using resistors, you now have to use **complex impedance,  $Z$** .

## ❖ For series connected impedances:



$$Z_{eq} = \frac{V}{I} = Z_1 + Z_2 + \dots + Z_N \quad (\text{Equivalent Impedance})$$

## ❖ Total impedance for parallel circuit:



- The impedance can be easily computed from the admittance:

$$\frac{1}{Z_{total}} = \sum \frac{1}{Z_x} = \frac{1}{Z_1} + \frac{1}{Z_2} + \dots + \frac{1}{Z_x} \Rightarrow$$
$$Z_{total} = \left( \sum \frac{1}{Z_x} \right)^{-1} = \left( \frac{1}{Z_1} + \frac{1}{Z_2} + \dots + \frac{1}{Z_x} \right)^{-1}$$

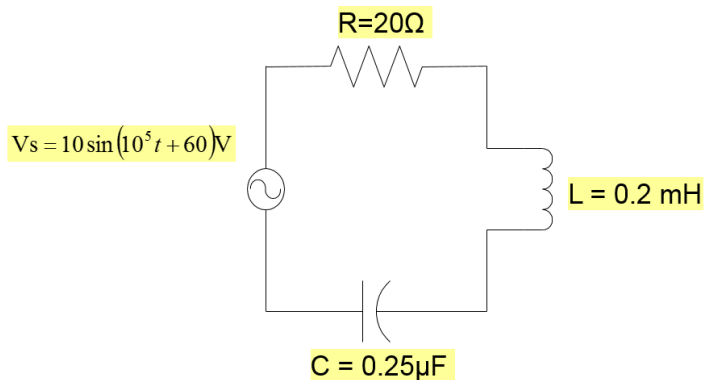
$$Z_{total} = \frac{1}{Y_{total}} = [Y_{total}]^{-1}$$
$$\therefore Y_{total} = (Y_1 + Y_2 + \dots + Y_x)$$



# C-TOTAL IMPEDANCE FOR AC CIRCUITS

## 1-Example of series circuit:

- a- Find Total Impedance
- b- Draw Impedance Triangle (Phasor Diagram).
- c- Find  $i_s$ ,  $v_R$ ,  $v_C$ ,  $v_L$
- d- Find  $v_R$ ,  $v_C$ ,  $v_L$  using Voltage Divider

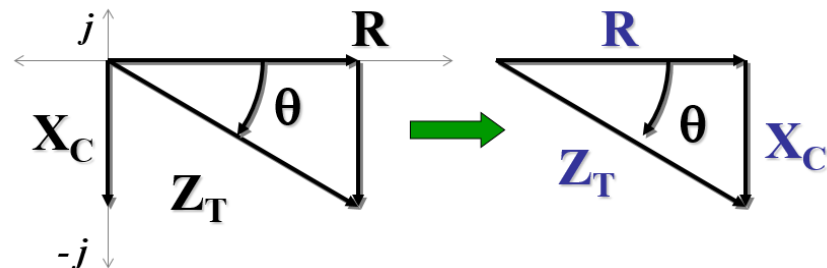


## ✓ Solution

- a- The total Impedance

$$\begin{aligned} Z_T &= \sum Z_R + Z_L + Z_C \\ &= 20 + j20 + (-j40) \\ &= (20 - j20)\Omega \\ &= 28.28 \angle -45^\circ \Omega \end{aligned}$$

- b- The Impedance Triangle (Phasor Diagram)





# C-TOTAL IMPEDANCE FOR AC CIRCUITS

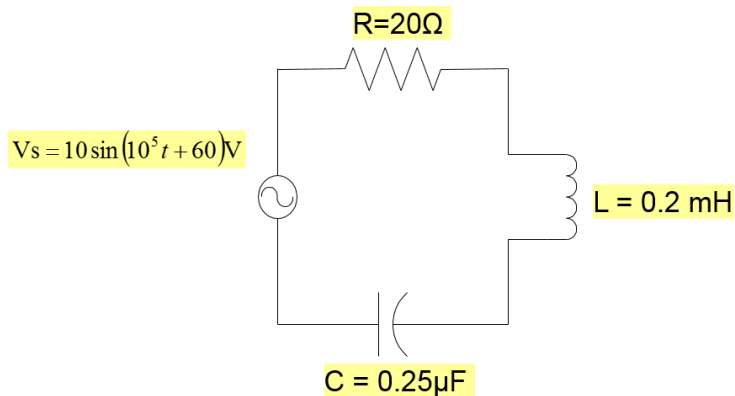
## 1-Example of series circuit:

a- Find Total Impedance

b- Draw Impedance Triangle (Phasor Diagram)

c- Find  $i_s$ ,  $v_R$ ,  $v_C$ ,  $v_L$

d- Find  $v_R$ ,  $v_C$ ,  $v_L$  using Voltage Divider



## ✓ Solution

➤ c-  $i_s$ ,  $v_R$ ,  $v_C$ ,  $v_L$ :

$$i_s = \frac{v_s}{Z_T} = \frac{10 \angle 60^\circ}{28.28 \angle -45^\circ}$$
$$= 353 \angle 105^\circ \text{ mA}$$

$$v_s = i_s \cdot Z_R = (353 \angle 105^\circ \text{ mA}) \cdot (20 \Omega) = 7 \angle 105^\circ \text{ V}$$

$$v_L = i_s \cdot Z_L = (353 \angle 105^\circ \text{ mA}) \cdot (20 \angle 90^\circ \Omega) = 7 \angle 195^\circ \text{ V}$$

$$v_C = i_s \cdot Z_C = (353 \angle 105^\circ \text{ mA}) \cdot (40 \angle -90^\circ \Omega) = 7 \angle 15^\circ \text{ V}$$



# C-TOTAL IMPEDANCE FOR AC CIRCUITS

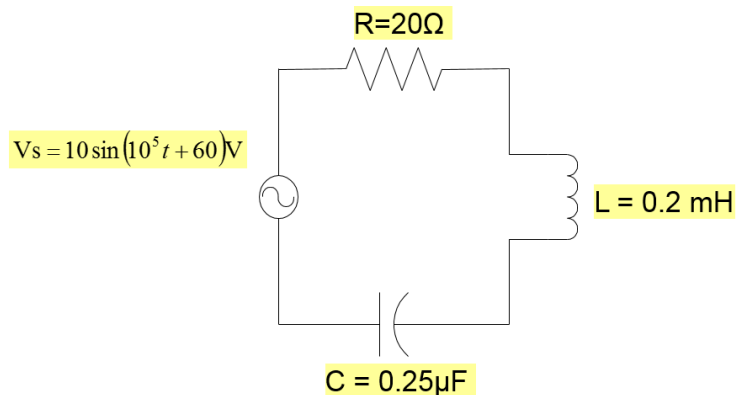
## 1-Example of series circuit:

a- Find Total Impedance

b- Draw Impedance Triangle (Phasor Diagram)

c- Find  $i_s$ ,  $v_R$ ,  $v_C$ ,  $v_L$

d- Find  $v_R$ ,  $v_C$ ,  $v_L$  using Voltage Divider



## ✓ Solution

➤ d- Find  $v_R$ ,  $v_C$ ,  $v_L$  using Voltage Divider

➤ Voltage divider still works, too.

$$v_R = \frac{Z_R}{Z_T} v_s = \frac{(20 \Omega \angle 0^\circ)}{(28.28 \angle -45^\circ)} \cdot 10 \text{ V} \angle 60^\circ = 7 \angle 105^\circ$$
$$v_L = \frac{Z_L}{Z_T} v_s = \frac{(20 \Omega \angle 90^\circ)}{(28.28 \angle -45^\circ)} \cdot 10 \text{ V} \angle 60^\circ = 7 \angle 195^\circ$$
$$v_C = \frac{Z_C}{Z_T} v_s = \frac{(20 \Omega \angle -90^\circ)}{(28.28 \angle -45^\circ)} \cdot 10 \text{ V} \angle 60^\circ = 7 \angle 15^\circ$$



# C-TOTAL IMPEDANCE FOR AC CIRCUITS

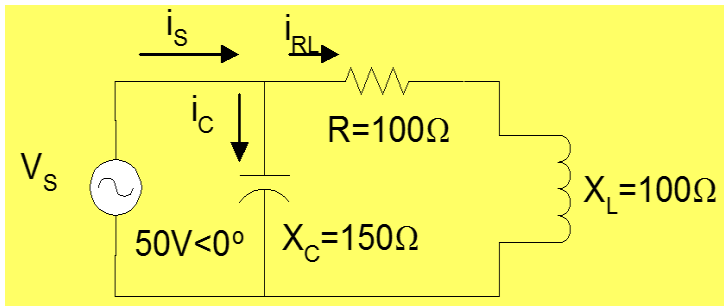
## 2-Example of Parallel circuit:

a- Find the total Impedance

b- Draw Impedance Triangle (Phasor Diagram)

c- Find  $i_s$ ,  $v_R$ ,  $v_C$ ,  $v_L$

d- Find  $v_R$ ,  $v_C$ ,  $v_L$  using Voltage Divider



✓ Solution ➤ a- The total Impedance

➤ The circuit given is already in frequency domain:

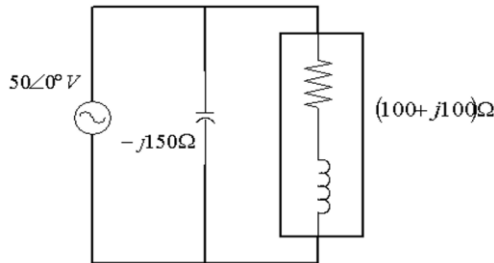
$$Z_R = 100\Omega \angle 0^\circ = 100 \Omega$$

$$Z_C = 150\Omega \angle -90^\circ = -j150 \Omega$$

$$Z_L = 100\Omega \angle 90^\circ = j100 \Omega$$



➤ **Circuit simplification**





# C-TOTAL IMPEDANCE FOR AC CIRCUITS

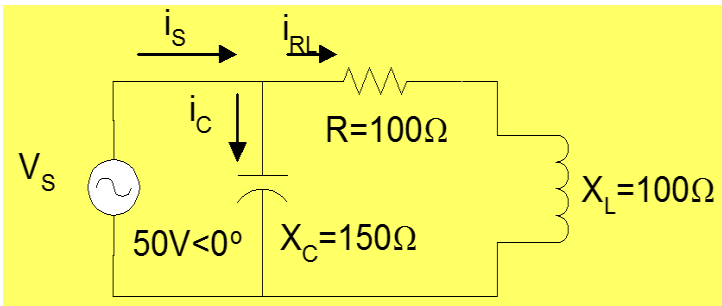
## 2-Example of Parallel circuit:

a- Find the total Impedance

b- Draw Impedance Triangle (Phasor Diagram)

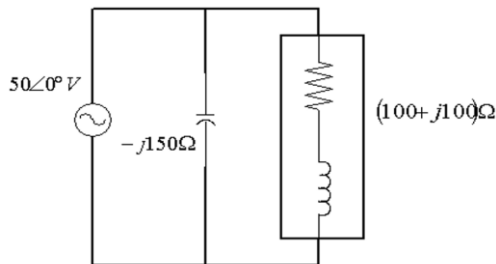
c- Find  $i_s$ ,  $v_R$ ,  $v_C$ ,  $v_L$

d- Find  $v_R$ ,  $v_C$ ,  $v_L$  using Current Divider



✓ Solution ➤ a- The total Impedance

➤ The circuit given is already in frequency domain:



$$\begin{aligned} Z_{total} &= (Z_C) \parallel (Z_R + Z_L) \\ &= (150 \angle -90^\circ) \parallel [(100) + (100 \angle 90^\circ)] \\ &= (150 \angle -90^\circ) \parallel (100 + j100) \\ &= (150 \angle -90^\circ) \parallel (141.42 \angle 45^\circ) \end{aligned}$$

$$\begin{aligned} \therefore Z_{total} &= [Y_{total}]^{-1} \\ &= \left[ \frac{1}{150 \angle -90^\circ} + \frac{1}{141.42 \angle 45^\circ} \right]^{-1} \end{aligned}$$

$$\therefore Z_{total} = \left( \frac{1}{150} (\cos(90^\circ) + j \sin(90^\circ)) + \frac{1}{141.42} (\cos(-45^\circ) + j \sin(-45^\circ)) \right)^{-1}$$

$$= (0.005 + j0.0016)^{-1}$$

$$= \left( \sqrt{0.005^2 + 0.0016^2} \angle \tan^{-1}\left(\frac{0.0016}{0.005}\right) \right)^{-1}$$

$$= (0.00524 \angle 17.744^\circ)^{-1} \approx 190 \angle -18^\circ$$

$$\therefore Z_{total} \approx 180 - j60 \Omega$$



# C-TOTAL IMPEDANCE FOR AC CIRCUITS

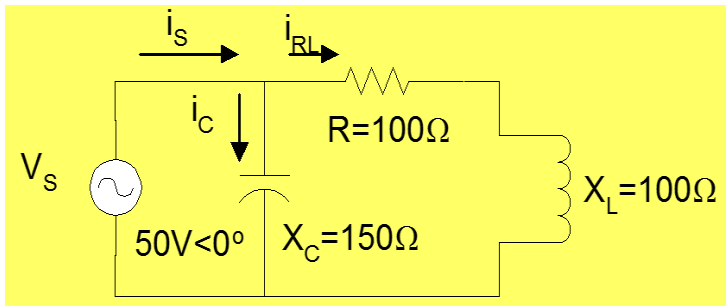
## 2-Example of Parallel circuit:

a- Find the total Impedance

b- Draw Impedance Triangle (Phasor Diagram)

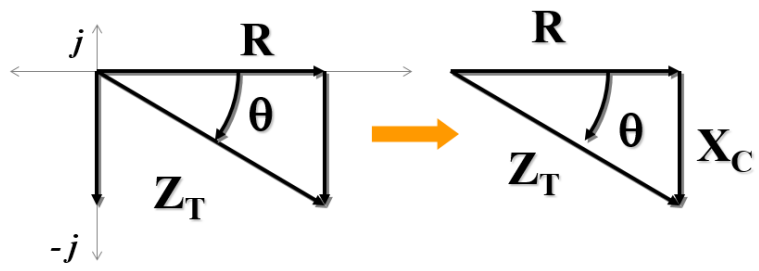
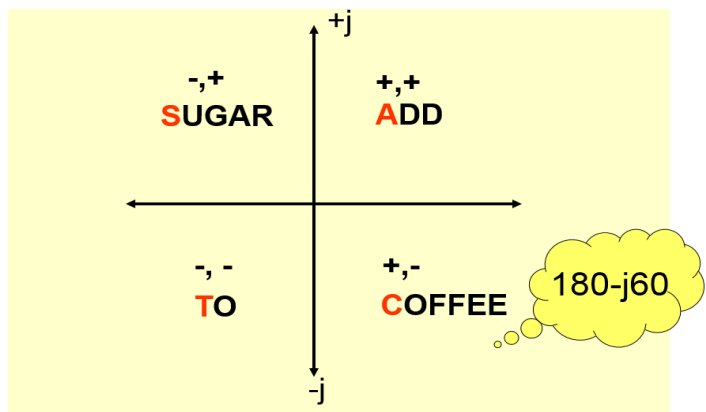
c- Find  $i_s$ ,  $v_R$ ,  $v_C$ ,  $v_L$

d- Find  $v_R$ ,  $v_C$ ,  $v_L$  using Current Divider



✓ Solution ➤ b- The Impedance Triangle (Phasor Diagram)

$$\therefore Z_{total} \simeq 180 - j60 \Omega$$





# C-TOTAL IMPEDANCE FOR AC CIRCUITS

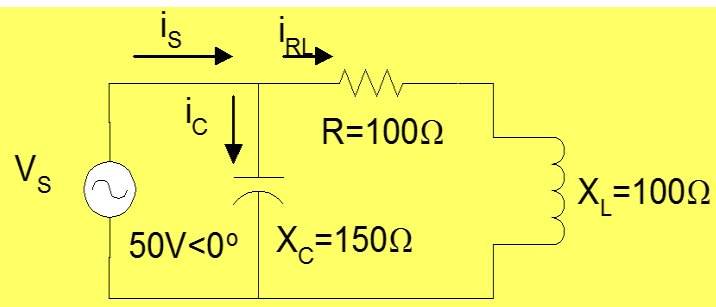
## 2-Example of Parallel circuit:

a- Find the total Impedance

b- Draw Impedance Triangle (Phasor Diagram)

c- Find  $i_s$ ,  $v_R$ ,  $v_C$ ,  $v_L$

d- Find  $v_R$ ,  $v_C$ ,  $v_L$  using Current Divider



✓ Solution      ➤ c-  $i_s$ ,  $v_R$ ,  $v_C$ ,  $v_L$ :

$$\therefore Z_{total} \simeq 180 - j60 \Omega$$

$$i_s = \frac{v_s}{Z_T} = \frac{50 \angle 0^\circ}{190 \angle -18^\circ} = 263 \angle 18^\circ \text{ mA}$$

$$v_S = v_C = (v_R + v_L) = 50 \angle 0^\circ \text{ V}$$

$$\Rightarrow i_C = \frac{v_S}{Z_C} = \frac{50 \angle 0^\circ}{150 \angle -90^\circ} = 333 \angle 90^\circ \text{ mA}$$

$$\Rightarrow i_{RL} = \frac{v_S}{Z_R + Z_L} = \frac{50 \angle 0^\circ}{100 + (100 \angle -90^\circ)} = 353 \angle -45^\circ \text{ mA}$$



# C-TOTAL IMPEDANCE FOR AC CIRCUITS

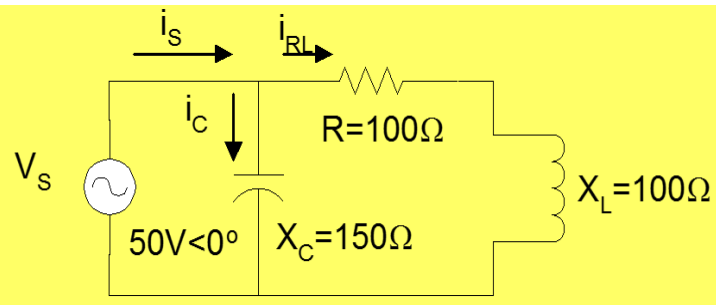
## 2-Example of Parallel circuit:

a- Find the total Impedance

b- Draw Impedance Triangle (Phasor Diagram)

c- Find  $i_s$ ,  $v_R$ ,  $v_C$ ,  $v_L$

d- Find  $v_R$ ,  $v_C$ ,  $v_L$  using Current Divider



✓ Solution ➤ d- Find  $v_R$ ,  $v_C$ ,  $v_L$  using Current Divider

$$i_c = \frac{Z_T}{Z_C} i_S = \frac{(190 \angle -18^\circ)}{(150 \angle -90^\circ)} \cdot (263 \angle 18^\circ \text{ mA})$$
$$= 333 \angle 90^\circ \text{ mA}$$

$$i_{RL} = \frac{Z_T}{Z_R + Z_L} i_S = \frac{(190 \angle -18^\circ)}{(100)(100 \angle 90^\circ)} \cdot (263 \angle 18^\circ \text{ mA})$$
$$= 353 \angle -45^\circ \text{ mA}$$



# D-Impedance as a Function of Frequency

- The Impedance  $Z$  of a circuit is a function of the frequency.

Element	Impedance
$L$	$Z = j\omega L$
$C$	$Z = \frac{1}{j\omega C}$

- Inductor is **SHORT CIRCUIT** at DC and **OPEN CIRCUIT** at high frequencies.  
Capacitor is **OPEN CIRCUIT** at DC and **SHORT CIRCUIT** at high frequencies.

$$Z_L = j\omega L$$

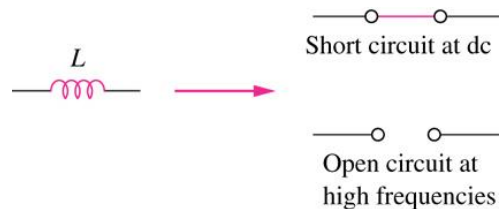
$$Z_L \rightarrow 0 \quad \omega \rightarrow 0 \quad (\text{Short at DC})$$

$$Z_L \rightarrow \infty \quad \omega \rightarrow \infty \quad (\text{Open as } \omega \rightarrow \infty)$$

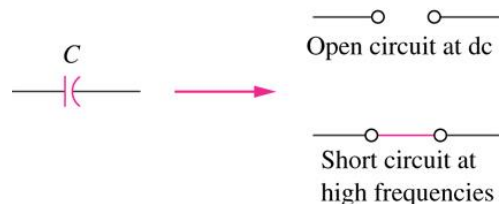
$$Z_C = \frac{1}{j\omega C}$$

$$Z_C \rightarrow \infty \quad \omega \rightarrow 0 \quad (\text{Open at DC})$$

$$Z_C \rightarrow 0 \quad \omega \rightarrow \infty \quad (\text{Open as } \omega \rightarrow \infty)$$



(a)



(b)



---

# AC Analysis Techniques

# AC Analysis Techniques



- Both **KVL** and **KCL** are hold in Phasor domain or more commonly called frequency domain.
- Moreover, the variables to be handled are phasors, which are complex numbers.
- All the mathematical operations involved are now in complex domain.
- **All DC circuit analysis principles apply to AC circuits.**
  - Voltage Division
  - Current Division
  - Circuit Reduction
  - Impedance equivalence
  - Y-Delta Transformation

# Example 22: Voltage Divider Rule

➤ Calculate the  $v_0$  in the given circuit

➤ Solution:

In the frequency domain,

the voltage source is  $V_s = 10\angle 75^\circ$

the 0.5-H inductor is  $j\omega L = j(10)(0.5) = j5$

the  $\frac{1}{20}$ -F capacitor is  $\frac{1}{j\omega C} = \frac{1}{j(10)(1/20)} = -j2$

Let  $Z_1 =$  impedance of the 0.5-H inductor in parallel with the 10- $\Omega$  resistor

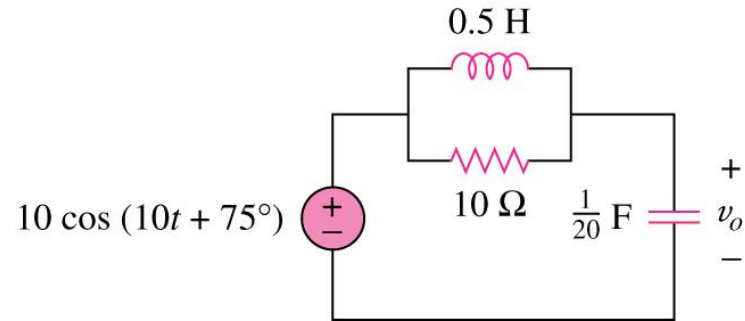
and  $Z_2 =$  impedance of the (1/20)-F capacitor

$$Z_1 = 10 \parallel j5 = \frac{(10)(j5)}{10 + j5} = 2 + j4 \quad \text{and} \quad Z_2 = -j2$$

$$V_o = Z_2 / (Z_1 + Z_2) V_s$$

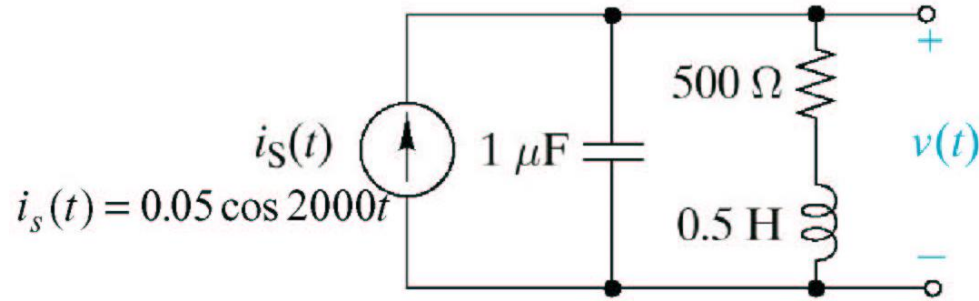
$$V_o = \frac{-j2}{2 + j4 - j2} (10\angle 75^\circ) = \frac{-j(10\angle 75^\circ)}{1 + j} = \frac{10\angle(75^\circ - 90^\circ)}{\sqrt{2}\angle 45^\circ} = 7.071\angle -60^\circ$$

$$v_o(t) = \underline{7.071 \cos(10t - 60^\circ) \text{ V}}$$

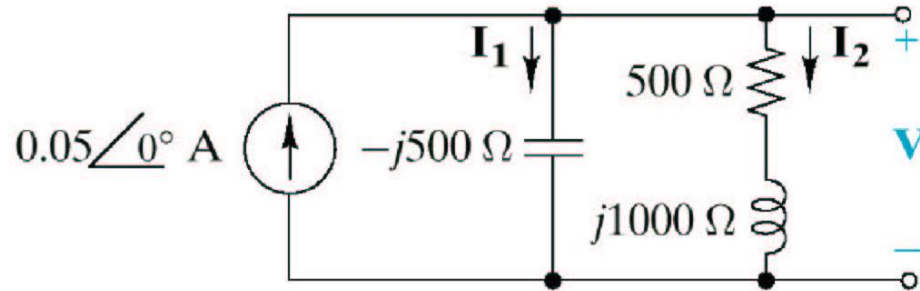


# Example 23: Current Divider Rule

Find  $I_1$  and  $I_2$  in phasor domain, then convert them into time domain

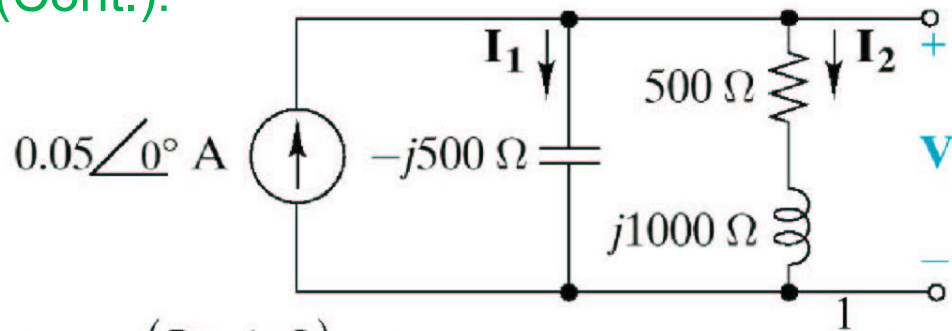


Solution:



# Example 23: Current Divider Rule

Solution (Cont.):



$$\hat{I}_1 = \frac{(R + j\omega L)}{R + j\omega L + \frac{1}{j\omega C}} \hat{I}$$

$$\hat{I}_1 = \frac{(500 + j1000)}{500 + j1000 - j500} 0.05 \angle 0^\circ$$

$$I_1 = 0.079 \angle 18.4^\circ \text{ A}$$

$$i_1(t) = 79 \cos(2000t + 18.4^\circ) \text{ mA}$$

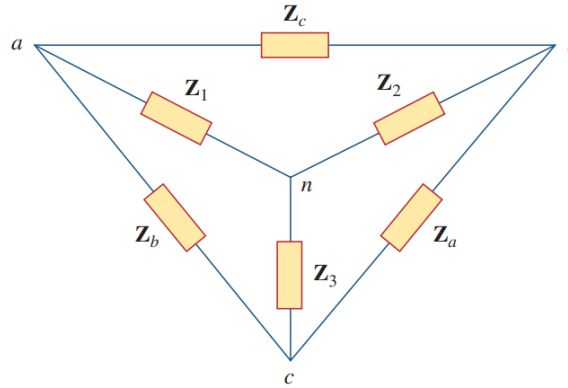
$$\hat{I}_2 = \frac{\frac{1}{j\omega C}}{R + j\omega L + \frac{1}{j\omega C}} \hat{I}$$

$$\hat{I}_2 = \frac{-j500}{500 + j1000 - j500} 0.05 \angle 0^\circ$$

$$I_2 = 0.03535 \angle -135^\circ \text{ A}$$

$$i_2(t) = 35.35 \cos(2000t - 135^\circ) \text{ mA}$$

# Delta-Wye ( $\Delta - Y$ ) Transformation



*Y- $\Delta$  Conversion:*

$$\mathbf{Z}_a = \frac{\mathbf{Z}_1\mathbf{Z}_2 + \mathbf{Z}_2\mathbf{Z}_3 + \mathbf{Z}_3\mathbf{Z}_1}{\mathbf{Z}_1}$$

$$\mathbf{Z}_b = \frac{\mathbf{Z}_1\mathbf{Z}_2 + \mathbf{Z}_2\mathbf{Z}_3 + \mathbf{Z}_3\mathbf{Z}_1}{\mathbf{Z}_2}$$

$$\mathbf{Z}_c = \frac{\mathbf{Z}_1\mathbf{Z}_2 + \mathbf{Z}_2\mathbf{Z}_3 + \mathbf{Z}_3\mathbf{Z}_1}{\mathbf{Z}_3}$$

*$\Delta$ -Y Conversion:*

$$\mathbf{Z}_1 = \frac{\mathbf{Z}_b\mathbf{Z}_c}{\mathbf{Z}_a + \mathbf{Z}_b + \mathbf{Z}_c}$$

$$\mathbf{Z}_2 = \frac{\mathbf{Z}_c\mathbf{Z}_a}{\mathbf{Z}_a + \mathbf{Z}_b + \mathbf{Z}_c}$$

$$\mathbf{Z}_3 = \frac{\mathbf{Z}_a\mathbf{Z}_b}{\mathbf{Z}_a + \mathbf{Z}_b + \mathbf{Z}_c}$$

# Example 24- ( $\Delta - Y$ ) Transformation

Find current  $\mathbf{I}$  in the circuit

**Solution:**

$$\mathbf{Z}_{an} = \frac{j4(2 - j4)}{j4 + 2 - j4 + 8} = \frac{4(4 + j2)}{10} = (1.6 + j0.8) \Omega$$

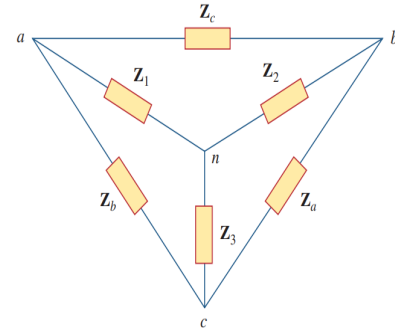
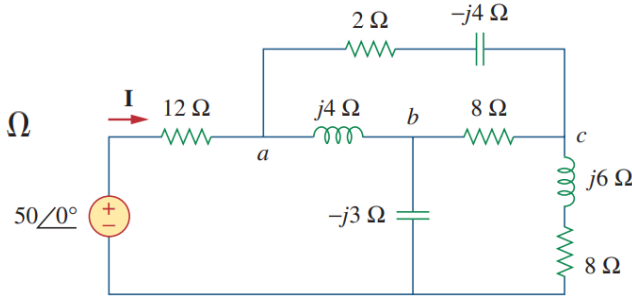
$$\mathbf{Z}_{bn} = \frac{j4(8)}{10} = j3.2 \Omega, \quad \mathbf{Z}_{cn} = \frac{8(2 - j4)}{10} = (1.6 - j3.2) \Omega$$

The total impedance at the source terminals is

$$\begin{aligned} \mathbf{Z} &= 12 + \mathbf{Z}_{an} + (\mathbf{Z}_{bn} - j3) \parallel (\mathbf{Z}_{cn} + j6 + 8) \\ &= 12 + 1.6 + j0.8 + (j0.2) \parallel (9.6 + j2.8) \\ &= 13.6 + j0.8 + \frac{j0.2(9.6 + j2.8)}{9.6 + j3} \\ &= 13.6 + j1 = 13.64 \angle 4.204^\circ \Omega \end{aligned}$$

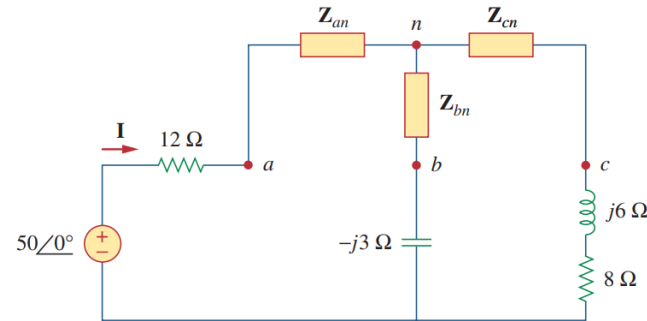
The desired current is

$$\mathbf{I} = \frac{\mathbf{V}}{\mathbf{Z}} = \frac{50 \angle 0^\circ}{13.64 \angle 4.204^\circ} = 3.666 \angle -4.204^\circ \text{ A}$$




$\Delta$ -Y Conversion:

$$\begin{aligned} \mathbf{Z}_1 &= \frac{\mathbf{Z}_b \mathbf{Z}_c}{\mathbf{Z}_a + \mathbf{Z}_b + \mathbf{Z}_c} \\ \mathbf{Z}_2 &= \frac{\mathbf{Z}_c \mathbf{Z}_a}{\mathbf{Z}_a + \mathbf{Z}_b + \mathbf{Z}_c} \\ \mathbf{Z}_3 &= \frac{\mathbf{Z}_a \mathbf{Z}_b}{\mathbf{Z}_a + \mathbf{Z}_b + \mathbf{Z}_c} \end{aligned}$$





# Frequency Domain Analysis (Using Phasor)



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Nodal Analysis  
Mesh Analysis  
Superposition,  
Source transformation  
Thevenin theorem, and  
Norton theorem

# Example 25- Nodal Analysis

Find  $i_x$  in the following circuit using nodal analysis

## Solution

We first convert the circuit to the frequency domain:

$$20 \cos 4t \Rightarrow 20 \angle 0^\circ, \quad \omega = 4 \text{ rad/s}$$

$$1 \text{ H} \Rightarrow j\omega L = j4$$

$$0.5 \text{ H} \Rightarrow j\omega L = j2$$

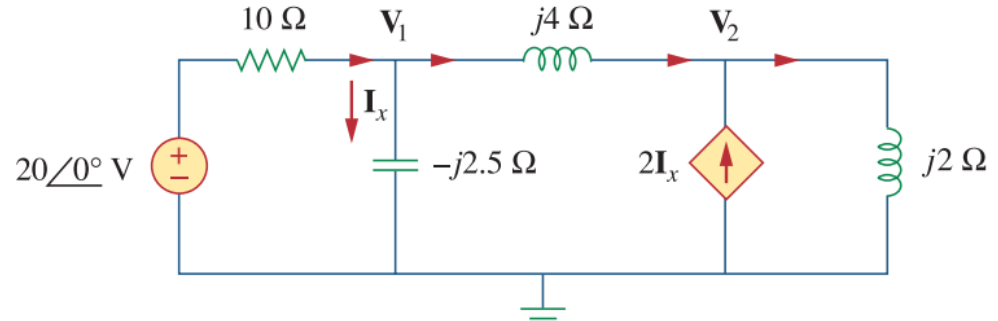
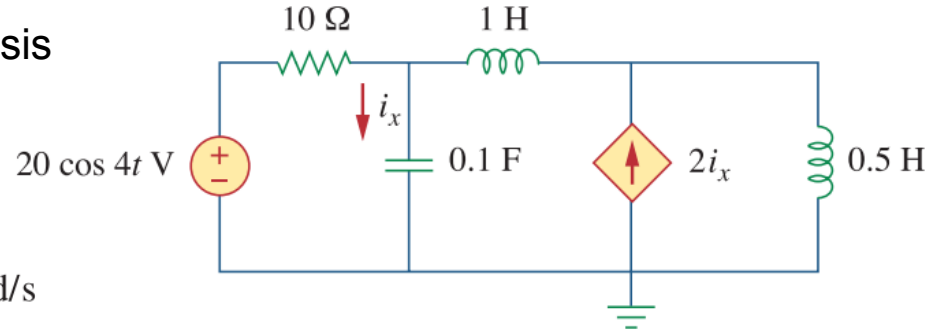
$$0.1 \text{ F} \Rightarrow \frac{1}{j\omega C} = -j2.5$$

Applying KCL at node 1,

$$\frac{20 - \mathbf{V}_1}{10} = \frac{\mathbf{V}_1}{-j2.5} + \frac{\mathbf{V}_1 - \mathbf{V}_2}{j4}$$

or

$$(1 + j1.5)\mathbf{V}_1 + j2.5\mathbf{V}_2 = 20$$



# Example 25- Nodal Analysis

Find  $i_x$  in the following circuit using nodal analysis

Solution (continue)

At node 2,

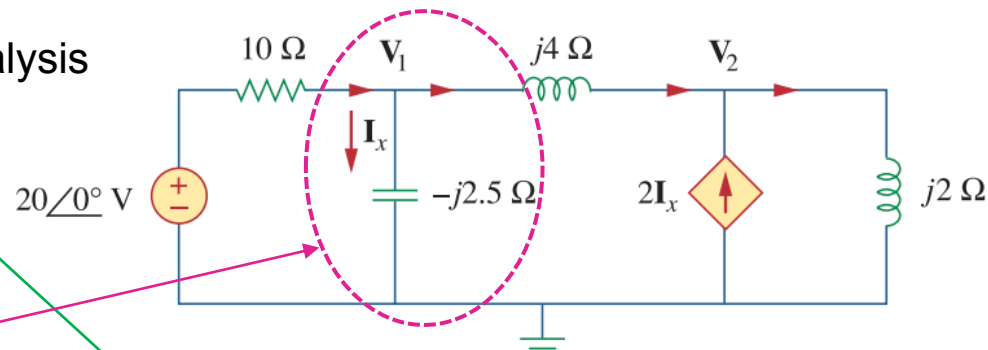
$$(1 + j1.5)V_1 + j2.5V_2 = 20$$

$$2\mathbf{I}_x + \frac{V_1 - V_2}{j4} = \frac{V_2}{j2}$$

But  $\mathbf{I}_x = V_1 / -j2.5$ . Substituting this gives

$$\frac{2V_1}{-j2.5} + \frac{V_1 - V_2}{j4} = \frac{V_2}{j2}$$

$$11V_1 + 15V_2 = 0$$



$$\begin{bmatrix} 1 + j1.5 & j2.5 \\ 11 & 15 \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} 20 \\ 0 \end{bmatrix}$$

$$V_1 = 18.97 / \underline{18.43^\circ} \text{ V}$$

$$V_2 = 13.91 / \underline{198.3^\circ} \text{ V}$$

The current  $\mathbf{I}_x$  is given by

$$\mathbf{I}_x = \frac{V_1}{-j2.5} = \frac{18.97 / \underline{18.43^\circ}}{2.5 / \underline{-90^\circ}} = 7.59 / \underline{108.4^\circ} \text{ A}$$

$$\longrightarrow i_x = 7.59 \cos(4t + 108.4^\circ) \text{ A}$$

# Example 26- Mesh Analysis

Find  $I_o$  in the following circuit using mesh analysis

## Solution

Applying KVL to mesh 1, we obtain

$$\begin{aligned} &\text{➤ } 8I_1 + j10(I_1 - I_3) - 2j(I_1 - I_2) = 0 \\ (8 + j10 - j2)I_1 - (-j2)I_2 - j10I_3 &= 0 \end{aligned}$$

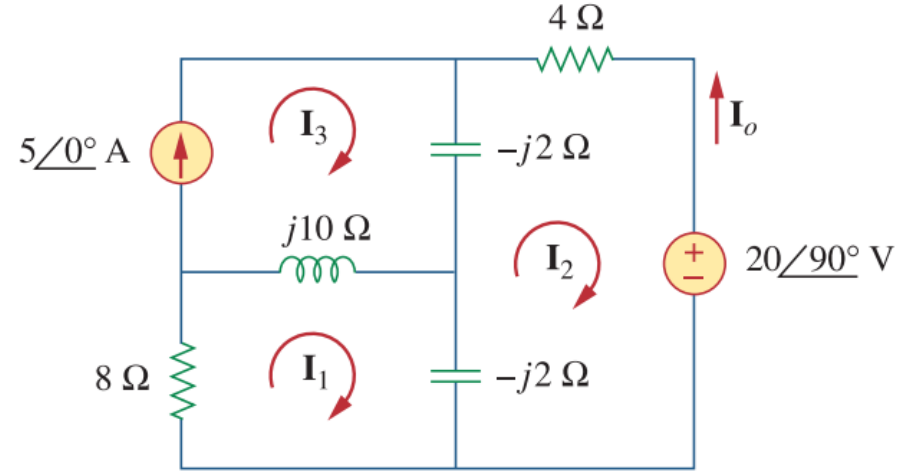
$$\text{For mesh 2, } \text{➤ } 20\angle 90^\circ + 4I_2 - j2(I_2 - I_3) - j2(I_2 - I_1) = 0$$

$$(4 - j2 - j2)I_2 - (-j2)I_1 - (-j2)I_3 + 20\angle 90^\circ = 0$$

For mesh 3,  $I_3 = 5$

$$\begin{bmatrix} 8 + j8 & j2 \\ j2 & 4 - j4 \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} j50 \\ -j30 \end{bmatrix}$$

$$I_2 = \frac{\Delta_2}{\Delta} = \frac{416.17\angle -35.22^\circ}{68} = 6.12\angle -35.22^\circ \text{ A} \longrightarrow I_o = -I_2 = 6.12\angle 144.78^\circ \text{ A}$$

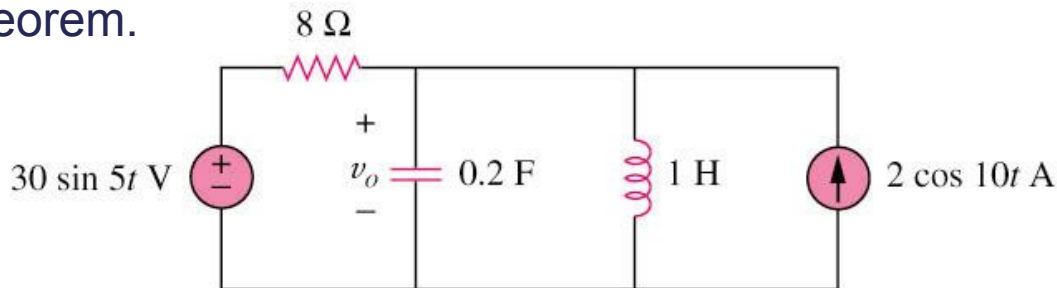


# Superposition Theorem

When a circuit has sources operating at different frequencies,

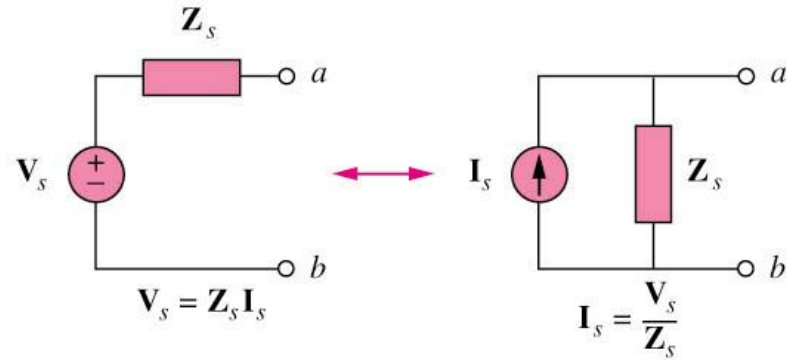
- The separate phasor circuit for each frequency must be solved independently, and
- The total response is the sum of time-domain responses of all the individual phasor circuits.

**Example** Calculate  $v_o$  in the circuit of figure shown below using the superposition theorem.

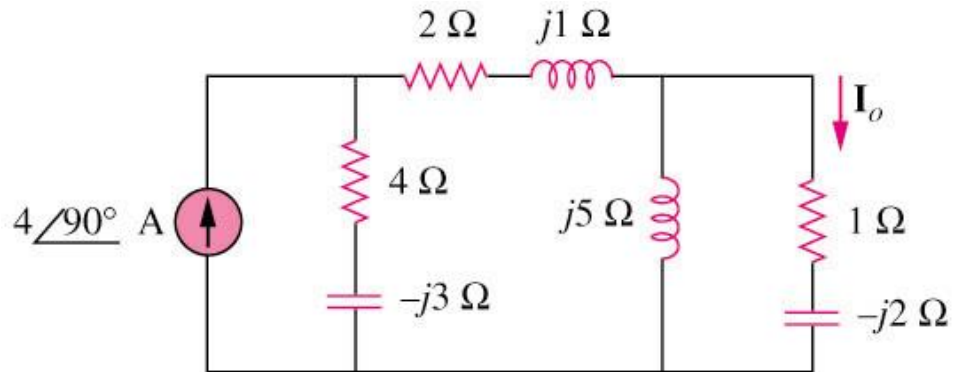


**Answer:**  $V_o = 4.631 \sin(5t - 81.12) + 1.051 \cos(10t - 86.24) \text{ V}$

# Source Transformation



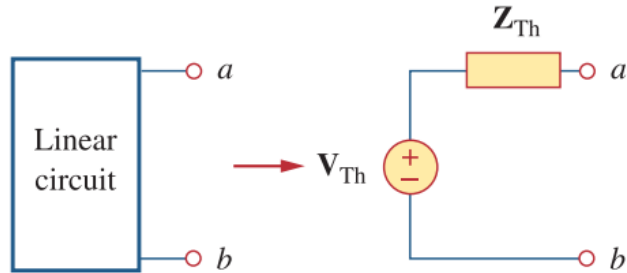
**Example** Find  $I_o$  in the circuit of figure below using the concept of source transformation.



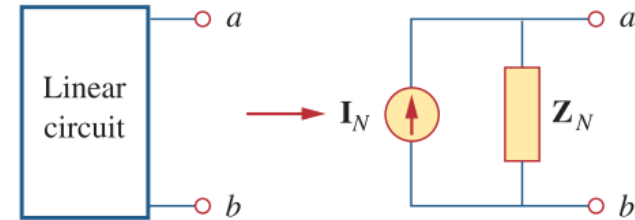
**Answer:**  $I_o = \underline{3.288 + j99.46 \text{ A}}$

# Thevenin and Norton Theorems in AC circuits

- Thevenin's and Norton theorems are applied to ac circuits in the same way as they are to DC circuits
- The **ONLY additional effort** is the need to manipulate **complex numbers**.



Thevenin equivalent.

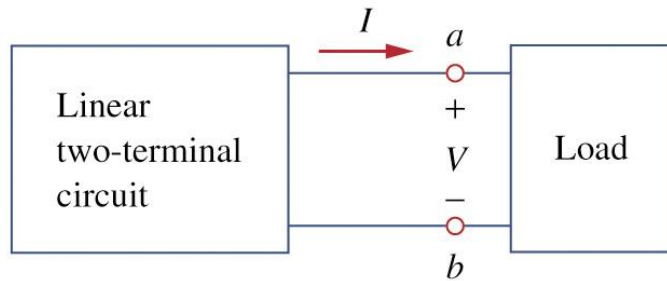


Norton equivalent.

Where;  $V_{Th} = V_{ab-OC}$  is the **open circuit voltage (PHASOR)** between terminals a-b,  $I_N = I_{ab-SC}$  is the **short circuit current (PHASOR)** through the terminals a-b, and  $Z_{Th}$  is the **input or equivalent IMPEDANCE** at the terminals **when the independent source are turn off**.

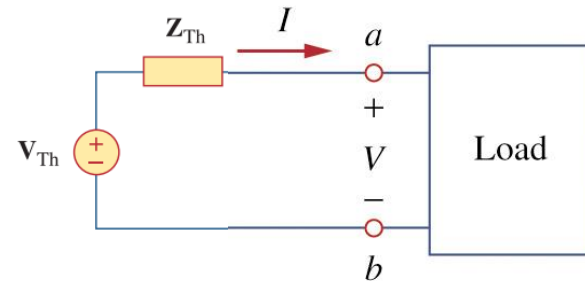
# How to Find Thevenin Equivalent Circuit in AC circuits

- ❖ First, **Open the circuit** (remove the load) at the **points** of interest **a-b**
  - 1-  $V_{th}$  = Open circuit voltage (keep all sources intact). Note:  $V_{th}$  is Phasor
  - 2-  $Z_{th}$  = Open circuit **equivalent Impedance** appears at terminals **a-b** while all **independent sources=0** (voltage source=SC , current source=OC).



Original Circuit

≡



Thevenin equivalent circuit

# Example 10.8- Thevenin Equivalent Circuit

Obtain the Thevenin equivalent at terminals a-b of the following circuit.

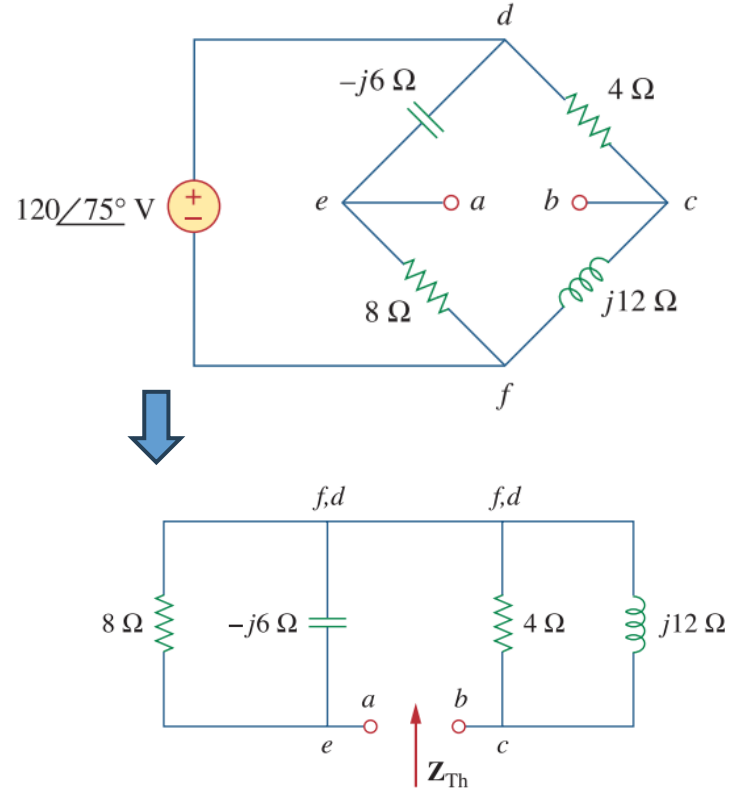
Solution

1- For  $Z_{th}$

$$\mathbf{Z}_1 = -j6 \parallel 8 = \frac{-j6 \times 8}{8 - j6} = 2.88 - j3.84 \Omega$$

$$\mathbf{Z}_2 = 4 \parallel j12 = \frac{j12 \times 4}{4 + j12} = 3.6 + j1.2 \Omega$$

$$\mathbf{Z}_{Th} = \mathbf{Z}_1 + \mathbf{Z}_2 = 6.48 - j2.64 \Omega$$



# Example 10.8- Thevenin Equivalent Circuit

Obtain the Thevenin equivalent at terminals a-b of the following circuit.

Solution (continue)

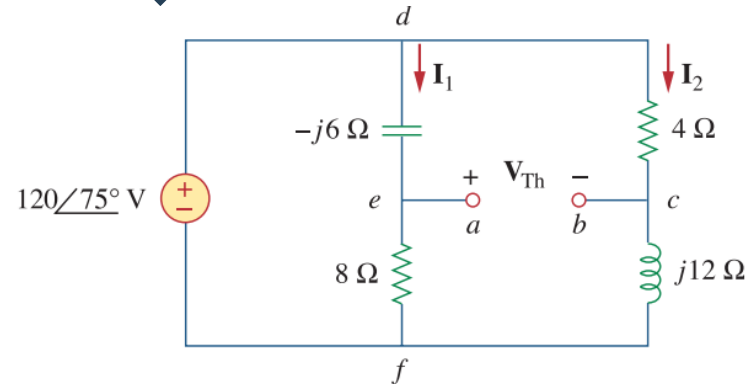
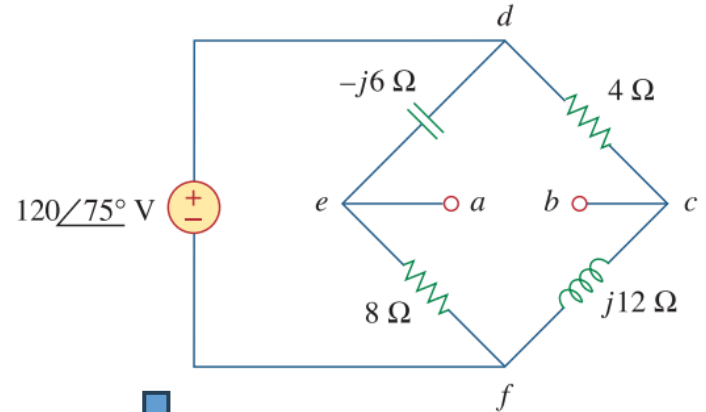
2- For  $V_{th}$

$$\mathbf{I}_1 = \frac{120 \angle 75^\circ}{8 - j6} \text{ A}, \quad \mathbf{I}_2 = \frac{120 \angle 75^\circ}{4 + j12} \text{ A}$$

Applying KVL around loop  $bcdeab$

$$\mathbf{V}_{Th} - 4\mathbf{I}_2 + (-j6)\mathbf{I}_1 = 0$$

$$\begin{aligned} \mathbf{V}_{Th} = 4\mathbf{I}_2 + j6\mathbf{I}_1 &= \frac{480 \angle 75^\circ}{4 + j12} + \frac{720 \angle 75^\circ + 90^\circ}{8 - j6} \\ &= 37.95 \angle 3.43^\circ + 72 \angle 201.87^\circ \\ &= -28.936 - j24.55 = 37.95 \angle 220.31^\circ \text{ V} \end{aligned}$$



# Example 10.9- Thevenin Equivalent Circuit

Obtain the Thevenin equivalent at terminals a-b of the following circuit.

## Solution

### 1- For $V_{th}$

To find  $V_{Th}$ , we apply KCL at node 1

$$15 = I_o + 0.5I_o \quad \Rightarrow \quad I_o = 10 \text{ A}$$

Applying KVL to the loop on the right-hand side

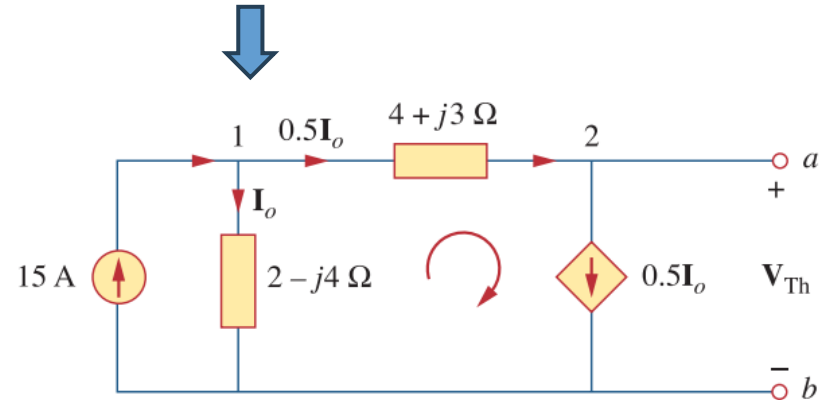
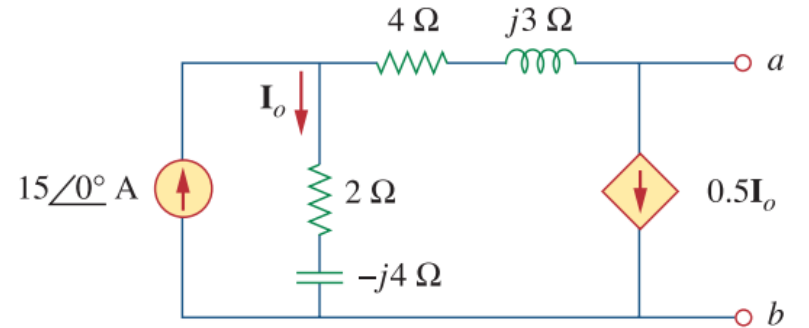
$$-I_o(2 - j4) + 0.5I_o(4 + j3) + V_{Th} = 0$$

or

$$V_{Th} = 10(2 - j4) - 5(4 + j3) = -j55$$

Thus, the Thevenin voltage is

$$V_{Th} = 55 \angle -90^\circ \text{ V}$$



# Example 10.9- Thevenin Equivalent Circuit

Obtain the Thevenin equivalent at terminals a-b of the following circuit.

Solution (continue)

2- For  $Z_{th}$

To obtain  $Z_{Th}$ , we remove the independent source. Due to the presence of the dependent current source, we connect a 3-A current source (3 is an arbitrary value chosen for convenience here, a number divisible by the sum of currents leaving the node) to terminals  $a-b$

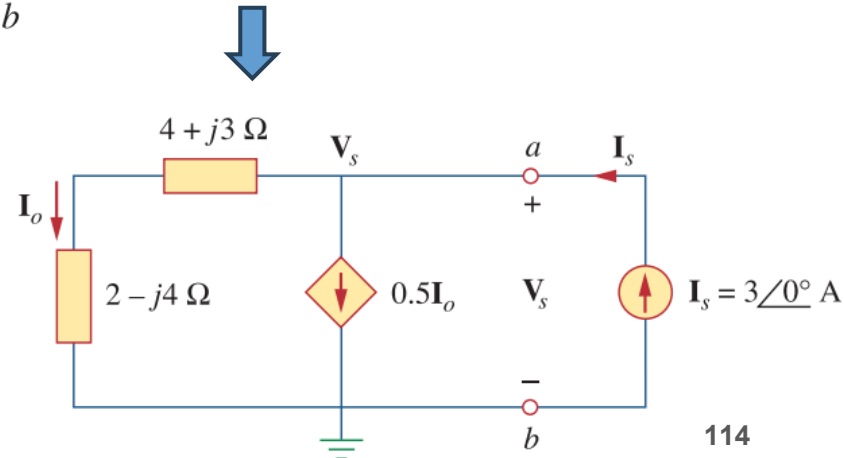
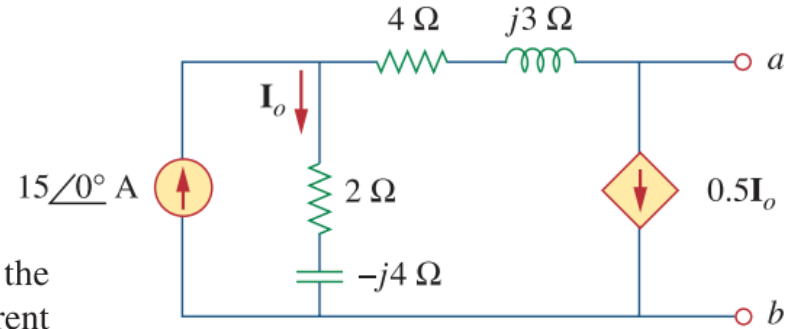
$$3 = \mathbf{I}_o + 0.5\mathbf{I}_o \quad \Rightarrow \quad \mathbf{I}_o = 2 \text{ A}$$

Applying KVL to the outer loop in Fig. 10.26(b) gives

$$\mathbf{V}_s = \mathbf{I}_o(4 + j3 + 2 - j4) = 2(6 - j)$$

The Thevenin impedance is

$$\mathbf{Z}_{Th} = \frac{\mathbf{V}_s}{\mathbf{I}_s} = \frac{2(6 - j)}{3} = 4 - j0.6667 \Omega$$



# Trigonometric Identities



- Sine and cosine form conversions.

$$\sin(A \pm B) = \sin A \cos B \pm \cos A \sin B$$

$$\cos(A \pm B) = \cos A \cos B \mp \sin A \sin B$$

$$\sin(\omega t \pm 180^\circ) = -\sin \omega t$$

$$\cos(\omega t \pm 180^\circ) = -\cos \omega t$$

$$\sin(\omega t \pm 90^\circ) = \pm \cos \omega t$$

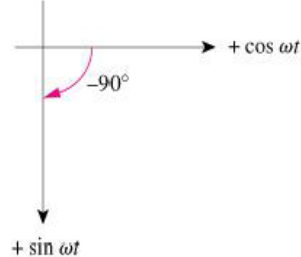
$$\cos(\omega t \pm 90^\circ) = \mp \sin \omega t$$

$$A \cos \omega t + B \sin \omega t = C \cos(\omega t - \theta)$$

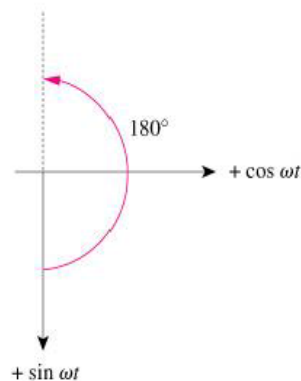
Where

$$C = \sqrt{A^2 + B^2} \quad \text{and} \quad \theta = \tan^{-1} \frac{B}{A}$$

Graphically relating sine and cosine functions.



$$\cos(\omega t - 90^\circ) = \sin \omega t$$



$$\sin(\omega t + 180^\circ) = -\sin \omega t$$



End of Lecture



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Questions?